INTERNATIONAL ORGANISATION FOR LEGAL METROLOGY

INTERNATIONAL RECOMMENDATION

R 21- Taximeters

Supprimé : systems

Metrological and Technical Requirements, Test Procedures and Test Report Format

Fourth Committee Draft

(TC7/SC4)

February 2006

EXPLANATORY NOTE

This fourth committee draft revision Recommendation has been prepared by the TC7 / SC4 Secretariat and reflects consideration of the comments received on the third committee draft consultation exercise in August 2005.

OIML TC7/SC4 “Measuring instruments for road traffic”

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FOREWORD

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TERMINOLOGY

The terminology used in this Recommendation conforms to the *International Vocabulary of Basic and General Terms in Metrology* [1], the International *Vocabulary of Legal Metrology* [2], to the *OIML Certificate System for Measuring* Instruments [3], and to the *OIML International Document for General requirements for Electronic Measuring Instruments* [4]. In addition, for the purposes of this Recommendation, the following definitions apply.

T.1 GENERAL

T.1.1 Taximeter

An instrument intended to measure duration and to measure distance on the basis of a signal delivered by a distance measurement transducer and to calculate and indicate the fare to be paid on the basis of the measured distance and/or measured duration.

T.1.2 Taxi

A vehicle controlled by a driver that takes passengers on a journey in exchange for a fare.

Supprimé : Taximeter system An electronic taximeter complete withall modules necessary for full installation and operation in a

T.1.3 Vehicle unit

A taximeter complete with a vehicle installed distance measurement transducer (Annex B), and all the appropriate connectors and peripheral devices (e.g. interfaces, printer, display, facilities for data entry) for normal operation in a vehicle.

T.1.4 Metrological authority

An authorized representative of the national service of legal metrology (i.e. the approving, testing and/or issuing authority) with responsibility for ascertaining and confirming that the instrument satisfies all or some of the requirements of this Recommendation.

T.1.5 Metrologically relevant

Any device, instrument, function or software of a taximeter that influences the measurement result or any other primary indication is considered as metrologically relevant.

T.2 CONSTRUCTION

T.2.1 Device

A "device" is the integral part of the taximeter providing the means by which a specific function is performed, irrespective of the physical realization, e.g. by a mechanism or a key initiating an operation; the device may be a small part or a major part of taximeter (e.g. calculator, totalizer, real time clock)..

Supprimé : ..Identifiable part of a taximeter system that performs a specific function or functions, and that can be separately evaluated according to specific metrological and technical performance requirements in the relevant Recommendation. The modules of a taximeter system are subject to specified partial error limits.

T.2.2 Peripheral device

A peripheral device is an additional device which repeats or further processes the measurement result and other primary indications (e.g. printer)

T.2.3 Calculator

A calculator incorporated into the taximeter that receives the output signals from the distance measurement transducer, the real-time clock, and possibly from associated measuring instruments, and converts them into the appropriate parameters (time, duration, distance, fare), and if appropriate totalizes and/or stores the results in memory until they are used. In addition, the calculator may be capable of communicating both ways with these devices.

Supprimé : transforms

Supprimé : A that allocates measurement results into different registers depending upon tariff or other criteria, each register having the possibility to be indicated individually. The may, for example, consists of specific keys and switches or software programs for specific functions

T.2.4 Real-time clock

A clock incorporated into the taximeter that tracks time and also functions in the event the voltage supply to the taximeter is interrupted.

T.2.5 Event-counter

A non-resettable counter that increments once each time a protected operational and measurement mode of the taximeter is entered and one or more changes are made to device-specific parameters (T.2.10.3). The reference number of the counter at the time of initial or in-service verification is fixed and secured by appropriate hardware or software means of the modified instrument.

Supprimé : the metrological parameters and modules

Note: The term "non-resettable" implies that if the counter has reached its maximum number it will not continue with zero without the intervention of an authorized person.

T.2.6 Distance measurement transducer

An instrument (Annex B) installed in a vehicle that converts the distance to be measured into pulses which are passed to the calculator in the taximeter.

Note: The distance measurement transducer does not provide information about the duration.

T.2.7 Communication interface

An electronic, optical, radio or other hardware and software interface that enables information to be automatically passed between taximeter devices.

T.2.8 User interface

An interface that enables information to be passed between a human user and the measuring instrument or its hardware or software components, as, e.g. switch, keyboard, mouse, display, monitor, printer, touchscreen.

T.2.9 Protective interface

Interface which allows the introduction of only such data into the data processing device of taximeter, which cannot

- display data, that are not clearly defined and could be taken for a measurement result,
- falsify displayed, processed or stored measurement results or primary indications,
- adjust the instrument or change any adjustment factor

T.2.10 Intelligent dedicated equipment

The equipment or device capable of performing secured data processing, transmitting, downloading and storage (e.g. intelligent transducer, calculator, personal computer)

T.2.11 Electronic equipment

T.2.11.1 Electronic instrument

An instrument employing electronic sub-assemblies and performing a specific function. An electronic instrument is usually manufactured as a separate unit and can be independently tested.

Note: As defined above, it may be a main part of the taximeter (e.g. distance measurement transducer) or a peripheral device (e.g. printer)

T.2.11.2 Electronic sub-assembly

A part of an electronic instrument comprised of electronic components and having a recognisable function of its own (e.g. A/D converter, display).

T.2.11.3 Electronic component

The smallest physical entity that uses electron or hole conduction in semiconductors, gases, or in a vacuum.

T.2.12 Software

T.2.12.1 Legally relevant software

Programs, data, type-specific and device-specific parameters that belong to the taximeter, and define or fulfil functions that are subject to metrological control.

T.2.12.2 Type-specific parameter

Legally relevant parameter with a value that depends on the type of taximeter only. They are fixed at type approval of the taximeter.

T.2.12.3 Device-specific parameter

Legally relevant parameter with a value that depends on the individual taximeter. Such parameters comprise calibration and configuration parameters, such as measurement data, i.e. tariff data, fare and totalled fares (including the decimal sign and the monetary unit), time and distance data, and software identification. They are adjustable or selectable only in the in-service mode of the taximeter and may be classified as those that should be secured (unalterable) and those that may be accessed (settable parameters) by an authorised person.

T.2.12.4 Software identification

A sequence of readable characters of software, and that is inextricably linked to the software (e.g. version number, checksum).

T.2.13 Data storage

Memory storage used for keeping measurement data (T.3.1) ready after completion of the measurement. Storage may be integrated with the taximeter (e.g. non-removable data storage that is part of the taximeter, e.g. hard disk, or removable storage, e.g. diskettes, CD-

RW). Storage may also be on a universal computer system (multitasking operating system where storage can be moved within the universal system), or a remote system, e.g. file server located anywhere, e.g. in the same building or even in a different country. Thus the communications link to storage devices may be direct, which permits handshaking, or indirect, whereby there might be an intermediate storage phase not under the control of the user, e.g. dial-up on Internet.

T.2.14 Vehicle identification number

Numbers and/or letters identifying the vehicle or national vehicle registration number.

T.3 METROLOGICAL CHARACTERISTICS

T.3.1 Measurement data

T.3.1.1 Fare

The monetary amount calculated, indicated and displayed as a fare by the taximeter, due for a taxi journey based on a fixed initial fee (excluding any supplementary charges) and/or the length and/or the duration of the journey.

T.3.1.1.1 Supplementary charges

Additional amount for an extra service, entered on manual command, suitably identified, indicated and displayed separately from the fare in 'Hired' (occupied) and in 'Stopped' (to pay) positions, with the possibility to add to the fare and display temporarily the total value of the fare including the supplementary charge at the end of the journey.

Supprimé : enetred

T.3.1.1.2 Initial hire fee

The initial hire fee is a fixed amount, charged to the passenger, regardless of the time or distance of the journey.

T.3.1.1.3 Fare increment step

The smallest amount of money by which the fare may be incremented in equal steps in 'Hired' (occupied) position in accordance with the national regulation.

Supprimé : prscription

T.3.1.2 Cross-over speed

The vehicle speed (km/h) at which the time-counting and distance-counting methods drive the taximeter at the same rate. The speed value is determined by division of the time tariff value by the applicable distance tariff value.

Supprimé : found

The crossover speed is worked out as:

Supprimé : changeover

$$\frac{\text{Time tariff [amount/h]}}{\text{Distance tariff [amount/km]}}$$

For example:

Time tariff: € 20.00/h
Distance tariff: € 50.00/km

Crossover speed [km/h]: $\frac{€\,20.00/h}{€\,50.00/km}$ = 40 km/h.

T.3.1.3 Fare calculation method

T.3.1.3.1 Normal calculation method S (single application of tariff)

Fare calculation based on application of the time tariff below the cross-over speed and application of the distance tariff above the cross-over speed.

T.3.1.3.2 Normal calculation method D (double application of tariff)

Fare calculation based on the combined application of time tariff and distance tariff over the whole journey.

T.3.1.4 Instrument constant k

The constant k of the taximeter is expressed as pulses per kilometre and represents the number of the pulses which the instrument must receive in order to indicate correctly a distance travelled of 1 kilometre.

Supprimé : Example: The tariff rate is applied according to the distance or to the time of the journey, or to a combination of both the distance and time of the journey.

Supprimé : According to the contruction of the instrument, the constant k may be fixed or may be adjustable by fixed amounts.

T.3.1.5 Vehicle constant w

The vehicle constant w is expressed as pulses per kilometre and represents the number of pulses a vehicle produces per kilometre of travel in its current location. The constant w varies in relation to several factors, in particular tyre wear and tyre pressure, the load carried by the vehicle and the conditions in which the journey is made.

T.3.1.6 Initial distance

The distance which can be travelled according to the tariff for the initial hire fare, considering distance-counting only.

Supprimé : initila

T.3.1.7 Initial time

The period during which the vehicle can be used for the initial hire fare, considering time-counting only.

Supprimé : initila

T.3.1.8 Time-counting

Time-counting is the calculation method in which the fare increases in proportion to the duration of the journey.

Supprimé : mode

Supprimé : duaration

Supprimé : hiring

T.3.1.9 Distance-counting

Distance-counting is the calculation method in which the fare increases in proportion to the distance travelled.

Supprimé : mode

T.3.1.10 Time-distance counting

Time-distance counting is the calculation method in which two components of the fare increase concurrently, one in proportion to the duration of the journey and the other in proportion to the distance travelled.

Supprimé : mode
Supprimé : additional
Supprimé : hiring

T.3.1.11 Distance measuring signal

The signal supplied by the distance measurement transducer to the calculator in the taximeter, in proportion to the distance travelled.

Supprimé : taximeter system
Supprimé : calculating module

T.3.1.12 Time measuring signal

The signal supplied by the real-time clock to the calculator in the taximeter, in proportion to the duration of the journey.

Supprimé : taximeter system
Supprimé : hiring

T.3.1.13 Reference number of pulses

The theoretical number of pulses from a distance and/or time measuring signal, which can be calculated using the tariff data and the instrument constant k, which should lead to a certain change in the fare indication.

Supprimé : contant

T.3.1.14 Tariff

A set of tariff values that represents a schedule of charges or rates which will be operative in the taximeter in a specified tariff position.

T.3.1.15 Tariff values

The values from which the taximeter calculates the fare.

T.3.1.16 Distance tariff value

The tariff value expressed as an amount of money for a given distance.

T.3.1.17 Time tariff value

The tariff value expressed as an amount of money for a given period of time.

T.3.1.18 Tariff position

A position to which the taximeter can be adjusted in the 'Hired' (occupied) position.

T.3.2 **Tariff regulation**

Supprimé : regulation

A regulation, establishing which tariffs and supplements are to be applied under specified conditions.

T.3.3 **Operating position**

The different operating positions in which a taximeter fulfils different parts of its functioning.

T.3.3.1 'For hire' (free) position

In 'For hire' (free) position the taximeter is not calculating a fare and no paying customer is making a taxi journey.

T.3.3.2 ‘Hired’ (occupied) position

In ‘Hired’ (occupied) position the taximeter is indicating and calculating a fare which is based on a possible initial hire fee and a tariff for the time of the journey and/or distance travelled.

Supprimé : increases as the journey progresses

T.3.3.3 ‘Stopped’ (to pay) position

In ‘Stopped’ (to pay) position a journey has been completed and the fare indicated has ceased to increase with time while distance-counting is active.

T.3.3.4 ‘Measure’ position

Additional operating position in which the total distance and duration of the journey are measured.

Supprimé : the

T.3.4 Repeatability

Ability of taximeter to provide results that agree one with the other under the same operating conditions of measurement [based on VIM 3.6].

T.3.5 Durability

Ability of a taximeter to maintain its performance characteristics over a period of use.

T.3.6 Checking facility

Facility that is incorporated in the taximeter and which enables significant fault to be detected and acted upon.

Note: The term ‘acted upon’ refers to any adequate response by the taximeter (luminous or acoustic signals, prevention of measurement process, etc).

T.3.7 Automatic checking facility

A checking facility that operates without the intervention of an operator, and performs securing and monitoring activities.

T.3.8 Taximeter operational mode

Taximeter mode in which the vehicle unit is fully operational and implements all functions, including security functions

T.3.9 Taximeter in-service mode

Taximeter mode for updating or confirming vehicle parameters to be held in the memory storage. Vehicle parameters include vehicle identification and vehicle characteristics (w, k, tyre size, current time and current odometer value).

In-service inspection of a vehicle unit is conducted by the appropriate metrological authority (T.1.4)

Supprimé : T.3. Accuracy of a measuring instrument¶
The ability of a measuring instrument to give responses close to a true value [VIM 5.18].¶
Note: Accuracy is a qualitative concept

T.4 INDICATIONS AND ERRORS

T.4.1 Taximeter indicator

A part of the taximeter that displays the measurement results either continuously or on demand.

Note: "Indication", "indicate" or "indicating" includes both displaying and/or printing.

T.4.1.1 Digital indication

An indication in which the output or display of the measurement results is digitized [VIM 4.11].

Note: The term 'digitized' relates to the form of presentation of the output or display, not to the principle of operation of the instrument.

T.4.1.2 Primary indications

Indications, signals and symbols that are subject to requirements of this Recommendation.

T.4.1.3 Totalization indicator

The part of the taximeter indicator that displays the sum of totalized values separately from other values.

T.4.1.4 Operating position indicator

The part of the taximeter indicator that displays the operating position (T.3.3) for the tariff (or other criteria) based measurement results allocated to individual registers.

T.4.2 Errors

T.4.2.1 Error (of indication)

The indicated measurement minus the actual measurement [VIM 5.20].

T.4.2.2 Intrinsic error

The error of an instrument determined under reference conditions [VIM 5.24].

T.4.2.3 Initial intrinsic error

The intrinsic error of an instrument as determined prior to performance tests.

T.4.2.4 Maximum permissible errors (MPE)

Extreme values of an error permitted by specifications, regulations, etc, for a given instrument. [VIM 5.21]

T.4.2.5 Fault

The difference between the error of indication and the intrinsic error of a taximeter.

Note: Principally, a fault is the result of an undesired change of data contained in or flowing through an electronic instrument. In this Recommendation, a "fault" is a numerical value.

Supprimé : T.4.1.2
Additional indicator display for the normal calculation method D (double application of tariff) A normal calculation method D taximeter system equipped with the 'MEASURE' operating mode may have an optional indicator display in which only the total distance and duration of the journey are displayed in real time (see 3.8.3).

T.4.2.6 Significant fault

A fault the magnitude of which is greater than the maximum permissible error of the taximeter.

The following are not considered to be significant faults:

- faults that result from simultaneous and mutually independent causes in the instrument,
- faults that make it impossible to perform any measurement,
- transitory faults that are momentary variations in the indications which cannot be interpreted, memorised or transmitted as a measurement result,
- faults that are so serious that they will inevitably be noticed by those interested in the measurement.

T.5 TEST CONDITIONS

T.5.1 Equipment under test (EUT)

Taximeter or a device subjected to performance tests.

Supprimé : system

T.5.2 Influence quantity

A quantity that is not the measurand but affects the result of the measurement [VIM 2.7].

T.5.3 Influence factor

An influence quantity having a value within the specified rated operating conditions of the EUT.

T.5.4 Disturbance

An influence quantity having a value within the limits specified in this Recommendation, but outside the specified rated operating conditions of the EUT.

T.5.5 Rated operating conditions

Conditions of use (e.g. reference conditions applicable in the IEC Standard) giving the range of values of the influence factors, for which the errors (of indication) of the EUT are required to be within the maximum permissible errors [based on VIM 5.5].

T.5.6 Reference conditions

A set of reference values, or reference ranges of influence quantities prescribed for testing the performance of the EUT, or the inter-comparison of the results of measurements [based on VIM 5.7].

T.5.7 Preconditioning

Treatment of the EUT, with the object of removing, or partly counteracting, the effects of its previous history. Where called for, it is the first process in the test procedure.

T.5.8 Conditioning

Exposure of the EUT to an environmental condition (influence factor or disturbance) in order to determine the effect of such a condition on it.

T.5.9 Recovery

Treatment of the EUT, after conditioning, in order that the properties of the EUT may be stabilised before measurement.

T.5.10 Performance test

A test intended to verify whether the EUT is capable of accomplishing its intended functions.

T.5.11 Function test

A test at reference conditions at the start and at the end of the type evaluation test to check the pulse and timer accuracy of the instrument.

Supprimé : T.5.11 Simulation testA test carried out on the EUT in which any part of the measurement operation is simulated to verify its performance.¶

T.5.12 Function control test

A test to verify the pulse and timer accuracy of the instrument during and after each influence factor and disturbance test.

T.6 Symbols, units and abbreviations

MPE	Maximum permissible error
EUT	Equipment Under Test
ms^{-2}	Metres per second per second
ASD	Acceleration spectral density

TAXIMETERS

1 GENERAL

1.1 Scope

This International Recommendation specifies the metrological and technical requirements and test procedures for taximeters that are subject to national metrological control.

It is intended to provide standardized requirements and testing procedures to evaluate the metrological and technical characteristics in a uniform and traceable way.

1.2 Application

This Recommendation applies to taximeters that calculate fares charged for journeys according to defined tariffs.

This Recommendation does not apply to mechanical taximeters.

1.3 Terminology

The terminology given in the terminology section shall be considered part of this Recommendation.

2 METROLOGICAL REQUIREMENTS

2.1 Main function of the taximeter

The taximeter shall be designed to measure the duration, and calculate the distance of a fare-paying journey based on a signal delivered by a distance measurement transducer.

Additionally, it calculates and displays on the indicator, the fare to be paid on a journey based on the calculated distance and/or the measured duration of the journey.

2.2 Accuracy class

The taximeter shall be designated with one accuracy class, which shall be marked on the taximeter in accordance with the descriptive markings in 3.12.

2.3 Maximum permissible errors (MPE)

2.3.1 Initial verification

The maximum permissible errors on initial verification are:

(a) For the time measured, the greatest value of:
  (i) 2 s,
  (ii) ± 0.1 % of the duration;
(b) For the distance measured, the greatest value of:
  (i) 4 m,
  (ii) ± 0.2 % of the distance, or a lower accuracy as necessitated by the vehicle constant w, where the minimum value for w is specified by the manufacturer;

Mis en forme : Retrait : Avant : -0,32 cm, Suspendu : 0,32 cm

Supprimé : Taximeter

Supprimé : system

Supprimé : for a taximeter

Supprimé : , or a lower accuracy as necessitated by the vehicle constant w, in the event that the w is less than 500 pulses per kilometre

(c) For the fare calculated: ± 0.1% for the fare calculation. Allowance shall be made for the rounding of the least significant digit of the fare indication.

2.3.2 In-service verification

Unless otherwise specified in national regulations, the maximum permissible errors for in-service verification of a vehicle unit shall be as follows:

(a) ± 0.2 % of the duration, or a lower accuracy as necessitated by the vehicle constant w, where the minimum value for w is specified by the manufacturer;
(b) ± 4 % of the distance;
(c) a difference of less than 0.5 % of the taximeter constant 'k' from the constant 'w' on the vehicle on which the taximeter is mounted.

