ORGANISATION INTERNATIONALE DE MÉTROLOGIE LÉGALE



INTERNATIONAL RECOMMENDATION

Automatic catchweighing instruments Part 2: Test report format

Instruments de pesage trieurs-étiqueteurs à fonctionnement automatique Partie 2: Format du rapport d'essai

OIML R 51-2

Edition 1996 (E)

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FOREWORD

The International Organization of Legal Metrology (OIML) is a worldwide, intergovernmental organization whose primary aim is to harmonize the regulations and metrological controls applied by the national metrological services, or related organizations, of its Member States.

The two main categories of OIML publications are:

- 1) **International Recommendations (OIML R)**, which are model regulations that establish the metrological characteristics required of certain measuring instruments and which specify methods and equipment for checking their conformity; the OIML Member States shall implement these Recommendations to the greatest possible extent;
- 2) **International Documents (OIML D)**, which are informative in nature and intended to improve the work of the metrological services.

OIML Draft Recommendations and Documents are developed by technical committees or subcommittees which are formed by the Member States. Certain international and regional institutions also participate on a consultation basis.

Cooperative agreements are established between OIML and certain institutions, such as ISO and IEC, with the objective of avoiding contradictory requirements; consequently, manufacturers and users of measuring instruments, test laboratories, etc. may apply simultaneously OIML publications and those of other institutions.

International Recommendations and International Documents are published in French (F) and English (E) and are subject to periodic revision.

OIML publications may be obtained from the Organization's headquarters:

Bureau International de Métrologie Légale 11, rue Turgot - 75009 Paris - France Telephone: 33 (0)1 48 78 12 82 and 42 85 27 11

Fax: 33 (0)1 42 82 17 27

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INTRODUCTION

This "test report format" aims at presenting, in a standardized format, the results of the various tests and examinations to which a pattern of an automatic catchweighing instrument shall be submitted with a view to its approval.

The test report format consists of two parts, a "checklist" and the "test report" itself.

The checklist is a summary of the examinations carried out on the instrument. It includes the conclusions of the results of the test performed, experimental or visual checks based on the requirements of Part 1. The words or condensed sentences aim at reminding the examiner of the requirements in R 51-1 without reproducing them.

The test report is a record of the results of the tests carried out on the instrument. The "test report" forms have been produced based on the tests detailed in R 51-1.

All metrology services or laboratories evaluating patterns of automatic catchweighing instruments accordingly to R 51 or to national or regional regulations based on this OIML Recommendation are strongly advised to use this test report format, directly or after translation into a language other than English or French. Its direct use in English or in French, or in both languages, is even more strongly recommended whenever test results may be transmitted by the country performing these tests to the approving authorities of another country, under bi- or multilateral cooperation agreements. In the framework of the *OIML Certificate System for measuring instruments*, use of this test report format is mandatory.

The "information concerning the test equipment used for pattern evaluation" shall cover all test equipment which has been used in determining the test results given in a report. The information may be a short list containing only essential data (name, type, reference number for purpose of traceability). For example:

- Verification standards (accuracy, or accuracy class, and No.)
- Simulator for testing of modules (name, type, traceability and No.)
- Climatic test and static temperature chamber (name, type and No.)
- Electrical tests, bursts (name of the instrument, type and No.)
- Description of the procedure of field calibration for the test of immunity to radiated electromagnetic fields

Note concerning the numbering of the following pages

In addition to a sequential numbering: "R 51-2 page .." at the bottom of the pages of this publication, a special place is left at the top of each page (starting with the following page) for numbering the pages of reports established following this model; in particular, some tests (e.g. metrological performance tests) shall be repeated several times, each test being reported individually on a separate page following the relevant format; in the same way, a multiple range instrument shall be tested separately for each range and a separate form (including the general information form) shall be filled out for each range. For a given report, it is advisable to complete the sequential numbering of each page by the indication of the total number of pages of the report.

IDENTIFICATION OF THE INSTRUMENT

Application No:			
Report date:			
Pattern designation:			
Manufacturer:			
Serial No:			
Manufacturing Documentation	on		
(Record as necessary to ident	ify the equipment under test)		
System or module name	Drawing number or software reference	Issue level	Serial No.
Simulator documentation			
System or	Drawing number or	Issue	Serial No.
module name	software reference	level	
Simulator function (summary)		

Simulator description and drawings, block diagram etc should be attached to the report if available.

IDENTIFICATION OF THE INSTRUMENT (continued)

Application No:	
Report date:	
Pattern designation:	
Manufacturer:	
Description or other informati	on pertaining to identification of the instrument:
(attach photograph here if ava	ilable)

GENERAL INFORMATION CONCERNING THE PATTERN

Application No:	
Pattern designation:	
Manufacturer:	
Applicant:	
Instrument category:	
Testing on:	Complete instrument Module(*)
Accuracy class	Instrument
Minimum capacity	Maximum capacity
T = +	T = - e =
U _{nom} (**) =	$V \qquad U_{min} = $
Zero-setting device:	
Nonautomatic	
Semi-automatic	
Automatic zero-setting	
Initial zero-setting	
Initial zero-s	etting range % Temperature range °C
Zero-tracking device:	
Printer:	Built in Connected Not present but connectable No Connection

^(*) The test equipment (simulator or part of a complete instrument) connected to the module shall be defined in the test form(s) used.

^(**) The voltage U_{nom} shall be as defined at IEC 1000-4-11 (1994) section 5.

GENERAL INFORMATION CONCERNING THE PATTERN (continued)

Instrument submitted:		Loadcell:	
Identification No:		Manufacturer:	
Connected equipment:		Type:	
Remarks:		Capacity:	
		Number:	
Interfaces: (number, nature)		Classification symbol:	
Remarks: see	following page		
Date of report:		Evaluation period:	
Observer:			

GENERAL INFORMATION CONCERNING THE PATTERN (continued)

Use this space to indicate additional remarks and/or information: other connected equipment, interfaces and load cells, choice of the manufacturer regarding protection against disturbances, etc.

SUMMARY OF PATTERN EVALUATION & CHECKLIST

The "SUMMARY OF PATTERN EVALUATION" and the "CHECKLIST" shall be completed according to this example:

when the instrument has passed the test:

when the instrument has failed the test:

X

when the test is not applicable:

//

SUMMARY OF PATTERN EVALUATION

Requirements:	Passed	Failed	Remarks
Metrological requirements			
Technical requirements			
Requirements for electronic instruments			
Metrological controls			
Test Report			
OVERALL RESULT			

Use this space to detail remarks from the summary of the pattern evaluation.

SUMMARY OF PATTERN EVALUATION (continued)

Use this page to detail remarks from the summary of the pattern evaluation.

Application No:	
Pattern designation:	

Requirement (R 51-1)	Test procedure	Catchweigher checklist	Passed	Failed	Remarks
2		Metrological requirements			
2.2	Maximum permissible errors for Class X()				
	A.6.1.1	Maximum permissible mean (systematic) error for automatic operation			
	A.6.1.1	Maximum permissible standard deviation of errors for automatic operation			
2.3	A.6.1.1	Maximum permissible errors for Class Y(a) and Y(b)			
2.4		Maximum and minimum capacities			
		Maximum capacity			
		Minimum capacity			
2.5		Maximum permissible errors for influence factor tests			
2.5.1	A.6.1.1	Class X(x) automatic operation			
	A.6.1.2	Class X(x) static weighing			
2.5.2	A.6.1.1	Class Y(y) automatic operation			
	A.6.1.2	Class Y(y) static weighing			
2.6		Indication or printout of weight for test purposes			
		For Class $X(\)$ scale interval e, is not greater than appropriate limit for Table 2			
		For Class $X(\cdot)$ alternative means are used to comply with Tables 1 and 2			
		For Class Y() practical means provided for demonstrating compliance with Table 1 and Table 3 $$			
2.7		Units of measurement: t, kg, g or mg			
2.8	A.6.7	Effect of eccentric loading			
		Maximum permissible errors in 2.5 are not exceeded			
2.9		Influence factors			
2.9.1	A.7.1	Static temperature tests			
	A.7.2	Temperature effect on no load indication			
2.9.2	A.7.4	Power voltage variation			
2.9.3	A.7.5	Tilting			
	A.7.5	Instruments not permanently installed no level indicator			
		Instruments not permanently installed with level indicator, can be set to 1 % or less			
3		Technical Requirements			
3.1	A.3.3	Suitability for use			
		Instrument suits the method of operation and the loads for which it is intended			

Requirement (R 51-1)	Test procedure	Catchweigher checklist	Passed	Failed	Remarks
3.1 cont.	A.3.3 cont.	Robust construction			
3.2	A.3.4	Security of operation			
3.2.1		Accidental maladjustment			
		Effect of accidental breakdown or maladjustment is evident			
3.2.2		Static adjustment			
		External influence on this device is practically impossible after securing			
3.2.3		Dynamic setting	•		
		Maximum permissible errors are not exceeded			
		Operation inhibited outside range where permissible errors not exceeded			
		Means available to automatically record access to setting facility or, for Class X() a static span adjustment device that can be sealed			
3.2.4	A.3.5	Controls	-		
		Come to rest in intended positions			
		Unambiguously marked keys			
3.3		Zeroing and tare devices			
3.3.1	A.6.4	Zero-setting			
	A.6.4.2	Range of adjustment not greater than 4 % Max			
		Automatic zero-setting operates only when:			
	A.6.5	Stability criteria are fulfilled			
	A.6.4.3	Sets zero to within 0.25 e			
	A.6.5	At a frequency such that the zero is maintained within 0.5 e			
		Nonautomatic zero-setting device is not operable during automatic operation			
		Semi-automatic zero-setting device functions only when stability criteria are fulfilled			
3.3.2		Zero-tracking device operates only when:			
		Indication is at zero, or at a negative net zero value equivalent to gross zero			
		Stability criteria are fulfilled			
		Corrections are not more than 0.5 e/second			
		When zero is indicated after a tare operation, zero-tracking may operate within a range of 4 % of Max around actual zero value			
3.3.3	A.6.6	Tare device			
		Has accuracy better than ± 0.25 e			
		Operation is clearly visible			
		Is independent of the zero-setting function			
		Scale interval is same as that of instrument			
		Operates only when stability criteria are fulfilled			