2.4 Taximeter accuracy conformance over time

Taximeters shall be designed to provide a level of confidence "near to certainty", that the accuracy and operation of the taximeter is within the requirements of this Recommendation for a period of at least one year of normal use. Any malfunction shall be automatically and clearly indicated (e.g. by a fault indication or by automatic switch off). The documentation submitted by the manufacturer (A.1.1) shall include a description of how this requirement is met.

The level of confidence shall take account of uncertainties of measurement, significant faults and failure of the instrument.

2.5 Units of measurement

The units of measurement to be used on a taximeter are:

- time, in seconds, minutes and hours;
- distance, in metres (m) or kilometres (km), or as specified in national regulation;
- the fare, as specified in national regulation.

2.6 Influence quantities

Unless otherwise specified by the manufacturer, the climatic, mechanical and electromagnetic operating influences on the taximeter shall be determined in accordance with the test conditions in Annex A.

2.6.1 Temperature

If no particular working temperature is specified by the manufacturer, then depending on local environmental conditions and/or national regulation, the taximeter shall maintain its metrological properties within the following temperature limits:

- the lower temperature limit shall be -40 °C, -25 °C, or -10 °C
- the higher temperature shall be + 40 °C, +55 °C, or +70 °C

2.6.2 DC power supply

A taximeter shall comply with the appropriate metrological and technical requirements, if the voltage supply varies from the nominal voltage from the lower and upper limits of the voltage range marked on the instrument at:

Supprimé : (d) ± 0.1 % accuracy of the number of pulses counted by the calculating (processing of the distance and time measurement signals) with a value not exceeding one of the following values, whichever is greater:0.1% accuracy of the number of pulses corresponding with 10 fare increment stepsSee Clause 6 for the functional tests for determining the pulse (distance) and time accuracy.

Supprimé : is less than 5000 pulses per kilometre

Supprimé : 2

Supprimé : or

Supprimé : 0.2

Supprimé : and it is not possible to verify continuously their satisfactory performance

Supprimé : shall be

Supprimé : shall be

Supprimé : shall be

Supprimé : Refer to sections Annex A for

Supprimé : stated in the descriptive markings of a taximeter

Supprimé : For special applications, however, the limits of the temperature range may differ provided that this range shall not be less than 80 °C and shall be specified in the descriptive markings. The limits may be chosen according to national regulation.

12 V road vehicle battery supply: lower limit is 9 V, upper limit is 16 V
24 V road vehicle battery supply: lower limit is 16 V, upper limit is 32 V

The taximeter shall either continue to function correctly or not indicate any measurement values if the voltage supply is below the lower operating limit specified by the manufacturer.

2.7 Constant k of the taximeter

The taximeter constant k shall not be lower than 500 pulses per kilometre and it shall be possible to adjust it to the vehicle constant w with such accuracy that the maximum permissible error is not exceeded. It shall be possible to display the constant k on the taximeter as a readily accessible decimal number. Every change of the constant k shall be secured in accordance with 3.2.5. The use of the taximeter shall not be possible when the change registration capacity is exceeded. That capacity will be defined by the manufacturer.

Supprimé : 2.7 Adjustment of the vehicle constant w ¶
It shall be possible to adjust a taximeter for the vehicle constant w of the vehicle in which it is to be installed and to secure the adjustment in accordance with the securing conditions specified in 3.2.5.

2.8 Real-time clock

The taximeter shall be equipped with a real time-clock by means of which the time of the day and the date are kept. One or both values shall be used for the automatic change of tariffs, and the following requirements apply:

a) The time keeping shall have an accuracy of 0.02 %
b) The time shall be correctable by no more than 2 minutes per week.
c) Correction for summer and winter time shall be performed automatically in applicable countries and comply with the securing requirements in 3.2.5.
d) Other time corrections, automatic or manually, shall be prevented during a journey, unless during in-service inspection mode as specified in 3.14.3, or in accordance with national regulation and the securing requirements in 3.2.5.

Supprimé : shall be 2 minutes per month

In the event of an interruption of the power, the real time clock shall continue to function correctly, and retain the correct time and date in the taximeter for at least one year, unless otherwise specified in national regulation.

Supprimé : 24 hours

2.9 Additional functions of a vehicle unit

In addition to the main functions of a taximeter described in 2.1, a taximeter complete with a vehicle installed distance measurement transducer shall ensure the following functions:

- detection and notification of events and/or faults
- reading, recording and storing in data storage;
- printing;
- data transmission and downloading to and from external devices;
- in-service inspection functions;
- driver manual entry functions;
- time correction functions;
- security functions;
- other functions as described in 3.14.3.

3 TECHNICAL REQUIREMENTS

3.1 Suitability for use

A taximeter shall be designed to suit the method of operation and vehicles for which it is intended. It shall be of adequately robust construction in order that it maintains its metrological characteristics.

3.2 Security of operation

3.2.1 Fraudulent use

A taximeter shall have no characteristics likely to facilitate its fraudulent use.

3.2.2 Accidental breakdown and maladjustment

A taximeter shall be so constructed that an accidental breakdown or maladjustment of devices likely to disturb its correct functioning cannot take place without its effect being evident.

3.2.3 Calculator

The taximeter shall be designed in such a way as to permit easy inspection and adjustments of the calculator in order to assess its functionality and to conform to changes in its functions imposed by national regulations. Any malfunction shall be clearly indicated (e.g. by a significant fault indication or by automatic switch off).

Supprimé : necessary

3.2.4 Controls

Controls on taximeters shall be so designed that they cannot normally come to rest in positions other than those intended by design, unless during the manoeuvre all indication is made impossible. Keys shall be marked unambiguously.

3.2.5 Securing of functions, devices, software and pre-set controls

Means shall be provided for securing taximeter functions, measurement data, interfaces and pre-set controls, to which access, adjustment or removal is prohibited. National regulation may specify the securing that is required.

Securing shall be provided by hardware, passwords or similar software means provided that:

(a) access shall only be allowed to authorised persons, e.g. by means of an event counter (T.2.5) or an automatic checking facility (T.3.6.1) providing an information record of the access;
(b) any access to the secured controls or functions becomes automatically evident, e.g. by means of an event counter or an automatic checking facility automatically updating a device-specific parameter the value of which at the time of the last verified set-up had been durably marked on the instrument in accordance with the requirements of 3.12.4;
(c) a minimum of ten of the most recent access or changes to the metrological functions shall be recorded and retained by the taximeter in its data memory;
(d) protection of device-specific and software functions against intentional, unintentional and accidental changes shall be provided in accordance with the requirements in 3.11;
(e) detection of physical tampering or removal of taximeter hardware shall be provided (e.g. seals);

(f) transmission of legally relevant data via interfaces shall be secured against intentional, unintentional and accidental changes in accordance with the requirements in 4.2.3;
(g) the securing possibilities available in a taximeter shall be such that separate securing of the settings is possible.

3.3 Fare calculation

The interval of fare to pay, and the monetary symbols shall comply with national regulation.

The calculation of fare can be carried out by one of the following methods:

a) Normal calculation method S (single application of tariff)

The change from time-counting to distance-counting and vice versa shall take place when the time or distance tariff is applied to the cross-over speed in accordance with the selected tariff.

b) Normal calculation method D (double application of tariff)

Subsequent changes in the combined calculation of time and distance tariff shall take place after a combination of time elapsed and distance travelled in accordance with the selected tariff.

If both method S and method D are possible in a taximeter, the option of switching between them shall be by a secured setting in accordance with 3.2.5.

The indications for fare calculation shall comply with 3.9.1

3.4 Tariff programming

3.4.1 Tariff data

The tariff data of each allocated tariff may include the following:

- initial hire fee;
- initial time;
- initial distance;
- time-tariff value;
- distance-tariff value;
- supplementary charge increment, if appropriate;
- signature of the corresponding tariff data;
- software identification.

3.4.2 Input of tariff data

It shall be possible to secure the access to the level where tariff data can be changed in accordance with the securing requirements 3.2.5.

The tariff data may be entered individually via an appropriate protective user interface(s).

Unauthorised or unintentional tariff re-programming due to interfacing with other equipment shall conform to the securing requirements in 3.2.5.

If the taximeter is capable of having its tariffs re-programmed in advance of the effective date, those tariffs shall not become effective until that date.

3.5 Operating position indication

The operating positions for the tariff based measurement results allocated to individual registers in a taximeter are distinguished on the indicator as follows:

Supprimé : mechanism

Supprimé : of the taximeter system shall be capable of being set in motion only after having been engaged by an operational mode control system in one of the following operating modes:

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3.5.1 'For hire' (free) position

In 'For hire' (free) position the fare calculation is disabled (i.e. time-counting and distance-counting are inactive).

In 'For hire' (free) position it shall be possible to display, when relevant, the following parameters:

a) all elements of the indicator display;
b) the contents of totalizers (see 3.4);
c) the constant k expressed in pulses per kilometre;
d) the contents of the event counters;
e) the tariff data of each allocated tariff (see 3.4.1).

The above parameters shall not be displayed for more than 10 seconds when the vehicle is moving.

Other indications in 'For hire' (free) position are permitted provided that they are in accordance with national regulation, they shall not be interpreted as fare or supplement indication and their use is subject to the security of operation requirements in 3.2.

3.5.2 'Hired' (occupied) position

In 'Hired' (occupied) position the fare calculation takes place on the basis of a possible initial charge and a tariff for distance travelled and/or duration of the journey (i.e. time-counting and distance-counting are active).

The indications in 'Hired' (occupied) position at the beginning of the journey shall be in the following order:

a) the initial charge,
b) the first fare indication, followed by subsequent fare indication changes corresponding to the initial and then successive equal time intervals or distances specified in the applied tariff;

Indications in 'Hired' (occupied) position may also include the distance and time displays provided they comply with the quality of indication requirements in 3.9.1. In addition, all indications in 'Hired' (occupied) position shall be in accordance with national regulation.

3.5.3 'Stopped' (to pay) position

In 'Stopped' (to pay) position the fare due for the journey is indicated and fare calculation based on time is disabled (i.e. time-counting inactive and distance-counting are active at the appropriate tariff).

Supprimé : When an initial predetermined distance (maximun 250 metres or a distance in accordance with national regulations) has been travelled in the 'STOPPED' (TO PAY) , the taximeter shall automatically switch to the 'FOR HIRE' (FREE) .

The indications in 'Stopped' (to pay) position at the end of the journey shall be:

a) the fare to be paid for the journey, or

b) If there is a supplementary charge for an extra service, entered by manual command, this shall be displayed separately from the indicated fare. However, in this case a taximeter may indicate temporarily the value of the fare including the supplementary charge.

Supprimé : seperately

In the case of b) the indication of the supplement shall be made by figures with a height not more than that of the figures indicating the fare.

The indications in the 'Stopped' position shall comply with 3.9.1.

3.5.4 'Measure' position for the normal calculation method D (double application of tariff) system

If the fare calculation is according to the normal calculation method D, the taximeter shall be equipped with the 'Measure' position in which the distance and duration of the journey are measured and displayed in real time on a separate indicator as follows:

a) time measured in hours with the smallest increment of 30 seconds;
b) distance measured shall have a resolution better than or equal to 0.1 km;
c) readings for both time and duration may be given at the same time, or may be recalled one after the other by means of the operating position indicator;
d) the indicated unit of measurement shall comply with the conditions in 3.9.1 so that there can be no confusion as to the quantity indicated.

3.6 Additional requirements for the operating position indicator

The indication of the operating positions is subject to the following requirements:

a) In 'Stopped' (to pay) position and before the start of any new journey, the indication of the fare at the end of a previous journey shall be displayed for a sufficient period (at least 10 seconds, or for a period in accordance with national regulation);
b) The design of the operating position indication shall ensure that any change in operating positions shall be secured in accordance with 3.2.5;
c) It shall not be possible to switch to any other operating positions other than those mentioned above, unless otherwise specified in national regulation.

3.7 Totalizers

A taximeter shall be fitted with non-resettable totalizers which can clearly and unambiguously display all of the following values:

a) total distance travelled by the taxi;
b) total distance travelled when hired;
c) total number of journeys;
d) total amount of money charged as supplements;
e) total amount of money charged as fare.

Other data may be totalled and indicated provided that they are in accordance with national regulation and are secured in accordance with 3.9.1 to prevent the display of totalized values being used to deceive passengers.

Values saved under conditions of power loss shall be included in the total.

Totalized values shall be displayed for a maximum of 10 seconds, or in accordance with national regulation.

Totalized values shall be stored for at least one year for the purposes of transferring the values to another device.

3.8 Automatic change of tariffs

The automatic change of tariffs may be triggered by the:

a) distance of the journey;
b) duration of the journey;
c) time of day;
d) date;
e) day of the week; or
f) other data specified in accordance with national regulation.

Each change of tariff shall be secured in accordance with 3.2.5.

3.9 Indicating and printing

3.9.1 Quality of reading

The primary indications shall be by means of a display or hard copy. Reading of the primary indications (T.4.1.2) shall be reliable, easy and unambiguous under conditions of normal use including in the daylight and night, and the figures forming the indications shall be of a size of at least 10 mm in height, shape and clarity for easy reading.

Primary indications shall contain names or symbols of the units of measurement and comply with the requirements of 2.5.

The indicator display shall be so designed that the indications of interest to the passenger are suitably identified and readable from a distance of 2 meters.

A digital indication shall show at least one figure beginning at the extreme right.

Supprimé : of the decimal sign

A decimal fraction value shall be separated from its integer by a decimal sign (comma or dot), with the indication showing at least one figure to the left of the decimal sign and all figures to the right of the decimal sign.

Zero may be indicated by one zero to the extreme right, without a decimal sign.

3.9.2 Printing

Printing of hard copy shall be clear and permanent for the intended use. Printed figures shall be clear, legible and unambiguous.

If printing takes place, the name or the symbol of the unit of measurement shall be either to the right of the value or above a column of values, or placed in accordance with national regulation.

Multiple copies of the print-out containing the same data must be marked “copy” or “duplicate”.

The minimum printout resulting from each measurement operation shall be dependent upon the application of the taximeter and in accordance with national regulation. In general the printout information may include the following:

– programmed tariff;
– fare;
– supplementary charge;
– distance and duration of the journey;
– date and the time of the journey

3.10 Data storage

Measurement data, legally relevant software and parameters may be stored in a memory of the taximeter (hard drive), or on a universal computer storage, or on external storage for subsequent indication, printing, data transfer, totalising, etc. In all cases, the data shall be adequately protected against intentional and unintentional changes during the transfer process and stored data shall contain all relevant information necessary to reconstruct an earlier measurement.

For securing data storage, the following apply:

a) Secured software transmission and downloading process in accordance with the requirements in 3.11;
b) External storage devices identification and security attributes shall be verified to ensure integrity and authenticity;
c) Exchangeable storage media is sealed against removing in accordance with 3.2.5;
d) Device specific parameters are not stored on the standard storages of the universal computer but in separate hardware that can be sealed in accordance with 3.2.5;
e) When storage capacity is exhausted, new data shall replace oldest data.

3.11 Software

The legally relevant software of a taximeter shall be identified by the manufacturer, i.e., the software that is critical for measurement characteristics, measurement data and metrologically important parameters, stored or transmitted, and software programmed to detect system fault (software and hardware), is considered as an essential part of a taximeter and shall meet the requirements for securing software specified below. National regulation may specify other requirements for securing software.

Supprimé : metrologically

3.11.1 Software documentation

The software documentation provided by the manufacturer shall include:

a) A description of the legally relevant software;
b) A description of the accuracy of the measuring algorithms (e.g. programming modes);
c) A description of the user interface, menus and dialogues;
d) The unambiguous software identification;
e) An overview of the system hardware, e.g. topology block diagram, type of computer(s), source code for software functions, etc, if not described in the operating manual;
f) Means of securing software;
g) The operating manual.

3.11.2 Means of securing software

The following means of securing legally relevant software apply:

(a) legally relevant software shall be adequately protected against accidental or intentional changes by means of an audit trail from a software event counter (T.2.5) and/or automatic checking facility (T.3.6.1) providing information record of the changes to legally

relevant software or parameter. Evidence of an intervention such as changing, uploading or circumventing the software shall be non-erasable, automatically recorded and stored for at least one year, or for a period set in accordance with national regulation;

(b) legally relevant software shall be assigned with a software identification (see T.2.10.4) which shall be adapted in the case of every software change that may affect the functions and accuracy of the taximeter. In addition, downloading of legally relevant software shall be with appended software identification, target equipment identification and security attributes to ensure integrity and authenticity. In this case, the software identification is considered as device-specific parameters (see T.2.10.3 and 3.2.5). Software identification shall be easily provided by the taximeter;

(c) downloading of legally relevant software and data shall be through appropriate protective interfaces connected to the taximeter;

(d) functions that are performed or initiated via a software interface shall meet the relevant requirements and conditions of 4.2.3.

3.12 Descriptive markings

Taximeters shall bear the following markings at each location having a fare indicating or printing device:

- name or identification mark of manufacturer;
- name or identification mark of the importer (if applicable);
- serial number and type designation of the taximeter;
- accuracy class;
- type approval sign;
- power supply V;
- relevant data in respect of the conditions of use;
- number of the type examination certificate;
- date of manufacture;
- specified range of the constant 'k' km $^{-1}$;
- temperature range °C;
- software identification.

Supprimé : (when not -40°C to 70°C)

Other markings may be specified in accordance with national regulation provided they are applied in accordance with the requirements in 3.2.

3.12.1 Supplementary markings

Depending upon the particular use of the taximeter, one or more supplementary markings may be required on type approval by the metrological authority issuing the type approval certificate. For example, where a particular taximeter is verified using a particular type of vehicle (e.g. air suspension systems only), then this should be marked on the taximeter.

3.12.2 Presentation of descriptive markings

Descriptive markings shall be indelible and of a size, shape and clarity that permit legibility under normal conditions of use of the instrument. Markings shall be grouped together in a clearly visible place on the instrument, either on a descriptive plate fixed near the indicating device or on the indicating device itself. It shall be possible to seal the plate bearing the markings, unless it cannot be removed without being destroyed.

Descriptive markings may be shown in an official language in accordance with national regulation.

As an alternative all applicable markings in 3.12 may be simultaneously displayed by a

software solution either permanently or on manual command. In this case the markings are considered as device-specific parameters (see T.2.10.3 and 3.2.5).

The descriptive markings may be shown on a programmable display which is controlled by software. In this case, the requirements of 3.11 shall apply.

3.13 Verification Marks

After every in-service verification, new markings shall replace the old markings, bearing at least the following:

- approving authority name and address
- vehicle constant 'w'
- specified range of the taximeter constant 'k' km $^{-1}$;
- date on which the vehicle constant 'w' was determined.
- vehicle identification number (see T.2.14).

3.13.1 Position of verification marks

A place shall be provided for the application of verification marks. This place shall:

a) be such that the part on which the marks are located cannot be removed from the taximeter without damaging the marks;
b) permit the easy application of the marks without changing the metrological qualities of the taximeter;
c) be clearly and visibly marked on, in or near the fare indicating device when the taximeter is in service.

3.13.2 Mounting of verification marks

Taximeters shall have a verification mark support located as specified above, which shall ensure the conservation of the marks as follows:

a) when the mark is made with a stamp, the support may consist of a strip of lead or any other material with similar qualities (for example plastic, brass etc. depending on national regulation) inserted into a plate fixed to the instrument or a cavity bored into the instrument;
b) when the mark consists of an adhesive transfer, a space shall be provided for this purpose.