Requirement (R 51-1)	Test procedure	Catchweigher checklist	Passed	Failed	Remarks
3.3.3 cont.	A.6.6 cont.	Not operable during automatic operation			
3.3.4	A.6.6.2	Preset tare device			
		Resolution better than e, in which case the instrument is inhibited from automatically modifying the entered value to correspond with the verification scale interval			
		Tare weight values are clearly designated when indicated or printed			
		Clearly indicated and identified at least temporarily			
3.4	A.3.6	Indication of weighing results			
3.4.1		Quality of reading			
		Reliable, easy and unambiguous			
		Overall inaccuracy of an analogue device shall not exceed 0.2 e			
		Figures forming the results shall be of a size, shape and clarity for reading to be easy			
		Scales, numbering and printing shall permit the figures to be read by simple juxtaposition			
3.4.2		Form of the indication			
		Results contain names and symbols of the units of mass			
		Scale interval in the form 1 x 10 ^k , 2 x 10 ^k or 5 x 10 ^k units (k being a positive or negative whole number or zero)			
		Digital indication displays at least one figure beginning at extreme right			
		Decimal sign used to separate integer and decimal fraction			
		Zero may be displayed by one zero to the extreme right without a decimal sign			
		Unit of mass is such that there is not more than one non- significant zero to the right			
3.4.3		Limits of indication			
		For Class X() instruments: no indication above Max + 9 e or Max + 3 times the mps as specified in Table 2, whichever is the greater			
		For Class Y() instruments: no indication above Max + 9 e			
3.4.4		Indication or printout of weight for normal operation		•	•
		Scale interval of indications or printouts is not less than the verification scale interval e			
3.5		Printing device			
		Clear and permanent			
		At least 2 mm high			
		Name or symbol of unit is to the right of the value or above a column of values			
		Printing below minimum capacity is not possible			

Requirement (R 51-1)	Test procedure	Catchweigher checklist	Passed	Failed	Remarks
3.5 cont.		The same data is not able to be printed twice on the ticket or label			
3.6	A.3.7	Price computing instrument			-
		Price is calculated and rounded to the nearest scale interval of price to pay			
		The interval of price to pay, and the monetary symbols complies with national regulations			
		Unit price is either Price/100 g or Price/kg			
3.7	A.3.8	Weigh or weigh-price labelling instruments			
		At least one display for the weight			
		Actual values of unit price can be verified during automatic operation			
		Actual values of preset tare can be verified during automatic operation			
		Total values of totalised weight and price data are identified by a special word or symbol and are algebraic sums of all the values printed			
3.8	A.3.2	Descriptive markings			
3.8.1		Markings shown in full:			
		Identification mark of the manufacturer			
		Identification mark of the importer (if applicable)			
		Serial number and type designation of the instrument			
		Maximum rate of operation			
		Maximum speed of load transport system (if applicable)			
		Electrical supply voltage			
		Electrical supply frequency			
		Working fluid pressure (if applicable)			
		Adjustment range (referred to set point) (if applicable)			
3.8.2		Markings shown in code:			
		Pattern approval sign			
		Indication of the class of accuracy X() or Y()			
		Verification scale interval			
		Scale interval			
		Maximum capacity			
		Minimum capacity			
		Maximum tare additive			
		Maximum tare subtractive			
3.8.3		Supplementary markings			
		Are required	enter in	n remarks	
3.8.4		Presentation of descriptive markings			
		Indelible			
		Size, shape and clarity that allows easy reading			

Requirement (R 51-1)	Test procedure	Catchweigher checklist	Passed	Failed	Remarks
3.8.4 cont.		Grouped together in a clearly visible place			
		Shown on a programmable display, access automatically and non-erasably recorded			
		Plate to contain type, designation of instrument, manufacturer, pattern approval number, electrical supply voltage, electrical supply frequency, pneumatic pressure			
3.9		Verification marks			
3.9.1		Position			
		Place where verification marks are located cannot be removed without damaging the marks			
		Allows easy application of marks			
		Visible without the instrument or its protective covers having to be removed			
3.9.2		Mounting			
		Verification mark support to ensure conservation of the marks			
		Support is of the correct construction			
4		REQUIREMENTS FOR ELECTRONIC INSTRUMENTS			
4.1		General requirements			
4.1.1		Rated operated conditions			
		Maximum permissible errors are not exceeded			
4.1.2		Influence factors			
	A.6.7	Complies with the requirements of 2.8			
	A.7.3	Damp heat steady state			
4.1.3	A.8	Disturbances			
	A.8.1	Short time power reduction			
	A.8.2	Electrical bursts			
	A.8.3	Electrostatic discharge			
	A.8.4	Electromagnetic susceptibility			
4.1.4		Evaluation for compliance			
		Complies with specified requirements			
4.2		Functional requirements			
4.2.1		Switch on procedure / indicator test			
4.2.2		Acting upon a significant fault			
		Either the instrument is made inoperative automatically, or			
		A visual or audible indication is provided automatically and continues until the user takes action or the fault disappears			
4.2.3	A.6.2	Warm-up time			
		No indication or transmission of weighing results			
		Automatic operation is inhibited			
		During first 30 minutes of operation:			
		zero error	r		
		span erroi			

procedure	Catchweigher checklist	Passed	Failed	Remarks
	Interface:			
	Instrument continues to function correctly when interfaces are used.			
	Metrological functions are not influenced			
	Battery power supply			
	Continues to function correctly whenever the voltage drops below the manufacturers specified minimum value, or			
	Is automatically put out of service			
	Examination and tests			
	Examinations:			
	General appraisal of design and construction			
	Instrument meets the requirements of the following tests:			
A.7.1	Static temperatures			
A.7.2	Temperature effect on no load indication			
A.7.3	Damp heat, steady state			
A.7.4	Power voltage variations			
A.7.5	Tilting			
A.8.1	Short time power reduction			
A.8.2	Bursts			
A.8.3	Electrostatic discharge			
A.8.4	Electromagnetic susceptibility			
A.9	Span stability			
	Performance tests and span stability			
	Continually updated weight indication			
	Is present when it is not possible for the instrument to be fully operational during the influence factor tests			
	METROLOGICAL CONTROLS			
	Pattern approval			
	Documentation includes:			
	Metrological characteristics of the instrument			
	A standard set of specifications for the instrument			
	A functional description of the components and devices			
	Drawings, diagrams and general software information (if applicable), explaining the construction and operation, and			
	Any document or other evidence that the design and construction of the instrument complies with the requirements of the recommendation			
	A.7.2 A.7.3 A.7.4 A.7.5 A.8.1 A.8.2 A.8.3 A.8.4	Instrument continues to function correctly when interfaces are used. Metrological functions are not influenced Battery power supply Continues to function correctly whenever the voltage drops below the manufacturers specified minimum value, or Is automatically put out of service Examination and tests Examinations: General appraisal of design and construction Instrument meets the requirements of the following tests: A.7.1 Static temperatures A.7.2 Temperature effect on no load indication A.7.3 Damp heat, steady state A.7.4 Power voltage variations A.7.5 Tilting A.8.1 Short time power reduction A.8.2 Bursts Electrostatic discharge A.8.4 Electromagnetic susceptibility A.9 Span stability Performance tests and span stability Continually updated weight indication Is present when it is not possible for the instrument to be fully operational during the influence factor tests METROLOGICAL CONTROLS Pattern approval Documentation includes: Metrological characteristics of the instrument A standard set of specifications for the instrument A functional description of the components and devices Drawings, diagrams and general software information (if applicable), explaining the construction and operation, and Any document or other evidence that the design and construction of the instrument complies with the	Instrument continues to function correctly when interfaces are used. Metrological functions are not influenced Battery power supply Continues to function correctly whenever the voltage drops below the manufacturers specified minimum value, or Is automatically put out of service Examination and tests Examinations: General appraisal of design and construction Instrument meets the requirements of the following tests: A.7.1 Static temperatures A.7.2 Temperature effect on no load indication A.7.3 Damp heat, steady state A.7.4 Power voltage variations A.7.5 Tilting A.8.1 Short time power reduction Bursts A.8.2 Bursts A.8.3 Electrostatic discharge A.8.4 Electromagnetic susceptibility Performance tests and span stability Continually updated weight indication Is present when it is not possible for the instrument to be fully operational during the influence factor tests METROLOGICAL CONTROLS Pattern approval Documentation includes: Metrological characteristics of the instrument A standard set of specifications for the instrument A functional description of the components and devices Drawings, diagrams and general software information (if applicable), explaining the construction and operation, and Any document or other evidence that the design and construction of the instrument complies with the	Instrument continues to function correctly when interfaces are used. Metrological functions are not influenced Battery power supply Continues to function correctly whenever the voltage drops below the manufacturers specified minimum value, or Is automatically put out of service Examination and tests Examinations: General appraisal of design and construction Instrument meets the requirements of the following tests: A.7.1 Static temperatures A.7.2 Temperature effect on no load indication A.7.3 Damp heat, steady state A.7.4 Power voltage variations A.7.5 Tilting A.8.1 Short time power reduction A.8.2 Bursts A.8.3 Electrostatic discharge A.8.4 Electromagnetic susceptibility A.9 Span stability Performance tests and span stability Continually updated weight indication Is present when it is not possible for the instrument to be fully operational during the influence factor tests METROLOGICAL CONTROLS Pattern approval Documentation includes: Metrological characteristics of the instrument A standard set of specifications for the instrument A functional description of the components and devices Drawings, diagrams and general software information (if applicable), explaining the construction and operation, and Any document or other evidence that the design and construction of the instrument complies with the