Supprimé : legislation

3.14 Installation and test conditions

3.14.1 General

Taximeters shall be manufactured, tested and installed so as to minimise any adverse effects of the testing and installation environment. If the correct testing or operation of the taximeter is likely to be affected by the properties of other connected equipment and the vehicle in which it is installed, then the taximeter shall be provided with a means to secure the correct testing and operation of the taximeter (e.g. a test connector as specified in 4.2.3 for testing purposes). Where particular details of installation have an effect on the accuracy of the taximeter these details shall be recorded in the test report.

Supprimé : type approval

3.14.2 Taximeter compatibility with distance measurement transducer

A taximeter shall be installed in accordance with the manufacturer's installation instructions providing that it comply with the requirements of this OIML Recommendation, especially the requirements in Clauses 3 for securing and security of operation and suitability for use.

Taximeters shall be installed non-activated, with all metrological and technical parameters set to appropriate and valid default values. Before activation, taximeters shall neither store nor transmit measurement data. During installation, all known parameters shall be pre-set.

Taximeters shall be connected to a vehicle installed distance measurement transducer to ensure the correct functioning of the vehicle unit to meet the requirements of this OIML Recommendation, especially the requirements in Clause 3. Further information is provided in Annex B.

In-service verification markings shall be applied in accordance with 3.13.

Supprimé : 3.13.2 Taximeter interfacingtaximeter3.13.3 Post-installation testingFor the purpose of testing after installation, the taximeter shall enable testing of time and distance measurement and the accuracy of the calculation.

3.14.3 Taximeter operation modes

A taximeter connected to the above distance measurement transducer shall possess at least the following modes of operation:

- operational mode (T.3.7)
- in-service mode (T.3.8)

All functions listed in 2.9 shall work in any mode of operation after activation with the following exceptions:

- the in-service inspection function is accessible in the in-service mode only;
- time correction is possible only in the in-service mode;
- driver manual entries functions during the journey (entry of places where the daily work periods begin and/or end for a driver) are accessible in the operational mode;
- downloading of legally relevant software is not accessible in the operational mode.

The in-service mode shall allow the taximeter to:

- automatically pair the distance measurement transducer with the vehicle unit;
- digitally adapt the taximeter constant (k) to the vehicle constant (w);
- adjust (without limitation) the current time;
- adjust the current odometer value,
- record and update vehicle unit details (vehicle unit identification, distance measurement transducer identification);
- record and store details of the metrological authority, vehicle identification and parameters updated or confirmed: w, k, tyre size, odometer (old and new values), date and time (old and new values), time adjustment data including (date and time, old value, date and time, new value), most recent in-service inspection.

4 ELECTRONIC REQUIREMENTS

4.1 General requirements

Taximeters shall comply with the following requirements in addition to the applicable requirements of all other clauses of this recommendation.

4.1.1 Rated operating conditions

Taximeters shall be so designed and manufactured that they do not exceed the maximum permissible errors under rated operating conditions.

4.1.2 Influence quantities

Taximeters shall comply with the requirements of 2.6 and shall also comply with appropriate metrological and technical requirements under conditions of high relative humidity above 93 % when combined with cyclic temperature changes and condensation.

4.1.3 Disturbances

Taximeters shall be so designed and manufactured that when exposed to disturbances, either

a) significant faults do not occur (i.e. the difference between the indication due to the disturbance and the indication without the disturbance (intrinsic error), either shall not exceed the value given in T.4.2.6, or
b) significant faults are detected and acted upon. The indication of significant faults in the display should not be confusing with other messages that appear in the display.

4.1.4 Durability

The requirements in 4.1.1, 4.1.2 and 4.1.3 shall be met durably in accordance with the intended use of the instrument.

4.1.5 Evaluation for compliance

A type of a taximeter is presumed to comply with the requirements of 4.1.1, 4.1.2, 4.1.3 if it passes the examination and tests specified in Annex A.

Supprimé : an electronic

4.1.6 Application

The requirements in 4.1.3 may be applied separately to each:

a) individual cause of significant fault, and/or
b) part of the electronic instrument.

The choice of whether 4.1.3 (a) or (b) is applied is left to the manufacturer.

4.2 Functional requirements

4.2.1 Indicator display test

Upon switch-on (switch-on of indication), a display test procedure shall be performed that shows all relevant signs of the indicator in their active and non-active state sufficiently long to be checked by the operator. This is not applicable for non-segmented displays, on which failures become evident, for example screen-displays, matrix-displays, etc

Supprimé : which is automatically or manually initiated upon switch-on

4.2.2 Acting upon significant faults

When a significant fault has been occurred, either the taximeter shall be made inoperative automatically, or a visual or audible indication shall be provided automatically and shall continue until the user takes action or the fault disappears.

4.2.3 Interface

A taximeter shall be equipped with communication interfaces (T.2.7) permitting the coupling of the taximeter to any other instruments or the vehicle for automatic transmission of information, and a user interface (T.2.8) permitting the exchange of information exchange between a human user and the taximeter.

A taximeter shall be able to transmit the following data through appropriate protective interfaces:

- operation position: 'For Hire ','Hired 'or 'Stopped';
- totalizer data according to 3.7;
- general information: constant of the distance measurement transducer, date of securing, vehicle identification, real time, tariff identification;
- fare information for a journey: total charged, fare, calculation of the fare, supplement charge, date, start time, finish time, distance travelled;
- tariff(s) information: parameters of tariff(s).

4.2.3.1 Interface documentation

The manufacturer shall provide documentation on all taximeter interfaces comprising of at least:

a) A list of all commands (e.g. menu items);
b) Description of the software interface;
c) A list of all commands together;
d) A brief description of their meaning and their effect on the functions and data of the measuring instrument.

4.2.3.2 Securing of taximeter interfaces

Communication and user interfaces shall not allow the metrological functions of the taximeter and its legally relevant software and measurement data to be inadmissibly influenced by other interconnected instruments, or by disturbances acting on the interface. The following means of securing taximeter interfaces apply:

a) Data is protected (for example, with a protective interface as in T.2.9) against accidental or deliberate interference during the transfer;
b) All functions in the software interface shall be subject to the requirements for securing software in 3.11;
c) All functions in the hardware interface shall be subject to the requirements for securing hardware in 3.2.5;
d) Metrologically relevant parts of the target instrument shall be included in the initial verification (or equivalent conformity assessment procedures);
e) it shall be easily possible to verify the authenticity and integrity of data transmitted to and/or from the taximeter and the target instrument;
f) Functions performed or initiated by other connected instruments through the interfaces shall meet the appropriate requirements of this OIML Recommendation.

Other instruments required by national regulation to be connected to the interfaces of a taximeter shall be secured to inhibit automatically the operation of the taximeter for reasons of the non-presence or improper functioning of the required device.

Supprimé : <#>4.2.3.1 Wirel ess interfaceall times ¶

4.2.4 Test connector interface

In addition to the requirements in 4.2.3, taximeters interfacing with a test connector shall ensure the correct communication of the data in Table 1 and any other applicable test data.

Supprimé : to a pulse sensor

Table 1 - Test connection information

Input:	Output:
Distance pulses at a rate equivalent to a speed of up to 200 km/h	Distance pulses
Time pulses at a rate equivalent of up to 10 times real time;	Time pulses
Signal to block time counting.	A signal to indicate fare increments.
The electrical data of the signals must be compatible with the following:	
Signal LOW (logic 0) -12 V< U_I < 0.8 V	Signal LOW (logic 0) 0 V< U_I < 1 V (1)
Signal HIGH (logic 1) 3 V< Uh < 12 V	Signal HIGH (logic 1) 3 V< Uh < 5 V (1)
Input resistance R, > 4, 7 k ohms	Source resistance Rs < 10 k ohms. (1)
Notes:	(1) No load at test pin. (2) Signals are referred to ground on the test connector, normally the negative line of the taximeter voltage supply. (3) All signals shall be of rectangular shape with a pulse width of at least 25 µs and a rise and fall time of 20% the pulse width.

The test connector shall be secured against unauthorised access in accordance with 3.2.5.

4.2.5 Voltage drop below the minimum operating voltage (2.6.2)

In case of a voltage drop below the minimum operating voltage, the taximeter shall automatically:

(a) continue to function correctly or resume its correct functioning without loss of data available before the voltage drop if the voltage drop is temporary (e.g. less than 20 seconds), i.e. due to restarting the vehicle engine;
(b) abort an existing measurement and return to the 'For hire' (free) position if the voltage drop is for a longer period (e.g. less than 60 seconds). In this case, the taximeter shall resume its correct functioning and the stored measurement data concerning the aborted journey must be correct;
(c) show a significant fault or is automatically put out of service if the voltage drop is for a lengthy period (e.g. longer than 60 seconds).

Supprimé : longer than 20 seconds.

In all cases, the period of the voltage drop may be set in accordance with national regulation;

If disconnected from the voltage supply, a taximeter shall store the totalized values for at least one year or for a period set in accordance with national regulations.

4.2.6 Repeatability

The application of the same taximeter under the same conditions of measurement shall result in the close agreement of successive measurements. The difference between the successive measurement results shall be less than the appropriate MPE in 2.3.

4.3 Examination and tests

The examination and testing of a taximeter and any devices having metrological influence is intended to verify compliance with the applicable requirements of this Recommendation.

4.3.1 Examination

A taximeter having metrological influence shall be examined to obtain a general appraisal of the design and construction.

Devices may be examined and tested only once while being connected to a taximeter, and may be declared as suitable for connection to any verified taximeter having an appropriate and protective interface.

A description of the operation and type of devices fitted to the taximeter shall be included in the type approval certificate.

4.3.2 Performance tests

A taximeter shall be tested as specified in Annex A to determine the correct functioning of the equipment.

As far as applicable, the same tests shall be performed as for complete instruments.

Susceptibility that would result from the use of electronic interfaces to other equipment shall be determined in the tests.

Supprimé : 4.2.4.1 Rated operating voltageThe functional and performance tests specified in Annex A and B shall be performed at the rated operating voltage of 12 V for 12 V systems. For other voltage systems (see 2.6.2) the appropriate corresponding voltages shall be applied.

Supprimé : simulated

4.3.3 Metrological features to be considered

All metrologically relevant features and functions (see T.3 and T.4) have to be tested at least once in a taximeter as far as applicable and as many as possible in the same taximeter. Variations in metrologically relevant features and functions like different housings, temperature and humidity ranges, instrument functions, indications, etc. may require additional partial testing of those factors which are influenced by that feature. These additional tests should preferably be carried out on the same taximeter, but if this is not possible, tests on one or more additional taximeter may be performed under the responsibility of the testing authority.

5 METROLOGICAL CONTROLS

5.1 General

The metrological controls of taximeters shall, in agreement with national regulation, consist of:

– type approval,
– initial verification,
– subsequent verification
– in-service inspection.

Tests should be applied uniformly by the legal metrology services and should form a uniform program. Guidance for the conduct of type approval and initial verification is provided in OIML International Documents D 19, [5] and D 20, [6] respectively.

5.2 Type approval

5.2.1 Documentation

The application for type approval of the taximeter having metrological influence shall include documentation comprising:

- the technical and electronic specifications;
- the metrological characteristics of the taximeter;
- a functional description of the taximeter and its devices;
- drawings, diagrams, and general software information, source code and operation manual, explaining the construction and operation;
- list of tariffs provided on the taximeter;
- any document or other evidence that the design and construction of the taximeter and devices complies with the requirements of this Recommendation.

Note: Adherence to requirements for which no test is available, such as software-based operations, may be demonstrated by a specific declaration of the manufacturer (e.g. for interfaces as per 4.2.3, and for password protected access to set-up and adjustment operations as per 3.2.5.

5.2.2 General requirements

Type evaluation shall be carried out on one or more taximeters submitted in a form suitable for laboratory tests. The type evaluation shall consist of tests specified in 5.2.3.

Supprimé : systems or simulator. If the performance of a taximeter could be affected by a particular manner of operation or a particular manner of use for which conditions cannot be duplicated other than in a in-situ operation then it shall be installed at a typical site. At least one of the shall be

Supprimé : simulation

5.2.3 Type Evaluation

The submitted documents shall be examined and tests carried out to verify that the taximeter complies with the:

a) metrological requirements in Clause 2, particularly with reference to the appropriate limits of error and the operating conditions specified by the manufacturer,
b) technical requirements in Clause 3,
c) requirements for electronic instruments in Clause 4.

The appropriate metrological authority shall conduct the tests in a manner that prevents an unnecessary commitment of resources, and permit the results of the tests to be assessed for initial verification

Note: The appropriate metrological authority is advised to accept, with the consent of the applicant, test data obtained from other metrological authorities without repeating tests.

5.2.3.1 Type evaluation tests

Type evaluation tests shall be done:

a) in accordance with the descriptive markings (3.12);
b) under the normal rated operating conditions for which the taximeter is intended;

c) to assess compliance with the requirements for security of operation in 3.2;
d) influence factors shall be applied to the taximeter as specified in 2.6;
e) in accordance with the test methods in 6.2;
f) either on the premises of the metrological authority to which the application has been submitted, or in any other suitable place agreed between the metrological authority concerned and the applicant.

The metrological authority may require the applicant to supply equipment and personnel to perform the tests.

5.2.3.2 Type approval certificate

The following information shall appear on the type approval certificate:

– name and address of the recipient of the certificate
– name and address of the manufacturer, if not the recipient
– type and/or commercial designation
– metrological and technical characteristics
– type approval mark
– information on the location of marks for type approval, initial verification, sealing
– list of documents accompanying the type approval certificate; and
– specific remarks.

If applicable, the version of the metrological part of the evaluated software shall be indicated in the type approval certificate or its annexes.

5.2.3.3 Determination of accuracy requirements

Accuracy requirements shall be determined in accordance with the appropriate parts of 2.3.1 by compliance with the metrological requirements at initial verification of the taximeter.

5.3 Initial verification

5.3.1 General requirements

Initial verification tests shall be carried out by the appropriate metrological authority in accordance with 5.3.2 to establish conformity of the taximeter to the approved type and the requirements of this Recommendation.

During the initial verification tests, the taximeter shall include all devices which form the assembly as intended for normal operational use.

The appropriate metrological authority shall conduct the tests in a manner that prevents an unnecessary commitment of resources. In appropriate situations and to avoid duplicating tests previously performed on the taximeter for type evaluation under 5.2.3, the authority may use the results of observed tests for type evaluation.

5.3.2 Initial verification tests

Initial verification tests shall be done:

a) in accordance with the metrological requirements in Clause 2, technical requirements in Clause 3 (especially the descriptive markings in 3.12), and the test methods in 6.3;
b) under the normal operating conditions for which the taximeter is intended;

Supprimé : on a complete taximeter

Supprimé : system or simulator

Supprimé : perfom

Supprimé : <#>5.2.3.2 Apportioning of errors to modules tested separatelySubject to agreement with the approving authority, the manufacturer may define and submit modules to be examined separately. Where modules are examined separately in the process of type approval, the following requirements applyThe error limits applicable to a module which is examined separately are equal to a fraction P_i of the maximum permissible errors. The fractions for any module have to be taken for at least the same accuracy class as for the complete instrument incorporating the module.The fractions P_i shall satisfy the following equation:$P_1^2 + P_2^2 + P_3^2 + ... \leq 1$The fraction P_i shall be chosen by the manufacturer of the module and shall be verified by an appropriate test, taking into account the following conditions:For digital modules p_i may be equal to 0¶ <#>For all other modules, the fraction shall not exceed 0.8 and shall not be less than 0.3, when more than one module contributes to the effect in question.Note: As the requirements of this subclause only apply to the instrument submitted for type evaluation and not to those subsequently submitted for verification, the means by which it will be possible to determine whether the appropriate accuracy requirement has been met will be decided mutually between the metrological authority and the applicant. For example:an adaptation of an indicating module or printer, or¶ <#>use of a suitable test connector, or¶ ... [1]

Supprimé : <#>period of validity¶

Supprimé : in a normal installation

Supprimé : and under normal operating conditions of use,

Supprimé : The taximeter system shall be installed so that a measurement operation will be the same for testing as it is for a normal operation. Where appropriate, pshall be conductedin order to determine the influences of the vehi ... [2]

c) in two stages:
   1) in a laboratory environment or any other suitable place agreed between the metrological authority concerned and the applicant to examine the metrological characteristics of the taximeter without the influence of the vehicle, and
   2) vehicle installed unit (see T.1.3) in order to determine the influences of the vehicle on the metrological properties of the taximeter (6.3).

The metrological authority may require the applicant to supply equipment and personnel to perform the tests.

Supprimé : c) at the place of use of the taximeter system.

Supprimé : perfom

Accuracy requirements shall be determined in accordance with the appropriate parts of 2.3.1.

5.4 Subsequent metrological control

5.4.1 Subsequent verification

Subsequent verification shall be carried out in accordance with the same provisions as in 5.3 for initial verification

5.4.2 In-service inspection

In-service inspection shall be carried out in accordance with the same provisions as in 5.3 for initial verification with the exception that the in-service maximum permissible errors in 2.3.2 shall be applied.

6 TEST METHOD

6.1 General

Taximeters shall be tested in accordance with the requirements in this Clause. All the relevant test information, indications and functional performance shall be recorded for the tests.

6.2 Functional tests

Function and function control tests are intended to verify that taximeters can maintain the performance required during or after the application of influences and disturbances (A.6.4). Functional tests are conducted in accordance with the test program in Table 2.

6.2.1 Function control under influences and disturbances (A.5.1.2)

Taximeter pulse and time accuracy (A.5.2) function control test is conducted during the application of the influences and disturbances, are performed according to the calculation methods (3.3) featured in the taximeter

6.2.2 Function test at reference conditions (A.5.1.1)

Taximeter time and distance (pulse) accuracy function test is conducted at reference conditions at the start and at the end of the test program in accordance with Table 2. The function tests are performed according to the calculation methods (3.3) featured in the taximeter and shall then be repeated for the lowest, middle and highest values of:

a) the specified pulse frequency range (from 5 km/h up to a maximum speed of at least 200 km/h as specified by the manufacturer)
b) pulse voltage levels
c) k values (minimum as specified in 2.8. Maximum specified by the manufacturer)

The function tests shall also be performed for a selection of the available programming modes and/or tariffs (including automatic changes).

6.3 Visual examination

The EUT shall be carefully checked for any visible deterioration after each test. Details of observations shall be noted and recorded.

6.4 Test report format

The results of the tests shall be recorded in the test report format given in Annex C.

6.5 Program of performance tests (A.4.1)

Table 2 – Performance test program

Test designation	Test	Test reference
A	Initial function test at reference conditions.	A.5.1.1
B	Dry heat and cold function control test.	A.5.1.2 and A.6.4.1
	Visual examination.	A.5.1.3
C	Damp heat cyclic test (condensing).	A.6.4.2
	Function control, and visual examination after damp heat cyclic test	A.5.1.2 and A.5.1.3
D	DC voltage supply function control test.	A.5.1.2 and A.6.4.3
	Visual examination	A.5.1.3
E	Random vibration function control test	A.5.1.2 and A.6.4.4.1
	Visual examination	A.5.1.3
	Sinusoidal vibration function control test.	A.5.1.2 and A.6.4.4.2
	Visual examination.	A.5.1.3
F	Radiated electromagnetic fields test.	A.6.4.5.1
	Conducted electromagnetic fields test.	A.6.4.5.2
	Electrostatic discharges test.	A.6.4.6
	Function control, and visual examination after electrostatic discharge test.	A.5.1.2 and A.5.1.3
G	Electrical transient conduction along supply lines	A.6.4.7.1
	Electrical transient conduction via lines other lines than supply lines	A.6.4.7.2
	Function control, and visual examination after transient conduction via lines other lines	A.5.1.2 and A.5.1.3
H	Slow dips below 9 V DC supply	A.6.5
	Function control, and visual examination test after slow dips test.	A.5.1.2 and A.5.1.3
I	Function test at reference conditions.	A.5.1.1, A.5.1.3

6.6 Initial verification tests (A.4.2)

Initial verification of a taximeter, including all devices which form the assembly as intended for normal operational use, shall be conducted as follows:

1) Check for conformity with the approved type and verification of time counting, distance counting, adjustment of k and programmed tariff. In appropriate situations and to avoid duplicating tests previously performed on the taximeter under 6.2, the authority may use the results of observed tests from 6.2.