Requirement (R 51-1)	Test procedure	Catchweigher checklist	Passed	Failed	Remarks					
5.2.3.1		Operational tests carried out as follows:								
		In accordance with the descriptive markings (subclause 3.8) under the normal conditions of use for which the instrument is intended, and								
		In accordance with the test methods in clause 6								
5.3		Initial verification and in-service inspection								
5.3.1		Tests								
		Are carried out to verify compliance with the requirements in clause 2 (excluding 2.8) and clause 3 (where applicable)								
6		TEST METHODS								
6.5	A.6.1.2	Static test loads for approval testing								
6.5.3		Influence factor testing								
	A.4.4	Use of static test loads in nonautomatic mode for influence factor testing								
	A.6.1.2	Instrument weighs statically in normal operation								
	A.6.1.2	Random errors not significant in normal operation		_						
	A.6.1.2	Influence factor tests done in non-auto mode								

Use this space to detail remarks from the checklist

Use this page to detail remarks from the checklist (continued)

INFORMATION CONCERNING THE TEST EQUIPMENT USED FOR PATTERN EVALUATION

TEST EQUIPMENT

Application No:				
Report date:				
Pattern designation:				
Manufacturer:				
List all test equipment used in	this report			
Equipment name	Manufacturer	Type No	Serial No: (test refe	Used for: rences)

CONFIGURATION FOR TEST

Application No:	
Report date:	
Pattern designation:	
Manufacturer:	

Use this space for additional information relating to equipment configuration, interfaces, data rates, load cells EMC protection options etc, for the instrument and/or simulator.

EXPLANATORY NOTES

Meaning of symbols:

 $\begin{array}{lcl} I & = & Indication \\ I_n & = & n^{th} \ indication \end{array}$

L = Load

 ΔL = Additional load to next changeover point

P = $I + \frac{1}{2}e - \Delta L$ = Indication prior to rounding (digital indication)

E = I - L or P - L = Error

mpme = Maximum permissible mean (systematic) error for automatic operation
mps = Maximum permissible standard deviation of the error for automatic operation

mpe = Maximum permissible error EUT = Equipment under test

The name(s) or symbol(s) of the unit(s) used to express test results shall be specified in each form.

The white spaces in boxes in the headings of the report should always be filled according to the following example:

	At start	At end	_
Temp:	20.5	21.1	°C
Rel. h:			%
Date:	96:01:29	96:01:30	yy:mm:dd
Time:	16:00:05	16:30:25	hh:mm:ss

where:

Temp = temperature Rel. h = relative humidity

"Date" in the test reports refers to the date that the test was performed.

In the disturbance tests, faults greater than e are acceptable provided that they are detected and acted upon, or that they result from circumstances such that these faults shall not be considered as significant; an appropriate explanation shall be given in the column "Yes (remarks)".

Section numbers in brackets refer to the corresponding subclauses of R 51-1.

_	_	
Report	Page	/

٢	2	יי	г	T'	٨	Λ	П	٨	/	r	A	1	п	١,		,	ſ	١	ı	7	r	Т	١	7	6	3	г	1	7	П	7	п	n	•	`	т	•	т	١
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Application No:	
Pattern designation:	

	Tests	Test Completed	Report page
1	Warm-up time test		
2	Dynamic setting		
3	Zero-setting		
4	Tare		
5	Eccentric loading		
6	Speed of operation		
7	Influence factors		
7.1	Pre-test for instruments that weigh statically		
7.2	Static temperatures		
7.3	Temperature effect on no load indication		
7.4	Damp heat, steady state		
7.5	Power voltage variation		
7.6	Tilting		
8	Disturbances		
8.1	Short time power reductions		
8.2	Electrical bursts		
8.3	Electrostatic discharges		
8.4	Electromagnetic susceptibility		
9	Span stability		

Note: A "sample test report" sheet for including weight indication for each pass of load (up to 60 passes) is included at the end of this document. These sheets are not included in each section as they are not required for all instrument types.

1 WARM-UP TIME (4.2.3, A.6.2)

Application No: Pattern designation:							
Observer:							
				At s	tart	At end	
				mp:			°C
				l. h:			%
				ate:			yy:mm:d
Verification scale interval e:			Ti 	me:			hh:mm:s
Resolution during test	st						
Duration of disconne before test:	ection						
Automatic zero-settir	ng and zero-t	tracking device	e is:			_	
Non-existent		Not in operati	on (Out of working r	ange	In operation	1
$E = I + \frac{1}{2}e - \Delta L - E_0 = \text{error calculated}$ $E_L = \text{error calculated}$	at zero or ne		aded)				
	time (*)	Load L	Indication I	Add load ΔL	Error	$E_L - E_0$	
Unloaded					$E_{0l}=$		
Loaded	0 min				$E_L =$		1
						_	
Unloaded					$E_0=$		_
Loaded	5 min				$E_L =$		
			_			_	
Unloaded					$E_0=$		_
Loaded	15 min				$E_L=$		
				1		_	
Unloaded	30 min				$E_0=$		_
Loaded	30 IIIII		<u> </u>		$E_L =$		
		nt an indicatio	on has first appeare	d.			
Initial zero-setting	error		E_{0I}	jj j			