2) Verification of the requirements for descriptive markings (3.12), securing methods (3.2.5) and software (3.11).

ANNEX A (MANDATORY)

TEST PROCEDURES FOR TAXIMETERS

A.1 EXAMINATION FOR TYPE APPROVAL

A.1.1 Documentation

Review the documentation that is submitted to determine if it is adequate and correct. Consider the operational manual. For type approval the documentation shall be as specified in 5.2.1.

A.1.2 Compare construction with documentation

Examine the various devices of the taximeter to ensure compliance with the documentation (5.2) in accordance with 4.3.

A.1.3 Metrological characteristics

Note the metrological characteristics using the checklist in the test report format in Annex C.

A.1.4 Technical requirements

Examine the taximeter for conformity with the technical requirements of Clause 3, using the checklist in the test report format in Annex C.

Supprimé : instrument

A.1.5 Functional requirements

Examine the taximeter for conformity with the functional requirements according to the details given in 4.2 and 4.3, using the checklist given in the test report format in Annex C.

A.2 EXAMINATION FOR INITIAL VERIFICATION

A.2.1 Compare construction with documentation

Examine the taximeter for conformity with the approved type in accordance with the requirements in 5.3.1.

A.2.2 Descriptive markings

Check the descriptive markings in accordance with 3.12 using the checklist in the test report format in Annex C.

A.2.3 Verification marks and sealing devices

Check the arrangement for verification marks and sealing in accordance with 3.2.5 and 3.12, using the checklist given in the test report format in Annex C.

A.2.4 Software

Check the requirements for the legally relevant software in accordance with 3.11 using the checklist in the test report format in Annex C.

A.3 GENERAL TEST REQUIREMENTS

A.3.1 Power supply (2.6.2)

Power-up the EUT and maintain the EUT energised for the duration of each test, unless otherwise specified in the test.

A.3.2 Temperature (2.6.1)

The tests shall be performed at a steady ambient temperature unless otherwise specified.

There shall be no condensation of water on the EUT unless otherwise specified for each test.

A.3.3 Recovery

After each test the EUT shall be allowed to recover sufficiently before the next test.

A.4 TEST PROGRAM

A.4.1 Type approval (5.2)

Examination for type approval in A.1 and the performance tests in A.6 shall normally be applied for type evaluation.

Supprimé : and in-situ testing in A.7.1

A.4.2 Initial verification (5.3)

Examination for initial verification in A.2 shall normally be applied for initial verification.

Supprimé : and in-situ testing in A.7.2

A.5 FUNCTIONAL TESTS AND VISUAL EXAMINATION

A.5.1 General

Tests shall be conducted using a test connector meeting the requirements of 4.2.4, a calibrated pulse counter and a calibrated timer.

A.5.1.1 Function test at reference conditions (6.2.2)

Function test in A.5.2 to check pulse and timer accuracy shall be conducted at reference conditions in accordance with the test program in Table 2 and the summary in Table 3.

Table 3 - Summary of function tests

Test conditions	Characteristics under test	Criterion	Error allowance	Procedure
Rated operating conditions	Rated operating voltage	Pulse and timer error	maximum permissible error (see 2.3.1)	A.5.2
	Pulse voltage levels: lowest, medium and highest			
	Pulse frequency levels: lowest, medium and highest			
	Specified k values: lowest, medium and highest			
	Featured calculation methods S and method D			
	Specified tariffs			

A.5.1.2 Function control test during performance testing (6.2.1)

Function control in A.5.1.2 to check the pulse and timer accuracy are conducted as specified for each influence and disturbance test in accordance with the test program in Table 2 and the summary in Table 4.

Table 3 - Summary of function control tests

Test conditions	Characteristics under test	Criterion	Error allowance	Procedure
As specified for each test	Static temperatures	Pulse and timer error	maximum permissible error (see 2.3.1)	A.5.2
	Voltage supply range limits			
	Temperature/relative humidity cycles			
	Random or sinusoidal vibration in each of three mutually perpendicular axes			
	Electrostatic discharges test			
	Electrical transient conduction.			
	Voltage dips below minimum operation limit. control test			

A.5.1.3 Visual examination (6.3)

The EUT shall be inspected visually during the tests in accordance with the test program in Table 2.

A.5.2 Pulse and timer accuracy

Distance and time counting accuracy tests are conducted as follows:

a) With the taximeter in 'For hire' (free) position and pulses at an appropriate frequency present at the pulse input of the taximeter, use a test connector and a pulse counter to measure the number of pulses generated, and test connector and a timer to measure the time elapsed, between switching the taximeter to 'Hired' (occupied) position and the initial charge by one fare increment step.
b) Compare the (actual) number of pulses counted to the number expected (reference) according to the programmed tariff, and compare the time measured (actual) to the time expected (reference) according to the programmed tariff;
c) Check for compliance of the two parameters (pulse and time) with the applicable initial verification maximum permissible error limits in 2.3.1, taking into consideration the distance represented by each pulse.

Note: The pulse frequency is determined by the speed of the vehicle simulated at up to 200 km/h and the number of pulses per distance of the particular transducer being simulated. When using this speed, it should be at least 10 fare increment steps.

A.6 PERFORMANCE TESTS

Supprimé : DURING TYPE EVALUATION

A.6.1 General test conditions

Metrological performance tests are intended to verify that taximeters can function as intended in the climatic, mechanical and electromagnetic environments and under the conditions specified. Each test indicates, where appropriate, the reference condition under which the intrinsic error is determined.

Where possible, tests shall be carried out on a taximeter in its normal operational state under laboratory conditions. The permissible effects of the influence factors or disturbances, under these laboratory conditions, are specified for each test in Annex A.

When the effect of one influence factor is being evaluated, all other factors are to be held relatively constant, at a value close to normal. After each test, the taximeter shall be subjected to the recovery condition as specified in A.3.3. The operational status of the taximeter shall be recorded for each test.

When a taximeter is connected in other than a normal configuration, the procedure shall be mutually agreed on by the metrological authority and the applicant.

Supprimé : unless the size and/or configuration of the instrument do not permit testing as a whole. In these cases, the may be subjected to influence factor tests under simula

A.6.2 Interfaces (4.2.3)

Susceptibility that would result from the use of interfaces to other equipment shall be determined in the tests.

Supprimé : A.6.2 Simulator requirements**The simulator for influence factor and disturbance tests should include all electronic modules of the taximeter system**

Supprimé : simulated

Supprimé : For this purpose, either an appropriate or interface cable to simulate the interface impedance of the other equipment shall be connected to each different type of interface.¶

Supprimé : Simulators

A.6.3 Documentation

Taximeters shall be defined in terms of hardware and functionality by reference to the EUT, and by any other documentation necessary to ensure reproducible test conditions. This information shall be attached to, or traceable from, the test report.

A.6.4 Influence factor and disturbance tests (2.6, 4.1.1)

Summary of tests

Test	Characteristic under test	Criterion	§
Static temperatures	influence	MPE	A.6.4.1
Damp heat (condensing)	disturbance	sf	A.6.4.2
Voltage supply	influence	MPE	A.6.4.3
Vibration (random or sinusoidal)	influence	MPE	A.6.4.4
Electromagnetic fields	disturbance	MPE	A.6.4.5
Electrostatic discharge	disturbance	MPE	A.6.4.6
Electrical transient conduction on supply lines or via lines other than supply lines	disturbance	MPE	A.6.4.7
Voltage slow dips	influence	MPE	A.6.5
Note: MPE - maximum permissible error (2.3.1) sf - significant fault (T.4.2.6)			

A.6.4.1 Static temperatures (2.6.1)

Static temperature tests are carried out according to basic standard IEC 60068-2-1 [7], IEC 60068-2-2 [8], IEC 60068-3-1 [9], and according to Table 5.

Table 5 - Dry heat (non-condensing) and cold

Environmental phenomena	Test specification	Test set-up
Temperature	Reference temperature of 20 °C	IEC 60068-2-2 IEC 60068-2-1 IEC 60068-3-1
	Specified high temperature for 2 hours	
	Specified low temperature for 2 hours	
	Reference temperature of 20 °C	
Note: Use IEC 60068-3-1 for background information.		

Supplementary information to the IEC test procedures:

Object of the test:	To verify compliance with the provisions in 4.1.1 under conditions of dry heat (non-condensing) and cold.
Test procedure in brief:	The test consists of exposure of the EUT to a steady ambient temperature within the range stated in 2.6.1, under free air conditions, for a 2 hour period after the EUT has reached temperature stability and for performing the required measurements. «Free air» conditions mean a minimum air circulation to keep the temperature at a stable level.
Pre-condition:	None.
Condition of the EUT:	Voltage supply "on" for the duration of the test. The EUT shall not be readjusted at any time during the test. Sufficient temperature stabilisation after each test.
Test sequence	In accordance with 2.6.1: a) at the reference temperature; b) at the specified high temperature; c) at the specified low temperature; and d) at the reference temperature.
Number of test cycles:	At least one cycle.
Test information:	After stabilisation at the reference temperature and again at each specified temperature conduct the function control test (A.5.1.2) and record: (a) date and time; (b) temperature; (c) relative humidity; (d) supply voltage; (e) pulse voltage levels (f) frequency levels (g) errors; (h) functional performance (i) indications (as applicable); The change of temperature shall not exceed 1 ^{0}C/min during heating and cooling down.
Maximum allowable variations:	All functions shall operate as designed. All errors shall be within the maximum permissible errors specified in 2.3.1.

A.6.4.2 Damp heat cyclic (condensing) test (4.1.2)

Damp heat, cyclic tests are carried out according to basic standard IEC 60068-3-4 [10], IEC 60068-2-30 [11], and according to Table 6.

Table 6 - Damp heat, cyclic test

Environmental phenomena	Test specification	Test set-up
Damp heat, cyclic	Temperature variations for 24 hours.	IEC 60068-2-30 IEC 60068-3-4
	Reference temperature of 20 °C at 95 % relative humidity.	
	Specified high temperature at 93 % relative humidity.	

Supplementary information to the IEC test procedures:

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Object of the test:	To verify compliance with the provisions in 4.1.2 after conditions of high humidity.
Test procedure in brief:	
Pre-condition:	None required.
Condition of the EUT:	Voltage supply "off" for the duration of the test. The handling of the EUT shall be such that condensation should occur on the EUT during the temperature rise. All parts of the EUT are within 3 °C of their final temperature.
Test sequence	24 hour cycle sequence: (a) Temperature rise during the first 3 hours. (b) Temperature maintained at the upper limit until 12 hours from start of the cycle. (c) Temperature lowered to reference limit within 3-6 hours. (d) Temperature maintained at the reference limit until the 24-hour cycle is completed.
Number of test cycles:	At least two cycles.
Test information:	After sufficient temperature stabilisation, conduct the test and record: (a) date and time; (b) temperature; (c) relative humidity; (d) supply voltage; (e) pulse voltage levels (f) frequency levels (g) errors; (h) functional performance (i) indications (as applicable);

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Maximum allowable variations:	All functions shall operate as designed. After the disturbance, no significant fault shall occur.
Note:	Function control (A.5.1.2) is conducted immediately after completion of the damp heat, cyclic test.

A.6.4.3 Voltage supply (2.6.2)

12 V and 24 V road vehicle voltage supply tests are carried out according to ISO 16750-2 [12], and according to Table 7.

Table 7 – DC voltage supply variations

Environmental phenomena	Test specification			Test set-up
	U_{nom}	Upper limit	Lower limit	
12 V and 24 V road vehicle battery tests	12 V	16 V	9 V	ISO 16750-2
	24 V	32 V	16 V	
Note: The nominal voltage (U_{nom}) of the electrical system in road vehicles is usually 12 V or 24 V. But the practical voltage at the battery-terminal points can vary considerably.				

Supplementary information to the ISO test procedures:

Object of the test:	To verify compliance with the provisions in 4.1.1 under conditions of voltage range limits in 12 V or 24 V road vehicle battery supply.
Test procedure in brief:	The test consists of exposure to the specified battery condition for a period sufficient for achieving temperature stability and for performing the required measurements.
Preconditioning:	None
Condition of the EUT:	Voltage supply "on" for the duration of the test. The EUT shall not be readjusted at any time during the test.
Number of test cycles:	At least one cycle.
Test information:	After stabilization of the EUT at the nominal voltage conduct the function control test (A.5.1.2) at the upper and lower limits and record: (a) date and time; (b) temperature; (c) relative humidity; (d) supply voltage; (e) pulse voltage levels (f) frequency levels (g) errors; (h) functional performance (i) indications (as applicable);
Maximum allowable variations:	All functions shall operate as designed. All errors shall be within the maximum permissible errors specified in 2.3.1.

A.6.4.4 Vibration (random or sinusoidal)

Two different vibration tests (random or sinusoidal) are described below. In general, the random vibration test is recommended. The sinusoidal vibration test may be applied if specified by the manufacturer. Guidance for the selection amongst both the tests can be found in IEC 60068-3-8 [13].

A.6.4.4.1 Vibration (random)

Vibration (random) tests are carried out according to basic standard IEC 60068-2-64 [14], IEC 60068-2-47 [15], IEC 60068-3-8 [13], and according to Table 8.

Table 8 - Vibration (random)

Environmental phenomena	Test specification		Test set-up
Random vibrations	Frequency range:	10 to 150 Hz	IEC 60068-2-64 IEC 60068-2-47 IEC 60068-3-8
	Total RMS level:	7 ms^{-2}	
	ASD level 10 - 20 Hz:	1 m^2s^{-3}	
	ASD level 20 - 150 Hz:	-3 dB/octave	
	Number of axes:	3	
	Duration per axis:	At least 30 minutes in each functional mode.	

Supprimé : 2

Supprimé : or a longer period if necessary for testing the various functions of the EUT.

Supplementary information to the IEC test procedures:

Object of the test:	To verify that the EUT complies with the provisions in 4.1.1 under conditions of random vibrations.
Test procedure in brief:	
Pre-condition:	None required.
Condition of the EUT:	Voltage supply "on" for the duration of the test. Mount the EUT on a rigid fixture by its normal mounting means, such that the gravitational force acts in the same direction as it would in normal use. Where the effect of gravitational force is not important, the EUT may be mounted in any position.
Test sequence	In accordance with the specifications in Table 8, apply random vibrations, over the specified frequency range, to the EUT, in three mutually perpendicular axes (2 horizontal and 1 vertical) in turn, for 30 minutes per axis in each functional mode.
Number of test cycles:	At least one cycle.
Test information:	Conduct the function control test (A.5.1.2) and record: (a) date and time; (b) temperature; (c) frequency range;

Supprimé : a sufficient period

(d) total RMS
(e) ASD levels;
(f) number of axes and duration per axis
(g) pulse levels
(h) frequency levels;
(i) errors;
(j) functional performance
(k) indications (as applicable);

Maximum allowable variations: All functions shall operate as designed.
All errors shall be within the maximum permissible errors specified in 2.3.1.

A.6.4.4.2 Vibration (sinusoidal)

Vibration (sinusoidal) tests are carried out according to basic standard IEC 60068-2-6 [16], IEC 60068-2-47 [15], IEC 60068-3-8 [13], and according to Table 9.

Table 9 - Vibration (sinusoidal)

Environmental phenomena	Test specification		Test set-up
Sinusoidal vibrations	Frequency range:	10 to 150 Hz	IEC 60068-2-6 IEC 60068-2-47 IEC 60068-3-8
	Max acceleration level:	10 ms^{-2}	
	Number of axes:	3	
	Number of sweeps per axis	20	

Supplementary information to the IEC test procedures:

Object of the test: To verify that the EUT complies with the provisions in 4.1.1 under conditions of sinusoidal vibrations.

Test procedure in brief:

Pre-condition: None required.

Condition of the EUT: Normal voltage "on" for the duration of the test.

Mount the EUT on a rigid fixture by its normal mounting means, such that the gravitational force acts in the same direction as it would in normal use. Where the effect of gravitational force is not important, the EUT may be mounted in any position.

Test sequence: In accordance with the specifications in Table 9, apply sinusoidal vibrations, over the specified frequency range, at 1 octave/min, at the specified acceleration level with a specified number of sweep per axis, in three mutually perpendicular main axes (2 horizontal and 1 vertical) of the rigidly mounted EUT

Number of test cycles: At least one cycle.

Test information: Conduct the function control test (A.5.1.2) and record:

(a) date and time;

(b) temperature;
(c) frequency range;
(d) acceleration level
(e) sweep per axis;
(f) number of axes and duration per axis
(g) pulse levels
(h) frequency levels;
(i) errors;
(j) functional performance
(k) indications (as applicable);

Maximum allowable variations: All functions shall operate as designed.
All errors shall be within the maximum permissible errors specified in 2.3.1.

A.6.4.5 Electromagnetic fields

A.6.4.5.1 Radiated radio frequency, electromagnetic fields

Radiated, radio frequency, electromagnetic field immunity tests are carried out in accordance to IEC 61000-4-3 [17], and according to Table 10.

The unmodulated carrier of the test signal is adjusted to the indicated test value. To perform the test the carrier is in addition modulated as specified.

Table 10 - Radiated electromagnetic fields

Test specification			
Environmental phenomena	Frequency ranges MHz	Field strength (V/m)	Test set-up
Radiated electromagnetic field	80 to 2000(1)	24	IEC 61000-4-3
	26 to 80(2)		
	1400 to 2000		
Modulation	80 % AM, 1 kHz sine wave		
Notes:	(1) IEC 61000-4-3 only specifies test levels above 80 MHz. For frequencies in the lower range the test methods for conducted radio frequency disturbances are recommended (A.6.4.2.2). (2) For EUT having no mains or other I/O ports available so that the test according to A.6.4.2.2 cannot be applied, the lower limit of the radiation test is 26 MHz.		

Supprimé : 10

Supplementary information to the IEC test procedures:

Object of the test: To verify compliance with the provisions in 4.1.3 under conditions of specified electromagnetic fields applied to the taximeter.

Test procedure in brief: The EUT shall be exposed to electromagnetic field strength as specified in Table 10.

Pre-condition:	None required.
Condition of the EUT:	Before any test stabilise the EUT under constant environmental conditions. The electromagnetic field can be generated in different facilities, the use of which is limited by the dimensions of the EUT and the frequency range of the facility.
Test sequence:	When using an electronic pulse generator to simulate the pulses produced by a typical distance measurement transducer, care should also be taken not to let the pulse generator be affected by the electromagnetic waves by using a suitable method of electromagnetic isolation. Alternatively a mechanically driven pulse generator may be used.
Test information:	Record: (a) date and time; (b) temperature; (c) test set-up information; (d) supply voltage; (e) indications (as applicable); (f) errors; (g) functional performance
Maximum allowable variations:	All functions shall operate as designed. All errors shall be within the maximum permissible errors specified in 2.3.1.

Supprimé : The EUT shall detect and act upon a significant fault.

A.6.4.5.2 Conducted radio-frequency, electromagnetic fields

Conducted, radio frequency, electromagnetic field immunity tests (radio-frequency electromagnetic fields lower than 80 MHz) are carried out in accordance to IEC 61000-4-6 [18], and according to Table 11.

Table 11 - Conducted electromagnetic susceptibility

Test specification			
Environmental phenomena	Frequency range MHz	RF amplitude (50 ohms) V (e.m.f)	Test set-up
Conducted electromagnetic field	0.15 to 80	10 V	IEC 61000-4-6
Modulation	80 % AM, 1 kHz sine wave		

Supplementary information to the IEC test procedures:

Object of the test:	To verify compliance with the provisions in 4.1.3 under conditions of specified conducted electromagnetic fields.
Test procedure in brief:	The EUT shall be exposed to electromagnetic field strength as specified in Table 11.
Pre-condition:	The performance of the test equipment, consisting of an RF generator, RF amplifiers, (de-)coupling devices, attenuators, etc.,

shall be verified before testing commences.