Remarks:

Maximum value of error unloaded

Maximum value of error loaded

 E_0

 $E_L - E_0$

2 RANGE OF DYNAMIC SETTING (3.2.3, A.6.3)

Application No:				
Pattern designation:				
Observer:				
		At start	At end	_
	Temp:			°C
	Rel. h:			%
	Date:			yy:mm:dd
	Time:			hh:mm:ss
Verification scale interval e:				_
Resolution during test (smaller than e):				
Load nominal value:				
Load setting range min value:				
max value:				
Rate of operation (max):				
INSIDE SET RANGE				

LOAD VALUE	NUMBER OF PASSES	MEAN X	STANDARD DEVIATION (s)
Min			
Max			

OUTSIDE SET RANGE

LOAD VALUE	OPERATION INHIBITED	PRINTING INHIBITED
Min		
Max		

Application No:					
Pattern designation:					
Observer:					
		_	At start	At end	_
		Temp:			°C
		Rel. h:			%
		Date:			yy:mm:dd
		Time:			hh:mm:ss
Verification scale interval e:					
Resolution during te (smaller than e):	st				

3.1 Modes of zero-setting (A.6.4.1)

ZERO-SETTING (3.3.1, A.6.4)

3

	PRESENT	RANGE TESTED	ACCURACY TESTED
Nonautomatic			
Semi-automatic			
Auto-zero at switch on			
Auto-zero at start of automatic operation			
Auto-zero as part of weighing cycle			
Auto-zero after fixed interval			

3.2 Range of zero-setting (A.6.4.2)

Positive	range L ₁	Negati	ve range L ₂	Range $L_1 + L_2$	% of Max load
Weight added	Zero yes/no	Weight added	Zero yes/no		

3.3 Accuracy of zero-setting:

$3.3.1 \quad Static \ test \ method \ (A.6.4.3.1)$

ΔL	$E = \frac{1}{2}e - \Delta L$

3.3.2 Dynamic test method (A.6.4.3.2)

Verification scale interval	e	
Number of weighings	n	60
Mean of the indications	$\overline{\mathbf{x}}$	
Standard deviation of the indications	S	
0.25 e - 0.167 s		

Results c	onfirm $X \le (0.25 \text{ e} - 0.167 \text{ s})$	
or 0.25 e	$> \overline{X} > (0.25 \text{ e} - 0.167 \text{ s})$	
or	$\bar{x} > 0.25 e$	

FURTHER TEST WITH n > 60

Verification scale interval	e	
Number of weighings	n	
Mean of the indications	$\overline{\mathbf{x}}$	
Standard deviation of the indications	s	
$0.25 \text{ e} - 1.296 \text{ s}/\sqrt{n}$		

Results	confirm $\overline{X} \le (0.25 \text{ e} - 1.296 \text{ s}/\sqrt{n})$	
or 0.25 e	$> \overline{x} > (0.25 \text{ e} - 1.296 \text{ s/}\sqrt{n})$	
or	$\overline{x} > 0.25 \text{ e}$	

3.3.3 Alternative dynamic test method

Details of method:

Result for true mean	μ	
----------------------	---	--

3.4 Stability of zero and frequency of automatic zero-settin	g (A	A.6	.5)
--	------	------------	----	---

Approximate maximum interval between automatic zero-setting	
Approximate maximum interval between automatic zero-setting	

$3.4.1 \quad Static \ test \ method \ (A.6.4.3.1)$

$\Delta \mathrm{L}$	$E = \frac{1}{2}e - \Delta L$

Remarks:

3.4.2 Dynamic test method (A.6.4.3.2)

Verification scale interval	e	
Number of weighings	n	60
Mean of the indications	$\overline{\mathbf{x}}$	
Standard deviation of the indications	S	
0.25 e - 0.167 s		

Results confirm $\overline{X} \le (0.25 \text{ e} - 0.167 \text{ s})$	
or $0.25 \text{ e} > \overline{X} > (0.25 \text{ e} - 0.167 \text{ s})$	
or $\overline{X} > 0.25 e$	

FURTHER TEST WITH n > 60

Verification scale interval	e	
Number of weighings	n	
Mean of the indications	$\overline{\mathbf{x}}$	
Standard deviation of the indications	S	
$0.25 \text{ e} - 1.296 \text{ s}/\sqrt{n}$		

Results confirm $\overline{X} \le (0.25 \text{ e} - 1.296 \text{ s}/\sqrt{n})$	
or $0.25 \text{ e} > \overline{x} > (0.25 \text{ e} - 1.296 \text{ s}/\sqrt{n})$	
or $\overline{x} > 0.25 e$	

3.4.3 Alternative dynamic test method

Details of Method:

μ	
	μ

3.5 Test of additional zero-setting modes (A.6.4)

7 1	
Zero-setting mode	
zero setting mode	

3.5.1 Accuracy of zero-setting (A.6.4.3.1)

Positive	range L ₁	Negative range L ₂		Range $L_1 + L_2$	% of Max load
Weight added	Zero yes/no	Weight added	Zero yes/no		

Remarks:

3.5.2.1 Accuracy of zero-setting: static test method (A.6.4.3.1)

ΔL	$E = \frac{1}{2} e - \Delta L$

Remarks:

3.5.2.2 Accuracy of zero-setting: dynamic test method (A.6.4.3.2)

Verification scale interval	e	
Number of weighings	n	60
Mean of the indications	$\overline{\mathbf{x}}$	
Standard deviation of the indications	S	
0.25 e - 0.167 s		

Results confirm $\overline{X} \le (0.25 \text{ e} - 0.167 \text{ s})$	
or $0.25 \text{ e} > \overline{X} > (0.25 \text{ e} - 0.167 \text{ s})$	
or $\overline{x} > 0.25 e$	

FURTHER TEST WITH n > 60

Verification scale interval	e	
Number of weighings	n	
Mean of the indications	$\overline{\mathbf{x}}$	
Standard deviation of the indications	S	
$0.25 \text{ e} - 1.296 \text{ s}/\sqrt{n}$		

3.5 Test of additional zero-setting modes (continued)

3.5.2.2 Accuracy of zero-setting (continued)

Results confirm $\overline{X} \le (0.25 \text{ e} - 1.296 \text{ s}/\sqrt{n})$	
or $0.25 \text{ e} > \overline{X} > (0.25 \text{ e} - 1.296 \text{ s}/\sqrt{n})$	
or $\overline{X} > 0.25 e$	

3.5.2.3 Alternative dynamic test method

Details of method:

|--|

4 TAKE DEVICE (Accuracy) (3.3.3, A.6.6)				
Application No:					
Pattern designation:					
Observer:					
			At start	At end	
		Temp:			°C
		Rel. h:			%
		Date:			yy:mm:dd
		Time:			hh:mm:ss
Verification scale interval e: Resolution during test					_
(smaller than e):					
	mi-automatic tare (A.6.6.6)			7	
Tare load					
				7	
ΔL		$E = \frac{1}{2}e -$	Δ L		
				<u>]</u>	
Remarks:					
4.1.2 Accuracy of tare:	dynamic test method (A.	.6.6.1.2)			
Tare load					
Verification scale interva	al e				

Tare load		
Verification scale interval	e	
Number of weighings	n	60
Mean of the indications	$\overline{\mathbf{x}}$	
Standard deviation of the indications	S	
0.25 e - 0.167 s		

4.1.2 Accuracy of tare: dynamic test method (continued)

Results o	confirm $\overline{X} \le (0.25 \text{ e} - 0.167 \text{ s})$	
or 0.25 e	$> \overline{X} > (0.25 \text{ e} - 0.167 \text{ s})$	
or	$\overline{x} > 0.25 \text{ e}$	

FURTHER TEST WITH n > 60

Verification scale interval	e	
Number of weighings	n	
Mean of the indications	$\frac{1}{x}$	
Standard deviation of the indications	s	
$0.25 \text{ e} - 1.296 \text{ s}/\sqrt{n}$		

Results	confirm $\overline{X} \le (0.25 \text{ e} - 1.296 \text{ s}/\sqrt{n})$	
or 0.25 e	$> \overline{x} > (0.25 \text{ e} - 1.296 \text{ s/}\sqrt{n})$	
or	$\frac{-}{x} > 0.25 \text{ e}$	

4.1.3 Alternative dynamic test method

Details of method:

Result for true mean	
Result for true mean	ıı l
result for true mean	P

4.2 Preset tare (A.6.6.2)

4.2.1 Accuracy of tare: static test method (A.6.6.2)

Tare load	
$\Delta ext{L}$	$E = \frac{1}{2} e - \Delta L$

4.2.2 Accuracy of tare: dynamic test method (A.6.6.2)

Tare load		
Verification scale interval	e	
Number of weighings	n	60
Mean of the indications	$\overline{\mathbf{x}}$	
Standard deviation of the indications	S	
0.25 e - 0.167 s		

Results	confirm $X \le (0.25 e - 0.167 s)$	
or 0.25 e	$e > \overline{X} > (0.25 \text{ e} - 0.167 \text{ s})$	
or	$\overline{X} > 0.25 \text{ e}$	

FURTHER TEST WITH n > 60

Verification scale interval	e	
Number of weighings	n	
Mean of the indications	\overline{x}	
Standard deviation of the indications	s	
$0.25 \text{ e} - 1.296 \text{ s}/\sqrt{n}$		