Condition of the EUT: Before any test, stabilise the EUT under constant environmental conditions.

Test sequence: Radio frequency electromagnetic current, simulating the influence of electromagnetic fields on conductors, shall be coupled or injected into EUT ports for voltage, inputs, and outputs using coupling/decoupling devices as defined in the referred standard.

Test information: Record:

(a) date and time;
(b) temperature;
(c) test set-up information;
(d) supply voltage;
(e) indications (as applicable);
(f) errors;
(g) functional performance

Maximum allowable variations: All functions shall operate as designed.
All errors shall be within the maximum permissible errors specified in 2.3.1.

Supprimé : The EUT shall detect and act upon a significant fault.

A.6.4.6 Electrostatic discharge tests

Electrostatic discharge tests are carried out in accordance to IEC 61000-4-2 [19], and according to Table 12.

Table 12 - Electrostatic discharge tests

Environmental phenomena	Test specification		Test set-up
Electrostatic discharge	Test voltage	Levels	IEC 61000-4-2
	contact discharge	6 kV	
	air discharge	8 kV	
Notes: 1) Tests shall be performed at the specified lower voltage levels in the IEC 61000-4-2 standard up to and including the voltage levels given in Table 12. 2) The 6 kV contact discharge shall be applied to conductive accessible parts. Metallic contacts, e.g. in battery compartments or in socket outlets are excluded from this requirement.			

Supprimé : above

Supplementary information to the IEC test procedures:

Object of the test: To verify compliance with the provisions in 4.1.3 under conditions where electrostatic discharges are applied.

Test procedure in brief: The EUT shall be exposed to electrostatic discharge tests as specified in Table 12.

Pre-condition: Before starting the tests, the performance of the electrostatic discharge generator as defined in IEC 61000-4-2 shall be verified.

Condition of the EUT: Before any test stabilise the EUT under constant environmental

conditions.

Test sequence: The taximeter and any relevant devices will be operational during this test.

At least 10 discharges shall be applied. The time interval between successive discharges shall be at least 10 seconds. For EUT not equipped with a ground terminal, the EUT shall be fully discharged between discharges.

Contact discharge is the preferred test method. air discharges shall be used were contact discharge cannot be applied.

Direct application:
In the contact discharge mode to be carried out on conductive surfaces, the electrode shall be in contact with the EUT.
In the air discharge mode on insulated surfaces, the electrode is approached to the EUT and the discharge occurs by spark.

Indirect application:
The discharges are applied in the contact mode to coupling planes mounted near the EUT.

Test information: Record:

(a) date and time;
(b) temperature;
(c) test set-up information;
(d) supply voltage;
(e) indications (as applicable);
(f) errors;
(g) functional performance

Maximum allowable variations: All functions shall operate as designed.
All errors shall be within the maximum permissible errors specified in 2.3.1.

Mis en forme : Espace Après : 6 pt

Note: Function control (A.5.1.2) is conducted after completion of the electrostatic discharge test.

A.6.4.7 Electrical transient conduction

A.6.4.7.1 Conduction along supply lines of 12 V and 24 V batteries

For this test refer to ISO 7637-2 [20], and according to Table 13.

Table 13 - Electrical transient conduction on supply lines

Environmental phenomena	Test specification			Test set-up
Electrical transient conduction on supply lines	Test pulse	Pulse voltage U_s		ISO 7637-2
		U_{nom} = 12 V	U_{nom} = 24 V	
	1	-100 V	-600 V	
	2a	+50 V	+50 V	
	2b	+10 V	+20 V	
	3a	-150 V	-200 V	
	3b	+100 V	+200 V	

	4	-7 V	-16 V	

Notes:
1) Test pulse 2b is only applicable if the instrument is connected to the battery via the main (ignition) switch of the car, i.e. if the manufacturer has not specified that the instrument is to be connected directly (or by its own main switch) to the battery.
2) No reference has been made to test pulses 5a and 5b

Supplementary information to the ISO test procedures

Applicable standards	ISO 7637-2	§ 5.6.1: Test pulse 1 § 5.6.2: Test pulse 2a + b, § 5.6.3: Test pulse 3a + 3b, § 5.6.4: Test pulse 4

Object of the test: To verify compliance with the provisions in 4.1.3 under the following conditions:

- transients on the supply lines due to supply disconnection from inductive loads (pulse 1);
- transients due to a sudden interruption of currents in a device connected in parallel with the device under test due to the inductance of the wiring harness (pulse 2a);
- transients from DC motors acting as generators after the ignition is switched off (pulse 2b);
- transients on the supply lines, which occur as a result of the switching processes (pulses 3a and 3b);
- voltage reductions caused by energizing the starter-motor circuits of internal combustion engines (pulse 4).

Test Procedures in brief:

Preconditioning: None

Condition of the EUT: Before any test, stabilize the EUT under constant environmental conditions.

Test sequence: The test consists of exposure to conducted disturbances on the voltage supply by direct brief coupling onto supply lines of the strength and character as specified in Table 13 while the taximeter is switched on.

Test information: Record:

(a) date and time;
(b) temperature;
(c) test set-up information;
(d) supply voltage;
(e) indications (as applicable);
(f) errors;
(g) functional performance

Maximum allowable variations: All functions shall operate as designed.
No significant error during the disturbance, except for test 2b. For test 2b, no significant error after the disturbance.

A.6.4.7.2 Electrical transient conduction via lines other than supply lines of 12 V and 24 V batteries.

Electrical conduction by capacitive and inductive coupling on signal lines are carried out in accordance to ISO 7637-3 [21], and according to Table 14.

Table 14 – Electrical transient conduction via lines other than supply lines

Environmental phenomena	Test specification			Test set-up
Electrical transient conduction via lines other than supply lines	Test pulse	Pulse voltage U_s		ISO 7637-3
		U_{nom} = 12 V	U_{nom} = 24 V	
	a	-60 V	-80 V	
	b	+40 V	+80 V	

Supplementary information to the ISO test procedures

Object of the test:	To verify compliance with the provisions in 4.1.3 under conditions of transients which occur via lines other than supply lines because of the switching processes (pulses a, and b).
Test procedure in brief:	
Preconditioning:	None
Condition of the EUT:	Before any test stabilise the EUT under constant environmental conditions
Test sequence:	The test consists of exposure of the EUT to conducted disturbances (bursts of voltage spikes by capacitive and inductive coupling on signal lines) of the strength and character as specified in Table 14 while the taximeter is switched on.
Test information:	Apply the test pulses and record the following: (a) date and time; (b) temperature; (c) test set-up information; (d) supply voltage; (e) indications (as applicable); (f) errors; (g) functional performance Repeat the test for the defined pulses and record the indications.
Maximum allowable variations:	All functions shall operate as designed. No significant error during the disturbance
Note:	Function control (A.5.1.2) is conducted immediately after completion of the test for electrical transient conduction via lines other than supply lines.

A.6.4 Voltage drop below the minimum operating voltage (4.2.5)

There is no reference to standards for this test. Refer to Table 15 for the test conditions.

Table 15 - Voltage supply variations – slow dips

Environmental phenomena	Test specification			Test set-up
Slow dips below minimum operating voltage	% of lower value of voltage dip (V_i)	Width of dip (seconds)	Requirement	No reference standard at present
	90, 40, 0	7, 14	Taximeter should show the previously indicated fare	
		15, 17.5 20	Taximeter should show the previously indicated fare or switch to 'For hire' (free) position	
		21, 30	Taximeter should switch to 'For hire' position	
Note. For specifications of the voltage supply used during the test to simulate the battery, refer to ISO 7637-2 [20], clause 4.4 [8].				

Mis en forme : Espace Avant : 6 pt

Supplementary information to the IEC test procedures:

Object of the test: To verify compliance with the provisions in 4.1.1 under conditions of voltage variations below the minimum operating voltage.

Test procedure in brief: The test consists of exposure of the voltage supply to the specified conditions in Table 15 and to observe the behaviour of the taximeter.

Pre-condition: None

Condition of the EUT: Before any test stabilise the EUT under constant environmental conditions.

Test sequence: Manually apply slow voltage dips below the minimum operating voltage for the following varying amounts of time listed in Table 15.

Additionally, reverse (incorrect) polarity shall be applied for 30 seconds. This shall cause no detectable change in registered information.

If a standard voltage supply (with sufficient current capacity) is used in bench testing to simulate the battery, the low internal impedance of the battery shall also be simulated.

The continuous supply source shall have an internal resistance R_i less than 0.01 ohms DC and an internal impedance $Z_i = R_i$ for

	frequencies less than 400 Hz.
Test information:	The function control test in A.5.1.2 shall run during the application of the dips. Record: (a) date and time; (b) temperature; (c) relative humidity; (d) supply voltage; (e) indications (as applicable); (f) errors; (g) functional performance
Maximum allowable variations:	All functions shall operate as designed. All errors shall be within the maximum permissible errors specified in 2.3.1.
Notes:	For battery systems higher than 12 V, the relevant specifications should be applied. Function control (A.5.1.2) shall run immediately after the slow dips test.

A.7 PROCEDURE FOR VERIFICATION TESTS

Supprimé : IN-SITU

A.7.1 Type approval tests

For type approval, tests shall be carried out in accordance with the requirements of this Recommendation, and especially the requirements in 5.2 and A.1.

A.7.2 Initial verification tests

For initial verification, tests shall be carried out in accordance with the requirements of this Recommendation, and especially the requirements in 5.3 and A.2.

A.7.3 Subsequent verification tests

Supprimé : corresponding to the normal site operation of the taximeter

For subsequent and in-service verification, tests shall be carried out in accordance with the requirements of this Recommendation, and especially the requirements in 5.4. Further information is given in Annex B.

Supprimé : In this case, the limits of error in 2.3.2 apply. Where appropriate, parts of the initial verification may be conducted in a laboratory environment or the observed results for type tests may be used.

ANNEX B (INFORMATIVE)

GENERAL INFORMATION ON THE CONDITIONS FOR THE COMPATIBILITY BETWEEN A TAXIMETER AND A DISTANCE MEASUREMENT TRANSDUCER

B Compatibility for use with distance measurement generator

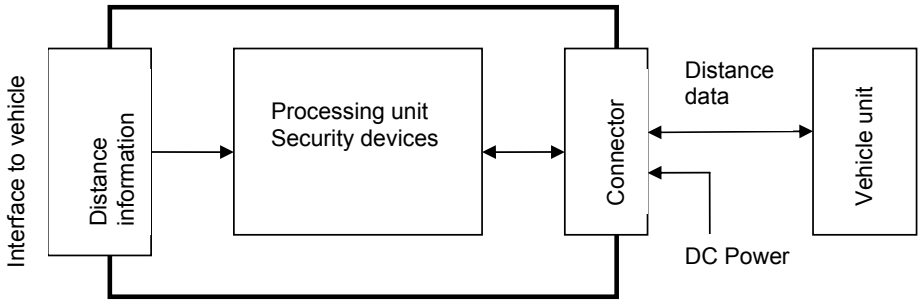
The conditions for the compatibility between the taximeter and the distance measurement generator shall specified by the manufacturer of the taximeter. This Annex provides additional information to ensure the conditions comply with the requirements of this OIML Recommendation.

B.1 Description and purpose

The distance measurement transducer is installed in road vehicles and its purpose is to provide a vehicle unit (T.1.3) with secured distance information representative of the distance travelled by the vehicle. The transducer is interfaced to a moving part of the vehicle and it may be located in any part of the vehicle. In its operational mode, the distance measurement transducer is connected to a vehicle unit.

The typical distance measurement transducer is described in Figure A.

Figure A - Typical distance measurement transducer



B.2 Suitability and security of operation

The design of the distance measurement transducer shall suit the method of operation and vehicle for which it is intended. The distance measurement transducer shall continuously measure distance travelled and transmit this information to the vehicle unit in accordance with the securing requirements in 3.2.5 so that the vehicle unit can determine accurately the movement of the vehicle in terms of distance travelled.

For vehicles to be used as a taxi (T.1.2), the following requirements apply:

a) The distance measurement transducer shall give a stable signal at every speed travelled.
b) The distance measurement transducer shall have defined characteristics regarding voltage level, pulse width and the relation of speed and frequency.

c) The distance measurement transducer shall be able to establish and authenticate, for any interaction, the identity of any device that it is connected to, at connection and at power supply recovery.
d) The distance measurement transducer shall ensure that motion information may only be processed and derived from the transducer mechanical interface.
e) Distance information shall be exchanged with associated security attributes so that the vehicle unit can meet the requirements of this Recommendation
f) The legally relevant software of a distance measurement transducer shall be identified by the manufacturer (e.g. vehicle constant factor k, interface parameters)

The distance measuring transducers may function as intelligent distance measuring transducers (T.2.10) with capabilities for secure processing, transmission and storage of information pertaining to the transducer identification and connected device identity.

B.3 Manufacturer documentation

The manufacturer of the distance measurement transducer shall include documentation comprising:

– name and address of the manufacturer;
– type and/or commercial designation;
– the technical specifications;
– the metrological characteristics of the transducer;
– a functional description of the transducer;
– drawings, diagrams, and general information, explaining the construction and operation;
– any document or other evidence that the design and construction of the transducer conforms to appropriate international standards.

Annex C Test Report Format

(Mandatory for application within the *OIML Certificate System for Measuring Instruments)*

EXPLANATORY NOTES ON THE TEST REPORT FORMAT

This "test report format" aims at presenting, in a standardized format, the results of the various tests and examinations to which a type of a taximeter shall be submitted with a view to its approval.

The *Test report forma*t consists of two parts, a "checklist" and the "test report" itself.

The checklist is a summary of the examinations carried out on the instrument. It includes the conclusions of the results of the test performed, experimental or visual checks based on the requirements of R21.

The test report is a record of the results of the tests carried out on the instrument. The "test report" forms have been produced based on the tests detailed in Annex A of this International Recommendation.

It is recommended that all metrology services or laboratories evaluating types of taximeter accordingly to R21 or to national or regional regulations based on this OIML Recommendation use this *Test report forma*t, directly or after translation into a language other than English or French.

It is also recommended that this *Test report forma*t in English or in French (or in both languages) be transmitted by the country performing these tests to the relevant authorities of another country, under bi- or multilateral cooperation agreements.

In the framework of the *OIML Certificate System for measuring instruments*, use of this *Test report forma*t is mandatory.

The "information concerning the test equipment used for type evaluation" shall cover all test equipment which has been used in determining the test results given in a report. The information may be a short list containing only essential data (name, type, reference number for purpose of traceability). For example:

- Verification standards (accuracy, or accuracy class, and No.)
- Simulator for testing of devices (name, type, traceability and No.)
- Climatic test and static temperature chamber (name, type and No.)
- Electrical tests, bursts (name of the instrument, type and No.)
- Description of the procedure of field calibration for the test of immunity to radiated electromagnetic fields

Note concerning the numbering of the following pages

In addition to a sequential numbering: "R21 page ..." at the bottom of the pages of this publication, a special place is left at the top of each page (starting with the following page) for numbering the pages of reports established following this model. In particular, some tests (e.g. metrological performance tests) shall be repeated several times, each test being reported individually on a separate page following the relevant format.

For a given report, it is advisable to complete the sequential numbering of each page by the indication of the total number of pages of the report.

Taximeter Supprimé : systems

TYPE EVALUATION REPORT

EXPLANATORY NOTES

Symbols, units and abbreviations:

MPE	Maximum permissible error
Rel. h.	Relative humidity
Temp	Temperature
Res.	Resolution
I	Indication (applicable currency unit)
Ref.	Reference (values)
EUT	Equipment Under Test
Hz	Hertz, cycles per second (unit of frequency measurement)
Ref.	Reference
AM	Amplitude modulation, varying the amplitude of a carrier wave in sympathy with a modulating audio signal
Pulses/km or km^{-1}	Pulses per kilometre
ASD	Acceleration spectral density
RMS	Root-mean-square acceleration

The name(s) or symbol(s) of the unit(s) used to express test results shall be specified in each test form.

For each test, the "SUMMARY OF TYPE EVALUATION" and the "CHECKLIST" shall be completed according to this example:

	P	F
when the instrument has passed the test:	X	
when the instrument has failed the test:		X
when the test is not applicable:	/	/

P = Passed
F = Failed

The white spaces in boxes in the headings of the report should always be filled according to the following example:

	At start	At end	
Temp:	20.5	21.1	°C
Rel. h.:			%
Date:	2006:01:29	2006:01:30	yyyy:mm:dd
Time:	16:00:05	16:30:25	hh:mm:ss

"Date" in the test report(s) refers to the date that the test was performed.

In the disturbance tests, faults greater than the value specified in T.4.2.6 are acceptable provided that they are detected and acted upon, or that they result from circumstances such that these faults shall not be considered as significant; an appropriate explanation shall be given in the column "Yes (remarks)".

Section numbers in brackets refer to the corresponding subclauses of R 21.

GENERAL INFORMATION CONCERNING THE TYPE

Application No:…… Manufacturer's name and address:…….

Applicant:…….. Date instrument submitted:……

Type designation:……. Evaluation period: Start:……. End:……...

Report date:…….. Observer:……

Issuing Institute name and address:……

Testing on: ☐ Taximeter ☐ Device[1]

Supprimé : Complete instrument

Supprimé : Module

Characteristic values:

Fare increment step (l)	Time tariff (l/h)			Distance tariff (l/km)			Instrument constant k (pulses/km)			Measuring range	
	Min	Max	Res.	Min	Max	Res.	Min	Max	Res.	Distance (km)	Time (h)

Power : U_{nom}[2] = ☐ V U_{min} = ☐ V U_{max} = ☐ V

Printer: ☐ Built-in ☐ Connected ☐ Not present but connectable ☐ No Connection

Temperature range: ☐ °C Min: ☐ °C Max: ☐ °C

[1] The test equipment connected to the taximeter shall be defined in the test form(s) used.

[2] The supply voltage U_{nom} of the electrical system is given in 2.6.2. For the specified voltage system for the instrument the appropriate corresponding voltages shall be applied for the tests.

GENERAL INFORMATION CONCERNING THE TYPE continued….

Additional Remarks:

Use this space to indicate additional remarks and/or information: other connected devices and interfaces, choice of the manufacturer regarding protection against disturbances, etc.

IDENTIFICATION OF THE INSTRUMENT

Application No: ……

Report date: ……

Type designation: ……

Manufacturer: ……..

Serial No: ……..

Manufacturing Documentation:

(Record as necessary to identify the equipment under test)

System or device name	Drawing number or software identification	Issue or reference level	Serial or reference No.

IDENTIFICATION OF THE INSTRUMENT (continued)

Description or other information pertaining to identification of the instrument: (*attach photograph here if available*)

INFORMATION CONCERNING THE TEST EQUIPMENT[3] USED FOR TYPE EVALUATION

TEST EQUIPMENT

Application No: ……

Report date: ……

Type designation: ……

Manufacturer: ……..

List all test equipment used in this report:

Equipment name or description	Manufacturer	Type or reference No.	Serial or Identification No.	Calibration date	Measurement Uncertainty (if applicable)	Used for (test references)
Power supply						
Pulse counter						
Timer						
Electrostatic discharge generator						
Pulse generator						
EMC chamber						
Climatic chamber						

[3] For traceability, test equipment with traceable calibration to national and international standards shall be used to perform the measurements.

CONFIGURATION FOR TEST

Provide additional information relating to equipment configuration, interfaces, data rates, EMC protection options etc, for the instrument and/or simulator.

Test connector:

– Input signals:		Output signals:	
Distance pulses:		Distance pulses:	
Low-high		Low-high	
High-low		High-low	
Max freq (Hz):			
Time pulses:		Time pulses:	
Low-high		Low-high	
High-low		High-low	
Min freq		Internal clock freq (Hz):	
Max freq (Hz):		Signal to indicate fare increment:	
Signal to block time-counting when:		Low-high signal	
Signal is low:		High-low signal	
Signal is high:			

Mise en forme : Puces et numéros

Distance sensor interface:

Low voltage	
High voltage	
Trigger:	
Low-high	

Use this space for additional information relating to equipment configuration.

SUMMARY OF TYPE TEST REPORT

Application No: ……

Report date: ……

Type designation: ……

Test reference		Description	Report page	Passed	Failed	Remarks
Table 2	Annex C					
A	C.1	Initial function test at reference conditions				
B	C.2.1	Dry heat and cold function test, and visual examination.				
C	C.2.2	Damp heat cyclic (condensing) test.				
	C.2.2.1	Function control, and visual examination after damp heat cyclic test				
D	C.2.3	DC voltage supply function test, and visual examination.				
E	C.2.4.1	Vibration (random) function test, and visual examination.				
	C.2.4.2	Vibration (sinusoidal) function test, and visual examination.				
F	C.2.5	Radiated electromagnetic fields/ Conducted disturbances test.				
	C.2.6	Electrostatic discharges test.				
	C.2.6.1	Function control and visual examination after electrostatic discharges test				
G	C.2.7.1	Electrical transient conduction along supply lines test.				
	C.2.7.2	Electrical transient conduction via lines other than supply lines test.				
	C.2.7.3	Function control, and visual examination after test for conduction via lines other than supply lines.				
H	C.2.8	Slow dips below 9 V DC				
	C.2.8.1	Function control, and visual examination after slow dips test.				
I	C.3	Function test at reference conditions				
A.1	C.4	**Examination of the construction**				
A.1		**Checklist**				

C.1 Function test at start of test program (A.5.1.1)

			At start	At end	
Application No:	.....	Temp:			°C
Type designation:	.....	Rel. h.:			%
Observer:	.....	Date:			yyyy:mm:dd
		Time:			hh:mm:ss

C.1.1 Initial test at reference conditions (A.5.2)

C.1.1.1 Voltage supply

Time measurement

Voltage supply[4]	Time measuring signal (Hz)		Number of test pulses		Indication (I)		Time tariff (I/h)	Time signal error		Test pulses Error		MPE %
	Actual	Ref.	Actual	Ref.	Start	End		Hz	%	pulses	%	
12 V DC												
24 V DC												

Pulse (distance) measurement

Voltage supply	Number of test pulses		Indication (I)		Instrument constant k (pulses/km)	Distance tariff (I/km)	Test pulses Error		MPE %
	Actual	Ref.	Start	End			pulses	%	
12 V DC									
24 V DC									

☐ Passed ☐ Failed

Remarks:

C.1.1.2 Pulse frequency levels (A.5.1.1)

Voltage at: ☐ V DC

Time measurement

Pulse frequency[5] (Hz)		Time measuring signal (Hz)		Number of test pulses		Indication (I)		Time tariff (I/h)	Time signal Error		Test pulses Error		MPE %
		Actual	Ref.	Actual	Ref.	Start	End		Hz	%	pulses	%	
Lowest													
Medium													
Highest													

Pulse (distance) measurement

Pulse frequency (Hz)		Number of test pulses		Indication (I)		Instrument constant k (pulses/km)	Distance tariff (I/km)	Test pulses Error		MPE %
		Actual	Ref.	Start	End			pulses	%	
Lowest										
Medium										
Highest										

☐ Passed ☐ Failed

Remarks:

[4] Tests are performed at the rated operating voltage for the specified voltage supply.
[5] At least 10 fare increment steps for subsequent distance at a simulated speed of 200 km/h.

C.1.1.3 Pulse voltage levels (A.5.1.1)

Voltage at: ☐ V DC

Time measurement

Pulse voltage (V)		Time measuring signal (Hz)		Number of test pulses		Indication (l)		Time tariff (l/h)	Time signal Error		Test pulses Error		MPE %
		Actual	Ref.	Actual	Ref.	Start	End		Hz	%	pulses	%	
Lowest													
Medium													
Highest													

Pulse (distance) measurement

Pulse voltage (V)		Number of test pulses		Indication (l)		Instrument constant k (pulses/km)	Distance tariff (l/km)	Test pulses Error		MPE %
		Actual	Ref.	Start	End			pulses	%	
Lowest										
Medium										
Highest										

☐ Passed ☐ Failed

Remarks:

C.1.1.4 Specified k values[6] (6.2.2, A.5.2)

Voltage at: ☐ V DC

Time measurement

Instrument constant k (pulses/km)		Time measuring signal (Hz)		Number of test pulses		Indication (l)		Time tariff (l/h)	Time signal Error		Test pulses Error		MPE %
		Actual	Ref.	Actual	Ref.	Start	End		Hz	%	pulses	%	
Lowest													
Medium													
Highest													

Pulse (distance) measurement

Instrument constant k (pulses/km)		Number of test pulses		Indication (l)		Instrument constant k (pulses/km)	Distance tariff (l/km)	Test pulses Error		MPE %
		Actual	Ref.	Start	End			pulses	%	
Lowest										
Medium										
Highest										

☐ Passed ☐ Failed

Remarks:

[6] k values (minimum as specified in 2.8. Maximum specified by the manufacturer)

C.1.1.5 Featured calculation method (A.5.1.1)

Voltage at: ☐ V DC

Time measurement

Calculation method set to:	Time measuring signal (Hz)		Number of test pulses		Indication (I)		Time tariff (I/h)	Time signal Error		Test pulses Error		MPE %
	Actual	Ref.	Actual	Ref.	Start	End		Hz	%	pulses	%	
Method S												
Method D												

Pulse (distance) measurement

Pulse voltage (V)	Number of test pulses		Indication (I)		Instrument constant k (pulses/km)	Distance tariff (I/km)	Test pulses Error		MPE %
	Actual	Ref.	Start	End			pulses	%	
Method S									
Method D									

☐ Passed ☐ Failed

Remarks:

C.1.1.6 Programmed tariffs[7] (6.2.2, A.5.2)

Voltage at: ☐ V DC

Time measurement

Programmed tariffs	Time measuring signal (Hz)		Number of test pulses		Indication (I)		Time tariff (I/h)	Time signal Error		Test pulses Error		MPE %
	Actual	Ref.	Actual	Ref.	Start	End		Hz	%	p	%	

Pulse (distance) measurement

Programmed tariffs	Number of test pulses		Indication (I)		Instrument constant k (pulses/km)	Distance tariff (I/km)	Test pulses Error		MPE %
	Actual	Ref.	Start	End			pulses	%	

☐ Passed ☐ Failed

Remarks:

[7] Tests shall are performed for a selection of the available programming modes and/or tariffs (including automatic changes).

C.2 Function control, and visual examination tests (2.6, A.6, A.5.1.2, and A.5.1.3).

Check the pulse and timer accuracy in accordance with the test program in Table 2. Examine the taximeter visually for any defects and record the test results.

			At start	At end	
Application No:	.....	Temp:			°C
Type designation:	.....	Rel. h.:			%
Observer:	.....	Date:			yyyy:mm:dd
		Time:			hh:mm:ss

C.2.1 Dry heat (non-condensing) and cold test, and visual examination (2.6.1, A.6.4.1)

Voltage at: [ ] V DC

Time measurement

Temperature conditions[8]	Time measuring signal (Hz)		Test pulses		Indication (I)		Time tariff (I/h)	Time signal Error		Test pulses Error		MPE %
	Actual	Ref.	Actual	Ref.	Start	End		Hz	%	p	%	
Reference 20^0C												
Specified high												
Specified low												
Reference 20^0C												

Pulse (distance) measurement

Temperature conditions	Number of test pulses		Indication (I)		Instrument constant k (pulses/km)	Distance tariff (I/km)	Test pulses Error		MPE %
	Actual	Ref.	Start	End			p	%	
Reference 20^0C									
Specified high									
Specified low									
Reference 20^0C									

Visual examination	Passed	Failed	Comments

[ ] Passed [ ] Failed

Remarks:

[8] The test is performed after sufficient temperature stabilization has occurred. The change of temperature shall not exceed 1 ^{0}C/min during heating and cooling down.

C.2.2 Damp heat, cyclic test (4.1.2, A.6.4.2)

			At start	After 3 h	After 12 h	At end	
Application No:	.....	Temp:					°C
Type designation:	.....	Rel. h.:					%
Observer:	.....	Date:					yyyy:mm:dd
		Time:					hh:mm:ss

Temperature/humidity sequence[9]	24 h period	Indication I	Significant fault		
			Yes	No	Yes (remarks)[10]
Temperature rise from reference at 95 % Rel. h.	0 to 3				
Specified high temperature at 93 % Rel. h.	3 to 12				
Temperature drop to reference at 95 % Rel. h.	18 to 24				

☐ Passed ☐ Failed

Remarks:

C.2.2.1 Function control, and visual examination after damp heat test, at reference conditions (2.6.1, A.6.4.1)

Time measurement

Voltage conditions [11]	Time measuring signal (Hz)		Test pulses		Indication (I)		Time tariff (I/h)	Time signal Error		Test pulses Error		MPE %
	Actual	Ref.	Actual	Ref.	Start	End		Hz	%	p	%	
12 V DC												
24 V DC												

Pulse (distance) measurement

Voltage conditions	Number of test pulses		Indication (I)		Instrument constant k (pulses/km)	Distance tariff (I/km)	Test pulses Error		MPE %
	Actual	Ref.	Start	End			p	%	
12 V DC									
24 V DC									

Visual examination	**Passed**	**Failed**	**Comments**

☐ Passed ☐ Failed

Remarks:

[9] All parts of the EUT are within 3 °C of their final temperature.
[10] Functional status of the instrument during and after exposure to disturbances..
[11] Tests are performed at the rated operating voltage for the specified voltage supply.

C.2.3 Variations in 12 V and 24 V voltage supply (2.6.2, A.6.4.3)

			At start	At end	
Application No:	.....	Temp:			°C
Type designation:	.....	Rel. h.:			%
Observer:	.....	Date:			yyyy:mm:dd
		Time:			hh:mm:ss

Time measurement

Voltage conditions [12] (DC)			Time measuring signal (Hz)		Number of test pulses		Indication (I)		Time tariff (l/h)	Time signal Error		Test pulses Error		MPE %
Supply limits	12 V	24 V	Actual	Ref.	Actual	Ref.	Start	End		Hz	%	pulses	%	
Lower	9 V	16 V												
upper	16 V	32 V												

Pulse (distance) measurement

Voltage Conditions (DC)			Number of test pulses		Indication (I)		Instrument constant k (pulses/km)	Distance tariff (l/km)	Test pulses Error		MPE %
Supply limits	12 V	24 V	Actual	Ref.	Start	End			pulses	%	
Lower	9 V	16 V									
upper	16 V	32 V									

	Passed	Failed	Comments
Visual examination			

☐ Passed ☐ Failed

Remarks:

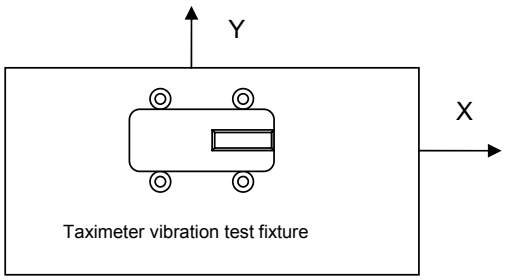
[12] Tests are performed at the upper and lower voltage limits for the specified voltage supply range.

:

C.2.4 Vibrations test (A.6.4.4)

Figure B EUT and configuration

Figure B.1 - Set up for Z axis vibration: Direction of motion is in and out of page.



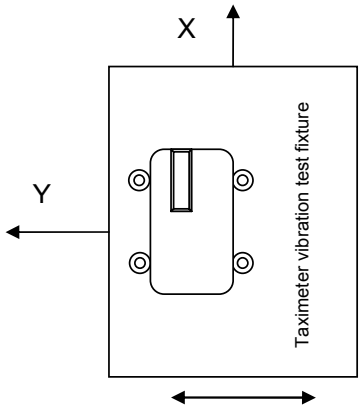


Figure 1.2 - Set up for Y axis vibration

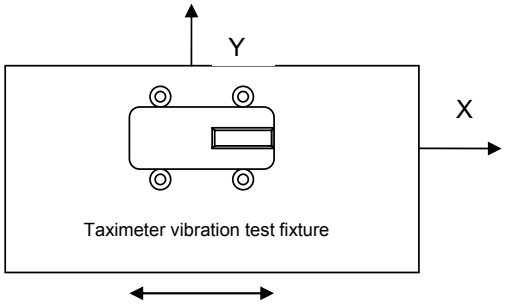


Figure 1.3 - Set up for X axis vibration

C.2.4.1 Vibration, random test, and visual examination (A.6.4.4.1)

			At start	At end	
Application No:	.....	Temp:			°C
Type designation:	.....	Rel. h.:			%
Observer:	.....	Date:			yyyy:mm:dd
		Time:			hh:mm:ss

Voltage at: ☐ V DC

Time measurement

Random vibrations in three mutually perpendicular axes[13]	Time measuring signal (Hz)		Number of test pulses		Indication (I)		Time tariff (I/h)	Time signal Error		Test pulses Error		MPE %
	Actual	Ref.	Actual	Ref.	Start	End		Hz	%	pulses	%	
First axis												
Second axis												
Third axis												

Pulse (distance) measurement

Random vibrations in three mutually perpendicular axes	Number of test pulses		Indication (I)		Instrument constant k (pulses/km)	Distance tariff (I/km)	Test pulses Error		MPE %
	Actual	Ref.	Start	End			pulses	%	
First axis									
Second axis									
Third axis									

Visual examination	**Passed**	**Failed**	**Comments**

☐ Passed ☐ Failed

Remarks:

[13] In accordance with the specifications in Table 8, apply random vibrations, over a frequency range of 10-150 Hz, to the EUT, at the specified ASD level, in three mutually perpendicular axes in turn, for 30 minutes per axis in each functional mode.

C.2.4.2 Vibration, sinusoidal test, and visual examination (A.6.4.4.2)

			At start	At end	
Application No:	.....	Temp:			°C
Type designation:	.....	Rel. h.:			%
Observer:	.....	Date:			yyyy:mm:dd
		Time:			hh:mm:ss

Voltage at: ☐ V DC

Time measurement

Sinusoidal vibration in three mutually perpendicular axes[14]	Time measuring signal (Hz)		Number of test pulses		Indication (I)		Time tariff (I/h)	Time signal Error		Test pulses Error		MPE %
	Actual	Ref.	Actual	Ref.	Start	End		Hz	%	pulses	%	
First axis												
Second axis												
Third axis												

Pulse (distance) measurement

Sinusoidal vibrations in three mutually perpendicular axes	Number of test pulses		Indication (I)		Instrument constant k (pulses/km)	Distance tariff (I/km)	Test pulses Error		MPE %
	Actual	Ref.	Start	End			pulses	%	
First axis									
Second axis									
Third axis									

Visual examination	Passed	Failed	Comments

☐ Passed ☐ Failed

Remarks:

[14] In accordance with the specifications in Table 9, apply sinusoidal vibrations, over a frequency range of 10 -150 Hz, at 1 octave/min, and at 10 ms^{-2} maximum acceleration level with 20 sweep cycles per axis, in three mutually perpendicular main axes of the rigidly mounted EUT

C.2.5 Electromagnetic fields

C.2.5.1 Radiated electromagnetic fields test (A.6.4.5.1)

			At start	At end	
Application No:	.....	Temp:			°C
Type designation:	.....	Rel. h.:			%
Observer:	.....	Date:			yyyy:mm:dd
		Time:			hh:mm:ss

Disturbances			MPE compliance		Remarks
Frequency range (MHz)	Polarization	Facing EUT	Yes	No	
without disturbance					
26 - 80	Vertical	Front			
		Right			
		Left			
		Rear			
	Horizontal	Front			
		Right			
		Left			
		Rear			
80 - 2000	Vertical	Front			
		Right			
		Left			
		Rear			
	Horizontal	Front			
		Right			
		Left			
		Rear			

Frequency range: 80 MHz to 2 GHz

Amplitude: 10 Volts/m

Modulation: 80 % AM, 1 kHz sine wave

Note: If EUT fails, the frequency and field strength at which this occurs must be recorded.

☐ Passed ☐ Failed

Remarks:

C.2.5.2 Conducted electromagnetic fields test (A.6.4.5.2)

			At start	At end	
Application No:	.....	Temp:			°C
Type designation:	.....	Rel. h.:			%
Observer:	.....	Date:			yyyy:mm:dd
		Time:			hh:mm:ss

Frequency Range (MHz)	Cable/Interface	Level (Volts RMS)	MPE compliance		Remarks[15]
			Yes	No	
without disturbance					
without disturbance					
without disturbance					
without disturbance					
without disturbance					
without disturbance					

Frequency range: 0.15 to 80 MHz

RF amplitude (EMF): 10 V RMS

Modulation: 80 % AM, 1 kHz sine wave

☐ Passed ☐ Failed

Remarks:

[15] Functional status of the instrument during and after exposure to disturbances. If EUT fails, the frequency and field strength at which this occurs must be recorded.

C.2.5 Electromagnetic fields (continued)

Include a description of the set-up of EUT, e.g. by photos or sketches.

Note: If EUT fails, the frequency and field strength at which this occurs must be recorded.

Radiated:

Conducted:

C.2.6 Electrostatic discharges (A.6.4.6)

			At start	At end	
Application No:	.....	Temp:			°C
Type designation:	.....	Rel. h.:			%
Observer:	.....	Date:			yyyy:mm:dd
		Time:			hh:mm:ss

Polarity[16]: ☐ pos ☐ neg

The EUT shall be in operation during the test.

Direct application

Type	Discharges			MPE compliance		Remarks[17]
	Test Voltage (kV)	Number of discharges ≥ 10	Repetition Interval (s)	Yes	No	
	without disturbance					
Contact	2					
Contact	4					
Contact	6					
Air	8					

Indirect application (Horizontal coupling plane)

Type	Discharges			MPE compliance		Remarks
	Test Voltage (kV)	Number of discharges ≥ 10	Repetition Interval (s)	Yes	No	
	without disturbance					
Contact	2					
Contact	4					
Contact	6					

Indirect application (Vertical coupling plane)

Type	Discharges			MPE compliance		Remarks
	Test Voltage (kV)	Number of discharges ≥ 10	Repetition Interval (s)	Yes	No	
	without disturbance					
Contact	2					
Contact	4					
Contact	6					

☐ Passed ☐ Failed

Remarks:

[16] IEC 61000-4-2 specifies that the test shall be conducted with the most sensitive polarity.

[17] Functional status of the instrument during and after exposure to disturbances. Significant faults or the test point at which EUT failure occurs shall be recorded.

C.2.6 **Electrostatic discharges (cont.)**

Specification of test points of EUT (direct application), e.g. by photos or sketches

a) Direct application

Contact discharges:

Air discharges:

b) Indirect application

C.2.6.1 Function control, and visual examination after electrostatic discharges test, at reference conditions

Time measurement

Voltage conditions[18]	Time measuring signal (Hz)		Test pulses		Indication (I)		Time tariff (I/h)	Time signal Error		Test pulses Error		MPE %
	Actual	Ref.	Actual	Ref.	Start	End		Hz	%	pulses	%	
12 V DC												
24 V DC												

Pulse (distance) measurement

Voltage conditions	Number of test pulses		Indication (I)		Instrument constant k (pulses/km)	Distance tariff (I/km)	Test pulses Error		MPE %
	Actual	Ref.	Start	End			pulses	%	
12 V DC									
24 V DC									

Visual examination	**Passed**	**Failed**	**Comments**

☐ Passed ☐ Failed

Remarks:

[18] Tests are performed at the rated operating voltage for the specified voltage supply.

C.2.7 Electrical transient conduction (A.6.4.7)

C.2.7.1 Electrical transient conduction along 12 V and 24 V supply lines (A.6.4.7.1)

			At start	At end	
Application No:	.....	Temp:			°C
Type designation:	.....	Rel. h.:			%
Observer:	.....	Date:			yyyy:mm:dd
		Time:			hh:mm:ss

Exposure of the EUT to disturbances on the DC supply line by direct coupling of pulses.

Voltage conditions [19] (DC)	Test pulse	Pulse voltage V	MPE compliance		Remarks[20]
			Yes	No	
12 V	1	-100			
	2a	+ 50			
	2b[21]	+10			
	3a	-150			
	3b	+100			
	4	-7			
24 V	1	-600			
	2a	+50			
	2b	+20			
	3a	-200			
	3b	+200			
	4	-16			

☐ Passed ☐ Failed

Remarks:

[19] Tests are performed at the rated operating voltage for the specified voltage supply.
[20] Functional status of the instrument during and after exposure to test pulses
[21] Test pulse 2b is only applicable if the instrument is connected to the battery via the main (ignition) switch of the car, i.e. if the manufacturer has not specified that the instrument is to be connected directly (or by its own main switch) to the battery.

C.2.7.2 Electrical transient conduction via lines other supply lines (A.6.4.7.2)

With the applicable voltage supply on, the various signal lines of the EUT are exposed to disturbances by capacitive/inductive coupling.

Voltage conditions (DC)	Test pulse	Pulse voltage U_s	MPE compliance		Remarks [22]
			Yes	No	
12 V	Cable/interface:				
	a	-60 V			
	b	+40 V			
	Cable/interface:				
	a	-60 V			
	b	+40 V			
	Cable/interface:				
	a	-60 V			
	b	+40 V			
	Cable/interface:				
	a	-60 V			
	b	+40 V			
	Cable/interface:				
	a	-60 V			
	b	+40 V			
24 V	Cable/interface:				
	a	-80 V			
	b	+80 V			
	Cable/interface:				
	a	-80 V			
	b	+80 V			
	Cable/interface:				
	a	-80 V			
	b	+80 V			
	Cable/interface:				
	a	-80 V			
	b	+80 V			
	Cable/interface:				
	a	-80 V			
	b	+80 V			

☐ Passed ☐ Failed

Remarks:

[22] Functional status of the instrument during and after exposure to test pulses

C.2.7.3 Function control, and visual examination, at reference conditions, after test for conduction via lines other than supply lines

Time measurement

Voltage conditions[23]	Time measuring signal (Hz)		Test pulses		Indication (I)		Time tariff (I/h)	Time signal Error		Test pulses Error		MPE %
	Actual	Ref.	Actual	Ref.	Start	End		Hz	%	pulses	%	
12 V DC												
24 V DC												

Pulse (distance) measurement

Voltage conditions	Number of test pulses		Indication (I)		Instrument constant k (pulses/km)	Distance tariff (I/km)	Test pulses Error		MPE %
	Actual	Ref.	Start	End			pulses	%	
12 V DC									
24 V DC									

Visual examination	**Passed**	**Failed**	**Comments**

☐ Passed ☐ Failed

Remarks:

[23] Tests are performed at the rated operating voltage for the specified voltage supply.

C.2.8 Voltage variations – slow dips below 9 V DC (4.2.5, A.6.4)

			At start	At end	
Application No:	.....	Temp:			°C
Type designation:	.....	Rel. h.:			%
Observer:	.....	Date:			yyyy:mm:dd
		Time:			hh:mm:ss

% of lower value of voltage dip (V_t)	Width of dip (seconds)	Passed	Failed	Remarks
80	7			
	14			
	15			
	17.5			
	20			
	21			
	30			
40	7			
	14			
	15			
	17.5			
	20			
	21			
	30			
0	7			
	14			
	15			
	17.5			
	20			
	21			
	30			

Polarity change: ± 12 V DC	Duration of polarity change (seconds)	Passed	Failed	Remarks

Mis en forme : Gauche

☐ Passed ☐ Failed

Remarks:

C.2.8.1 Function control, and visual examination after slow dips test, at reference conditions

Time measurement

Voltage conditions[24]	Time measuring signal (Hz)		Test pulses		Indication (I)		Time tariff (I/h)	Time signal Error		Test pulses Error		MPE %
	Actual	Ref.	Actual	Ref.	Start	End		Hz	%	pulses	%	
12 V DC												
24 V DC												

Pulse (distance) measurement

Voltage conditions	Number of test pulses		Indication (I)		Instrument constant k (pulses/km)	Distance tariff (I/km)	Test pulses Error		MPE %
	Actual	Ref.	Start	End			pulses	%	
12 V DC									
24 V DC									

	Passed	Failed	Comments
Visual examination			

☐ Passed ☐ Failed

Remarks:

[24] Tests are performed at the rated operating voltage for the specified voltage supply.

C.3 Function test at end of test program (A.5.1.1)

			At start	At end	
Application No:	.....	Temp:			°C
Type designation:	.....	Rel. h.:			%
Observer:	.....	Date:			yyyy:mm:dd
		Time:			hh:mm:ss

C.3.1 Test at reference conditions (A.5.2)

C.3.1.1 Voltage supply

Time measurement

Voltage supply[25]	Time measuring signal (Hz)		Number of test pulses		Indication (I)		Time tariff (I/h)	Time signal error		Test pulses Error		MPE %
	Actual	Ref.	Actual	Ref.	Start	End		Hz	%	pulses	%	
12 V DC												
24 V DC												

Pulse (distance) measurement

Voltage supply	Number of test pulses		Indication (I)		Instrument constant k (pulses/km)	Distance tariff (I/km)	Test pulses Error		MPE %
	Actual	Ref.	Start	End			pulses	%	
12 V DC									
24 V DC									

☐ Passed ☐ Failed

Remarks:

C.3.1.2 Pulse frequency levels (A.5.1.1)

Voltage at: ☐ V DC

Time measurement

Pulse frequency[26] (Hz)		Time measuring signal (Hz)		Number of test pulses		Indication (I)		Time tariff (I/h)	Time signal Error		Test pulses Error		MPE %
		Actual	Ref.	Actual	Ref.	Start	End		Hz	%	pulses	%	
Lowest													
Medium													
Highest													

Pulse (distance) measurement

Pulse frequency (Hz)		Number of test pulses		Indication (I)		Instrument constant k (pulses/km)	Distance tariff (I/km)	Test pulses Error		MPE %
		Actual	Ref.	Start	End			pulses	%	
Lowest										
Medium										
Highest										

☐ Passed ☐ Failed

Remarks:

[25] Tests are performed at the rated operating voltage for the specified voltage supply.
[26] At least 10 fare increment steps for subsequent distance at a simulated speed of 200 km/h.

C.3.1.3 Pulse voltage levels (A.5.1.1)

Voltage at: ☐ V DC

Time measurement

Pulse voltage (V)		Time measuring signal (Hz)		Number of test pulses		Indication (I)		Time tariff (I/h)	Time signal Error		Test pulses Error		MPE %
		Actual	Ref.	Actual	Ref.	Start	End		Hz	%	pulses	%	
Lowest													
Medium													
Highest													

Pulse (distance) measurement

Pulse voltage (V)		Number of test pulses		Indication (I)		Instrument constant k (pulses/km)	Distance tariff (I/km)	Test pulses Error		MPE %
		Actual	Ref.	Start	End			pulses	%	
Lowest										
Medium										
Highest										

☐ Passed ☐ Failed

Remarks:

C.3.1.4 Specified k values[27] (6.2.2, A.5.2)

Voltage at: ☐ V DC

Time measurement

Instrument constant k (pulses/km)		Time measuring signal (Hz)		Number of test pulses		Indication (I)		Time tariff (I/h)	Time signal Error		Test pulses Error		MPE %
		Actual	Ref.	Actual	Ref.	Start	End		Hz	%	pulses	%	
Lowest													
Medium													
Highest													

Pulse (distance) measurement

Instrument constant k (pulses/km)		Number of test pulses		Indication (I)		Instrument constant k (pulses/km)	Distance tariff (I/km)	Test pulses Error		MPE %
		Actual	Ref.	Start	End			pulses	%	
Lowest										
Medium										
Highest										

☐ Passed ☐ Failed

Remarks:

[27] k values (minimum as specified in 2.8. Maximum specified by the manufacturer)

C.3.1.5 Featured calculation method (A.5.1.1)

Voltage at: ☐ V DC

Time measurement

Calculation method set to:	Time measuring signal (Hz)		Number of test pulses		Indication (I)		Time tariff (I/h)	Time signal Error		Test pulses Error		MPE %
	Actual	Ref.	Actual	Ref.	Start	End		Hz	%	pulses	%	
Method S												
Method D												

Pulse (distance) measurement

Pulse voltage (V)	Number of test pulses		Indication (I)		Instrument constant k (pulses/km)	Distance tariff (I/km)	Test pulses Error		MPE %
	Actual	Ref.	Start	End			pulses	%	
Method S									
Method D									

☐ Passed ☐ Failed

Remarks:

C.3.1.6 Programmed tariffs[28] (6.2.2, A.5.2)

Voltage at: ☐ V DC

Time measurement

Programmed tariffs	Time measuring signal (Hz)		Number of test pulses		Indication (I)		Time tariff (I/h)	Time signal Error		Test pulses Error		MPE %
	Actual	Ref.	Actual	Ref.	Start	End		Hz	%	p	%	

Pulse (distance) measurement

Programmed tariffs	Number of test pulses		Indication (I)		Instrument constant k (pulses/km)	Distance tariff (I/km)	Test pulses Error		MPE %
	Actual	Ref.	Start	End			pulses	%	

☐ Passed ☐ Failed

Remarks:

[28] Tests shall are performed for a selection of the available programming modes and/or tariffs (including automatic changes).

C.4 EXAMINATION OF THE CONSTRUCTION OF THE INSTRUMENT

Use this page to indicate any description or information pertaining to the instrument, additional to that already contained in this report and in the accompanying national type approval or OIML certificate. This may include a picture of the complete instrument, a description of its main devices, and any remark which could be useful for authorities responsible for the initial or subsequent verifications of individual instruments built according to the type. It may also include references to the manufacturer description.

Description:

Remarks:

CHECKLIST

The checklist has been developed based on the following principles:

To include requirements that cannot be tested according to test C.1 through C.4 above, but shall be checked experimentally or visually, e.g. the descriptive markings (3.12);

Not to include general requirements, e.g. suitability for use (3.1);

This checklist is intended to serve as a summary of the results of examinations to be performed and not as a procedure. The items on this checklist are provided to recall the requirements specified in R 21 and they shall not be considered as a substitution for these requirements.

The requirements that are not included in this type evaluation report (test C.1 through C.4 and the checklist) are considered to be globally covered by the type approval or OIML certificate], (e.g. suitability for use [3.1]).

For non-mandatory devices, the checklist provides space to indicate whether or not the device exists and, if appropriate, its type. A cross in the box for “present” indicates that the device exists and that it complies with the definition given in the terminology; when indicating that a device is non-existent, also check the boxes to indicate that the tests are not applicable (see p. 2).

If appropriate, the results stated in this checklist may be supplemented by remarks given on additional pages.

CHECKLIST (continued)

Application No: ..... Type designation: .....

R 21 Clause	Test Clause	Taximeters		Passed	Failed	Remarks
2.1	A.1.3	**Main function of the taximeter:**				
		Designed to measure the duration, and to calculate the distance of a journey based on a signal delivered by a distance measurement transducer				
		Calculates and displays the fare to be paid, based on the calculated distance and/or measured duration of the journey				
2.4	A.1.3	**Taximeter accuracy conformance over time:**				
		Designed to provide a level of confidence 'near to certainty' that the automatic operation of the instrument complies with the requirements of this Recommendation for at least one year.				
		Manufacturer provides documented description of how this condition is met.				
2.5	A.1.3	**Units of measurement to be used on a taximeter are:**				
		Time, in seconds, minutes and hours;				
		Distance, in metres (m) or kilometres (km), or as specified in national regulation;		Remarks		
		Fare, in accordance with national regulation.				
2.6.1		**Temperature limits:**				
		Specified by manufacturer				
		Specified according to:	the lower temperature shall be -40 °C, -25 °C, or -10 °C			
			the higher temperature shall be + 40 °C, +55 °C, or +70 °C			
2.6		**DC power supply:**	12 V battery			
			24 V battery			
2.7	A.1.5	**Constant k of the taximeter:**				
		Taximeter constant k shall not be lower than minimum value specified by the manufacturer.				
		It shall be possible to display k on the taximeter as a readily accessible decimal number.				
		Every change of k shall be secured in accordance with 3.2.5.				
		The use of the taximeter shall not be possible when the change registration capacity is exceeded. That capacity will be defined by the manufacturer.				
2.8	A.1.3	**Real-time clock**		Present [ ]		Not-Present [ ]
		The taximeter is equipped with a real time-clock by means of which the time of the day and the date are kept and used are used for the automatic change of tariffs				
		Accuracy of time interval shall be ± 0.02 %.				

R 21 Clause	Test Clause	Taximeters	Passed	Failed	Remarks
2.8	A.1.3	Clock accuracy shall be within ± 2 minutes per month			
		Correction for summer and winter time is performed automatically in applicable countries.			
		Other corrections, automatic or manual, shall be prevented during a journey, unless specified in national regulation and comply with the securing requirements in 3.2.5.			
		In the event of interruption of the power, real time clock shall continue to function correctly, and retain the correct time and date for at least one year, or a period in accordance with national regulation.			
		Additional functions of a vehicle unit			
2.9		In addition to the main functions of a taximeter described in 2.1, taximeter connected to a vehicle installed distance measurement transducer shall ensure the following functions:			
		– detection of events and/or faults			
		– reading, recording and storing in data storage;			
		– printing;			
		– data transmit and downloading to and from external devices;			
		– in-service functions,			
		– time correction functions;			
		– securing function;			
		– built-in self tests, fault detection and notification;			
		– other functions as described in 3.14.3.			
3.2	A.1.4	**Security of operation:**			
3.2.1		**Fraudulent use:** No characteristics likely to facilitate fraudulent use			
3.2.2		**Accidental maladjustment:** Effect of accidental breakdown or maladjustment is evident			
3.2.3		**Controls:** Controls come to rest in intended positions and unambiguously marked keys			
3.2.4		**Calculator:**			
		Easy inspection and adjustments of the calculator functions is possible			
		Any malfunction shall be clearly indicated (e.g. by a significant fault indication or by automatic switch off).			
3.2.5	A.2.4	**Securing of functions, devices, software and pre-set controls**	Present [ ]		Present [ ]
		Securing in accordance with national regulation	Remarks		
		Securing by other means, e.g. passwords, software, etc.			
		Access/adjustment prohibited and automatically self-evident			
		Access allowed to authorized people, e.g. by changeable code (key-word) or of a special device (hard key, etc);			

R 21 Clause	Test Clause	Taximeters	Passed	Failed	Remarks
3.2.5	A.2.4	Protection of device-specific and software functions against intentional, unintentional and accidental changes provided in accordance with 3.11;			
		Protection and detection of physical tampering with taximeter hardware provided (e.g. seals);			
		Transmission of data protected against intentional, unintentional and accidental changes in accordance with 4.2.3			
		Securing possibilities available in taximeter allows for separate securing of the settings			
3.3	A.1.4	**Fare calculation:**			
		The interval of fare to pay, and the monetary symbols shall comply with national regulations.	Remarks		
		Fare calculation is performed by:			
		Normal calculation method S (single application of tariff)			
		Normal calculation method D (double application of tariff)			
		If both normal calculation methods S and D are possible in an instrument, the option of switching between them shall be under the securing conditions specified in 3.2.5.			
		indications for fare calculation comply with 3.9.1			
3.4	A.1.4	**Tariff programming**			
3.4.1		**Each allocated tariff may include following data:**			
		– initial hire fee as an amount of money;			
		– initial time;			
		– initial distance;			
		– time-tariff value as an amount of money per hour;			
		– Distance-tariff value as an amount of money per kilometre, or in accordance with national regulations;			
		– Supplementary charge increment, if appropriate;			
		– Signature of the corresponding tariff data.			
3.4.2		**Input of tariff data**			
		The tariff data may be entered individually via an appropriately protected interface (4.2.3).			
		Unauthorized or unintentional tariff re-programming due to interfacing with other equipment shall conform to the securing requirements in 3.2.5.			
		If the taximeter is capable of having its tariffs re-programmed in advance of the effective date, those tariffs shall not become effective until that date.			
3.5	A.1.4	**Operating position indication**			
		The indication in the operating positions shall be as follows:			

R 21 Clause	Test Clause	Taximeters	Passed	Failed	Remarks
3.5.1		**In 'For hire' (free) position**			
		Time-counting and distance-counting shall be inactive.			
		In 'For hire' (free) position it shall be possible to display, when relevant, the following parameters:			
		– all elements of the indicator display;			
		– the contents of totalizers (see 3.4);			
		– the constant k expressed in pulses per kilometre;			
		– the contents of the event counters;			
		– the tariff data of each allocated tariff (see 3.4.1).			
		The above parameters shall not be displayed for more than 10 seconds when the vehicle is moving.			
		Other indications in 'For hire' (free) position are permitted in accordance with national regulation, and shall not be interpreted as fare or supplement indication and their use is subject to the security of operation requirements in 3.2.			
3.5.2		**In 'Hired' (occupied) position**			
		Time-counting and distance-counting shall be activated.			
		The indications in 'Hired' position at the beginning of the journey shall be in the following order:			
		a) the initial charge,			
		b) the first fare indication, followed by subsequent fare indication changes corresponding to the initial and then successive equal time intervals or distances specified in the applied tariff;			
		Indications in 'Hired' position may also include the distance and time displays provided they comply with the quality of indication requirements in 3.9.1.			
		In addition, all indications in 'Hired' position shall be in accordance with national regulation.			
3.5.3		**In 'Stopped' (to pay) position**			
		Time-counting shall be inactivated and distance-counting shall be active at the appropriate tariff			
		The indications in 'Stopped' position at the end of the journey shall be:			
		a) the fare to be paid for the journey, or			
		a) If there is a supplementary charge for an extra service, entered by manual command, this shall be displayed separately from the indicated fare. However, in this case a taximeter may indicate temporarily the value of the fare including the supplementary charge.			
3.5.3		In the case b) the indication of the supplement shall be made by figures with a height not more than that of the figures indicating the fare.			
		Indications in the 'Stopped' position shall comply with 3.9.1.			
3.5.4		In the 'Measure' position for the normal calculation method D (double application of tariff) system distance and duration of the journey are measured and displayed in real time on a separate indicator as follows:			
		a) time measured in hours with smallest increment of 30 s;			
		b) distance measured resolution better than or equal to 0.1 km;			
		c) readings for both time and duration may be given at the same time, or may be recalled one after the other by means of the operating position indicator;			
		d) the indicated unit of measurement shall comply with 3.9.1 so that there can be no confusion as to the quantity indicated.			

Tableau mis en forme

Tableau mis en forme

Mise en forme : Puces et numéros

R 21 Clause	Test Clause	Taximeters	Passed	Failed	Remarks
3.6	A.1.4	**Additional requirements for operating position indicator:**			
		– In 'Stopped' position and before the start of any new journey, the indication of the fare at the end of a previous journey shall be displayed for a sufficient period (at least 10 seconds, or a time in accordance with national regulations);			
		– The design of the operating position indication shall ensure that any change in operating positions shall be secured in accordance with 3.2.5;			
		– It shall not be possible to place the operating position indication in any positions other than those mentioned above, unless otherwise specified in national regulation.			
3.7	A.1.4	**Taximeter fitted with totalizes for:**			
		a) Total distance travelled by the taxi;	Present [ ]		Not-Present [ ]
		b) Total distance travelled when hired;	Present [ ]		Not-Present [ ]
		c) Total number of journeys;	Present [ ]		Not-Present [ ]
		d) Total amount of money charged as supplements;	Present [ ]		Not-Present [ ]
		e) Total amount of money charged as fare.	Present [ ]		Not-Present [ ]
		Other data may be totalled provided they are in accordance with national regulation and are not misleading..	Remarks		
		Values saved under conditions of loss of voltage supply (4.2.5) shall be included in the total.			
		Adequate measures taken to prevent the display of totalized values being used to deceive passengers.			
		Indications of the totalized values comply with 3.9.1.			
		Totalized values shall be displayed for a maximum of 10 seconds, or in accordance with national regulation			
3.8		**The tariff data may be triggered by the:**			
		Distance of the journey;			
		Duration of the journey;			
		Time of day;			
		Date;			
		Day of the week; or			
		Each change of tariff shall be secured in accordance with 3.2.5.			
3.9	A.1.4	**Indicating and printing**			
3.9.1		**Quality of reading:**			
		Primary indications shall be by means of a display or hard copy	Remarks		
		Reliable, easy and unambiguous reading of primary indications under conditions of normal use including in daylight and night			
		The figures forming the primary indications shall be of a size of at least 10 mm in height, shape and clarity for easy reading			
		Primary indications contain names or symbols of the units of measurement and comply with the requirements of 2.5.			
		Indications of interest to the passenger are suitably identified and readable from a distance of 2 meters			
3.9.1	A.1.4	A digital indication shall display at least one figure beginning at the extreme right.			
		A decimal fraction shall be separated from its integer by a decimal sign (comma or dot), with the indication showing at least one figure to the left of the sign and all figures to the right			

Tableau mis en forme

R 21 Clause	Test Clause	Taximeters	Passed	Failed	Remarks
3.9.1	A.1.4	Zero may be indicated by one zero to the extreme right, without a decimal sign.			
3.9.2		**Printing**	Present [ ]		Not-Present [ ]
		Printing shall be clear and permanent for the intended use. Printed figures shall be clear, legible and unambiguous.			
		If printing takes place, the name or the symbol of the unit of measurement shall be either to the right of the value or above a column of values, or placed in accordance with national regulation.			
		Multiple copies of the print-out containing the same data must be marked “copy” or “duplicate”.			
		The minimum printout from each measurement operation shall be dependent upon the application of the taximeter and in accordance with national regulation.	Remarks		
		In general the printout information may include the programmed tariff, fare, supplementary charge, distance and duration of the journey, date and the time of the journey			
3.10	A.1.4	**Data storage for measurement data, legally relevant software and parameters:**			
		Taximeter hard drive memory	Present [ ]		Not-Present [ ]
		Universal computer storage	Present [ ]		Not-Present [ ]
		External (removable) storage	Present [ ]		Not-Present [ ]
		In all cases, the data shall be adequately protected against intentional and unintentional changes during the transfer process and stored data shall contain all relevant information necessary to reconstruct an earlier measurement.			
		Additional data storage requirements:			
		a) Software transmission and downloading shall be secured in accordance with the requirements in 3.11;			
		b) External storage devices identification and security attributes shall be verified to ensure integrity and authenticity;			
		c) Exchangeable storage media is sealed against removing in accordance with 3.2.5;			
		d) Device specific parameters are not stored on the standard storages of the universal computer but in separate hardware that can be sealed in accordance with 3.2.5;			
3.11	A.1.4	**Software:**	Present [ ]		Not-Present [ ]
		Legally relevant software of a taximeter shall be identified by the manufacturer	Remarks		
		Securing of legally relevant in accordance with national regulation	Remarks		
3.11.1		**Software documentation supplied by manufacturer**			
		a) A description of the legally relevant software;	Present [ ]		Not-Present [ ]
		b) A description of the accuracy of the measuring algorithms (e.g. programming modes);	Present [ ]		Not-Present [ ]
		c) A description of the user interface, menus and dialogues;	Present [ ]		Not-Present [ ]
		d) The unambiguous software identification;	Present [ ]		Not-Present [ ]
		e) An overview of the system hardware, e.g. topology block diagram, type of computer(s), source code for taximeter functions, etc, if not described in the operating manual;	Present [ ]		Not-Present [ ]
		f) Means of securing software	Present [ ]		Not-Present [ ]
		g) The operating manual.	Present [ ]		Not-Present [ ]

R 21 Clause	Test Clause	Taximeters	Passed	Failed	Remarks
3.11.2		**Means of securing legally relevant software:**			
		a) Adequately protected against accidental or intentional changes by means of an audit trail from a software event counter (T.2.5) and/or automatic checking facility (T.3.6.1).			
		b) Evidence of an intervention such as changing, uploading or circumventing the software shall be non-erasable, automatically recorded and stored for at least one year, or for a period set in accordance with national regulation;			
		c) Assigned with a software identification (T.2.10.4) which shall be adapted in the case of every software change that may affect the functions and accuracy of the taximeter. Software identification shall be easily provided by the taximeter;			
		d) Downloading of legally relevant software shall be with appended software identification, target equipment identification and security attributes to ensure integrity and authenticity. In this case, the software identification is considered as device-specific parameters (T.2.10.3, 3.2.5).			
		e) Downloading of legally relevant software and data shall be through appropriate protective interfaces connected to the taximeter;			
		f) Functions that are performed or initiated via a software interface shall meet the relevant requirements and conditions of 4.2.3.			
3.12	A.2.2	**Descriptive markings:**			
		– name or identification mark of manufacturer			
		– name or identification mark of the importer (if applicable);			
		– serial number and type designation of the instrument			
		– accuracy class/type approval sign			
		– power supply			
		– relevant data in respect of the conditions of use;			
		– number of the type examination certificate;			
		– date of manufacture;			
		– specified range of the constant ‘k’			
		– temperature range (°C)			
		Other markings may be specified in accordance with national regulation provided they are applied in accordance with the requirements in 3.2.	Remarks		
3.12.1		**Supplementary markings:**			
		Are required	Remarks		
3.12.2		**Presentation of descriptive markings:**			
		– Indelible			
		– Size, shape and clarity that allows easy reading			
		– Grouped together in a clearly visible place			
		– Descriptive plate bearing markings to be sealed, unless it cannot be removed without being destroyed			
		– Plate to contain: – Type, and designation of instrument, manufacturer, type approval sign, electrical supply voltage, electrical supply frequency, pneumatic/hydraulic pressure			
		– Shown in an official language in accordance with national regulation.			
		Alternatively, descriptive markings simultaneously displayed by a software solution either permanently or on manual commend. In this case markings are considered as device-specific parameters secured in accordance with 3.2.5	Remarks		

R 21 Clause	Test Clause	Taximeters	Passed	Failed	Remarks
3|13	A.2.3	**Verification marks**			
3|13.1		**Position:**			
		Part where verification marks are located cannot be removed from the instrument without damaging the marks	Remarks		
		Allows easy application of marks without changing the metrological qualities of the instrument			
		Visible when the instrument is in service			
3|13.2		**Mounting:**			
		Verification mark support to ensure conservation of the marks			
		Support is of the correct construction			
3|14	A.1.4	**Installation and test conditions:**			
		Taximeter shall be provided with:			
		a) Means (e.g. a test connector meeting the requirements in 4.2.4) to facilitate correct testing and operation with connected equipment and vehicle;			
		b) Details of installation having an effect on the accuracy of the taximeter shall be recorded in the verification report.			
3|14.2		**Taximeter compatibility with distance measurement transducer:**			
		– Taximeter shall be installed in accordance with the manufacturer's installation instructions providing that it comply with the requirements of this OIML Recommendation, especially the requirements in Clauses 3 for security of operation and securing against intentional changes.			
		– Taximeters shall be installed non-activated, with all metrological and technical parameters set to appropriate and valid default values.			
		– Before its activation, taximeters shall neither store nor transmit measurement data.			
		– Taximeters shall be connected to a vehicle installed distance measurement transducer to ensure the correct functioning of the vehicle unit to meet the requirements of this OIML Recommendation.			
		– During installation, all known parameters shall be pre-set;			
		– Markings on installation verification shall be in accordance with 3.13.			
3|14.3		**Taximeter operation modes**			
		A taximeter connected to the above distance measurement transducer shall possess at least the following modes of operation:			
		– operational mode (T.3.7)			
		– in-service inspection mode (T.3.8)			
		All functions listed in 2.9 shall work in any mode of operation after activation with the following exceptions:			
		– the inspection function is accessible in the in-service mode only;			
		– time correction is possible only in the in-service mode;			
		– driver manual entries functions during the journey (entry of places where the daily work periods begin and/or end for a driver) are accessible in the operational mode;			
		– downloading of legally relevant software is not accessible in the operational mode.			

R 21 Clause	Test Clause	Taximeters	Passed	Failed	Remarks
3.14.3		The in-service mode shall allow the taximeter to:			
		– automatically pair the distance measurement transducer with the vehicle unit;			
		– digitally adapt the taximeter constant (k) to the vehicle constant (w);			
		– adjust (without limitation) the current time;			
		– adjust the current odometer value;			
		– record and update vehicle unit details (vehicle unit identification, distance measurement transducer identification);			
		– record and store details of the metrological authority, vehicle identification and parameters updated or confirmed: w, k, tyre size, odometer (old and new values), date and time (old and new values), time adjustment data including (date and time, old value, date and time, new value), most recent in-service inspection.			
4.2	A.1.5	**Functional requirements**			
4.2.1	A.5.4	**Indicator display test:**			
		Relevant signs of indicator are active and non-active for sufficient time to be checked by operator			
4.2.2	A.1.5	**Acting upon a significant fault**			
		Either the instrument is made inoperative automatically, or			
		A visual or audible indication is provided automatically and continues until the user takes action or the fault disappears			
4.2.3	A.6.2.1	**Interfaces:**			
		Communication interfaces			
		User interfaces			
		A taximeter shall be able to supply the following data through appropriate protective interfaces:			
		– operation position: ‘For Hire ’,‘Hired ’or ‘Stopped’;			
		– totalizer data according to 3.7;			
		– general information: constant of the distance measurement transducer, date of securing, vehicle identification, real time, tariff identification;			
		– fare information for a journey: total charged, fare, calculation of the fare, supplement charge, date, start time, finish time, distance travelled;			
		– tariff(s) information: parameters of tariff(s).			
4.2.3.1		**Interface documentation supplied by manufacturer**			
		A list of all commands (e.g. menu items);			
		Description of the software interface;			
		A list of all commands together;			
		A brief description of their meaning and their effect on the functions and data of the measuring instrument.			

R 21 Clause	Test Clause	Taximeters	Passed	Failed	Remarks
4 2.3.2		**Securing of interface**			
		a) Allows instrument continues to function correctly,			
		b) Prevents the influencing of the metrological functions by devices or other connected instrument or disturbances acting on the interface,			
		c) Data is protected (e.g. a protective interface) against accidental or deliberate interference during the transfer;			
		d) All functions in the software interface shall be subject to the requirements for securing software in 3.11;			
		e) All functions in the hardware interface shall be subject to the requirements for securing hardware in 3.2.5;			
		f) Metrologically relevant parts of the target instrument shall be included in the initial verification;			
		g) it shall be easily possible to verify the authenticity and integrity of data transmitted to and/or from the taximeter and the target instrument;			
		h) Functions performed or initiated by other connected instruments through the interfaces shall meet the appropriate requirements of R 21.			
		Other instruments required by national regulation to be connected to the interfaces of a taximeter shall be secured to inhibit automatically the operation of the taximeter for reasons of the non-presence or improper functioning of the required device.			
4 2.4		**Test connector interface**			
		A test connector capable of communicating the correct information in accordance with Table 2 is provided.			
4 2.5	A.1.4	**Voltage drop below the minimum operating voltage:**			
		Taximeter continue to function correctly or resume its correct functioning without loss of data prior to the voltage drop if the voltage if the period of voltage drop is temporary (e.g. less than 20 seconds);			
		Abort an existing measurement and switch to the 'For hire' position if the period of voltage drop is for a longer period (e.g. less than 20 seconds);			
		In the case of b) taximeter resumes its correct functioning and retain the correct stored data concerning the journey;			
		Show a significant fault or is automatically put out of service if the voltage drop is for a lengthy period (e.g. longer than 60 seconds).			
		If disconnected from the voltage supply, the taximeter shall maintain the totalized value information for at least one year or for a period set in accordance with national regulation.			
4 2.6		**Repeatability**			
		The difference between the successive measurement results shall be less than the appropriate MPE in 2.3			
5 2.1	A.1.1	**Documentation includes:**			
		Metrological characteristics of the instrument;			
		A standard set of specifications for the instrument;			
		A functional description of the instruments and devices;			
		Drawings, diagrams and general software information (if applicable), explaining the construction and operation.			
		Any document or other evidence that the design and construction of the instrument complies with the requirements of this Recommendation			

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R 21 Clause	Test Clause	Taximeters	Passed	Failed	Remarks
5.2.3	A.1.2	**Examination of:**			
		Documents			
		Functional checks			
		Test reports from other authorities			
5.3.1	A.2	**Initial verification:**			
		Taximeter examined to establish conformity to the approved type.			
		During verification, the taximeter includes all devices which form the assembly as intended for normal use.			
5.3.2		**Initial verification tests conducted:**			
		In accordance with the requirements in Clause 2 and Clause 3 using test procedures in A.2.			
		in two stages:			
		a) In a laboratory a environment or any other suitable place agreed between the metrological authority concerned to examine the metrological characteristics of the taximeter without the influence of the vehicle; and			(Indicate in remarks if and where the results of observed tests for type are used).
		b) Vehicle installed unit to determine the influences of the vehicle on the metrological requirements of the taximeter.			

Use this space to detail remarks from the checklist

BIBLIOGRAPHY

Below are references to Publications of the International Electro-technical Commission (IEC), where mention is made in some of the tests in Annex A. Use these or refer to the most recent issue of the publication valid at the time of testing the instrument.

Ref.	Standards and reference documents	Description
[1]	International Vocabulary of Basic and General Terms in Metrology (VIM), (1993)	Vocabulary, prepared by a joint working group consisting of experts appointed by BIPM, IEC, IFCC, ISO, IUPAC, IUPAP and OIML
[2]	International Vocabulary of Terms in Legal Metrology, BIML, Paris, (2000)	Vocabulary including only the concepts used in the field of legal metrology. These concepts concern the activities of the legal metrology service, the relevant documents as well as other problems linked with this activity. Also included in this Vocabulary are certain concepts of a general character which have been drawn from the VIM.
[3]	OIML B 3, (2003) OIML Certificate System for Measuring Instruments (formerly OIML P1)	Provides rules for issuing, registering and using OIML Certificates of conformity
[4]	OIML D11, (2004) General requirements for electronic measuring instruments	Provides guidance for establishing appropriate metrological performance testing requirements for influence quantities that may affect the measuring instruments covered by International Recommendations
[5]	IEC 60068-2-1, (1990-05) with amendments 1, (1993-02) and 2, (1994-06)	Basic environmental testing procedures - Part 2: Tests, Test Ad: Cold, for heat dissipating equipment under test (EUT), with gradual change of temperature.
[6]	OIML D 19, (1988)	Provides advice, procedures and influencing factors on pattern evaluation and pattern approval
[7]	OIML D 20, (1988) Initial and subsequent verification of measuring instruments and processes	Provides advice, procedures and influencing factors on the choice between alternative approaches to verification and the procedures to be followed in the course of verification
[8]	IEC 60068-2-2, (1974-01) with amendments 1, (1993-02) and 2, (1994-05)	Basic environmental testing procedures, Part 2: Tests, Test Bd: Dry heat, for heat dissipating equipment under test (EUT) with gradual change of temperature.
[9]	IEC 60068-3-1, (1974)	Background information, section 1: Cold and dry heat tests.
[10]	IEC 60068-3-4, (2001-08)	Environmental testing – Part 3-4: Guidance for damp heat tests.

Ref.	Standards and reference documents	Description
[11]	IEC 60068-2-30, (1980-01) with amendment 1, (1985-01)	Environmental testing - Part 2: Tests. Test Db and guidance: Damp heat, cyclic (12 + 12-hour cycle).
[12]	ISO 16750-2, (2003)	Road vehicles – Environmental conditions and testing for electrical and electronic equipment. Part 2: Electrical loads.
[13]	IEC 60068-3-8, (2003-08)	Environmental testing: Supporting documentation and guidance – Selecting amongst vibration tests.
[14]	IEC 60068-2-64 Ed. 1.0, (1993-05)	Environmental testing - Part 2: Test methods - Test Fh: Vibration, broad-band random (digital control) and guidance.
[15]	IEC 60068-2-47 Ed. 2.0, (1999-10)	Environmental testing - Part 2-47: Test methods - Mounting of components, equipment and other articles for vibration, impact and similar dynamic tests.
[16]	IEC 60068-2-6 (1995-03), with Corr. 1, (1995-03)	Environmental testing – Part 2: Tests-Test Fc: Vibration (sinusoidal).
[17]	IEC 61000-4-3 consolidated Edition 2.1, (2002-09) with amendment 1, (2001-08)	Electromagnetic Compatibility (EMC) - Part 4: Testing and measurement techniques - Section 3: Radiated, radio-frequency, electromagnetic field immunity test.
[18]	IEC 61000-4-6 (2003-05) with amendment 1, (2004-10)	Electromagnetic Compatibility (EMC) - Part 4: Testing and measurement techniques - Section 6: Immunity to conducted disturbances, induced by radio-frequency fields.
[19]	IEC 61000-4-2, (1995-01) with amendment 1, (1998-01) and amendment 2, (2000-11) Consolidated Edition: IEC 61000-4-2, (2001-04) Ed. 1.2.	Basic EMC Publication. Electromagnetic Compatibility (EMC) - Part 4: Testing and measurement techniques - Section 2: Electrostatic discharge immunity test. Basic EMC Publication.
[20]	ISO 7637-2, (2004)	Road vehicles - Electrical disturbance by conduction and coupling - Part 2: Electrical transient conduction along supply lines only.
[21]	ISO 7637-3, (1995) with correction 1, (1995)	Road vehicles - Electrical disturbance by conduction and coupling - Part 3: Passenger cars and light commercial vehicles with nominal 12 V supply voltage and commercial vehicles with 24 V supply voltage - electrical transient transmission by capacitive and inductive coupling via lines other than supply lines.

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5.2.3.2 Apportioning of errors to modules tested separatelySubject to agreement with the approving authority, the manufacturer may define and submit modules to be examined separately. Where modules are examined separately in the process of type approval, the following requirements applyThe error limits applicable to a module which is examined separately are equal to a fraction P_i of the maximum permissible errors. The fractions for any module have to be taken for at least the same accuracy class as for the complete instrument incorporating the module.The fractions P_i shall satisfy the following equation:$P_1^2 + P_2^2 + P_3^2 +... \leq 1$The fraction P_i shall be chosen by the manufacturer of the module and shall be verified by an appropriate test, taking into account the following conditions:For digital modules p_i may be equal to 0

–For all other modules, the fraction shall not exceed 0.8 and shall not be less than 0.3, when more than one module contributes to the effect in question.Note: As the requirements of this subclause only apply to the instrument submitted for type evaluation and not to those subsequently submitted for verification, the means by which it will be possible to determine whether the appropriate accuracy requirement has been met will be decided mutually between the metrological authority and the applicant. For example:an adaptation of an indicating module or printer, or

–use of a suitable test connector, or

–use of calibrated pulse counter, or

any other means mutually agreed.5.2.3. Place of testing

Instruments submitted for type approval may be tested either:

a)on the premises of the metrological authority to which the application has been submitted, or

b)in any other suitable place agreed between the metrological authority concerned and the applicant.

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The taximeter system shall be installed so that a measurement operation will be the same for testing as it is for a normal operation. Where appropriate, pshall be conductedin order to determine the influences of the vehicle on the metrological requirements of the taximeter.