Results c	onfirm $\overline{X} \le (0.25 \text{ e} - 1.296 \text{ s}/\sqrt{n})$	
or 0.25 e	$> \overline{x} > (0.25 \text{ e} - 1.296 \text{ s}/\sqrt{n})$	
or	$\overline{X} > 0.25 \text{ e}$	

4.2.3 Alternative dynamic test method

Details of method:

|--|

5 ECCENTRIC LOADING (2.8, 6.2, A.6.7)

5.1 Eccentric test for instruments that weigh in motion (6.2, A.6.7.1)

Application No:				
Pattern designation:				
Observer:				
		At start	At end	
	Temp:			°C
	Rel. h:			%
	Date:			yy:mm:dd
	Time:			hh:mm:ss
Verification scale interval e:				
Resolution during test (smaller than e):				
Load (¹ / ₃ Max):				
Location of test loads for inst	ruments that weigh dynamically:			
Band 1 1/2 W	$\qquad \qquad \downarrow \mathbf{w}$	Band 2	w ļ	↓ 1/2 W
Rate of operation (max):				
CLASS X()				
Number of weighings				
Position	Mean X	Standard dev	viation s	
Band 1	+			
Band 2				
Dalid 2				

CLASS Y()

Number of weighings	

Position	Maximum error
Band 1	
Band 2	

5.2 Eccentric test for instruments that weigh statically (6.3, A.6.7.2)

 	···		
 	···		
 			
_	At start	At end	
Temp:			°C
Rel. h:			%
Date:			yy:mm:dd
Time:			hh:mm:ss
			_
	Rel. h: Date: Time:	Temp: Rel. h: Date: Time:	Temp: Rel. h: Date: Time:

Location of test loads for instruments that weigh statically

b

— а е |

d

Position	Indication	Error
a		
b		
С		
d		
e		

6 ALTERNATIVE OPERATING SPEEDS (6.1.4, A.6.8)

(Max speed, max load)					
Application No:					
Pattern designation:					
Observer:					
			At start	At end	
		Temp:			°C
		Rel. h:			%
		Date:			yy:mm:de
		Time:			hh:mm:ss
Verification scale interval e:					_
Resolution during test (smaller than e):					
Speed					
Automatic zero-setting devi	ce is:				
Non-existent	Not in operation	Out of wo	rking range	In opera	tion
Belt speed	Load	Mean X	Standard	deviation s	
Max	Max				
Max	Min				
Alternative	Max				
Alternative	Min				

7 INFLUENCE FACTORS (2.8 and 6.5.3)

7.1 Pre-test for instruments that weigh statically (6.5.3, A.4.4)

7.1.1	Pre-test for instru (Use this test shee							
Appl	ication No:							
Patte	rn designation:							
Obse	rver:				•			
				_	At start		At end	
				Temp:			c	C
				Rel. h:			9	6
				Date:				y:mm:dd
				Time:			h	h:mm:ss
	ication e interval e:							
	lution during test ller than e):							
Load	: (see 6.1.6)							
Speed	i:			Permitted	error:			
Autom	natic zero-setting dev	rice is:						
	Non-existent	Not in oper	ration	Out of	working range		In operation	
	1	-	<u> </u>		<u> </u>			1
Tes	st Indication	Error	Test	Indication	Error	Test	Indication	Error
1			21			41		
2			22			42		
3			23			43		
4			24			44		
5			25			45		
6			26			46		
7			27			47		
H-								
8			28			48		
9			29			49		
10			30			50		
11			31			51		
12			32			52		
13			33			53		
14			34			54		
15			35			55		
16	i		36			56		
17			37			57		
18			38			58		
19			39			59		
20			40			60		

7.1.1	Pre-test for instruments that weigh statically - Test 1 (continued)
Maxim	num error =

7.1.2 Pre-test for instruments that weigh statically - Test 2 (Use this test sheet for max. speed, min. load)

Application No:					
Pattern designation:					
Observer:					
		_	At start	At end	i
		Temp:			°C
		Rel. h:			%
		Date:			yy:mm:dd
		Time:			hh:mm:ss
Load: (see 6.1.6)					
Speed:	P	ermitted error:			
automatic zero-setting of	levice is:				
Non-existent	Not in operation	Out of w	orking range	In operation	on

Test	Indication	Error	Test	Indication	Error	Test	Indication	Error
1			21			41		
2			22			42		
3			23			43		
4			24			44		
5			25			45		
6			26			46		
7			27			47		
8			28			48		
9			29			49		
10			30			50		
11			31			51		
12			32			52		
13			33			53		
14			34			54		
15			35			55		
16			36			56		
17			37			57		
18			38			58		
19			39			59		
20			40			60		

7.1.2	Pre-test for it	nstruments that	weigh statically	- Test 2	(continued)
/ • 1 • 4	1 1 6-1631 101 11	usu umemis mai	weigh stantany	- 1 CSt 2	commuda,

 $Maximum\ error =$

7.1.3 Pre-test for instruments that weigh statically - Test 3 (Use this test sheet for alternative speed, max. load)

Application No:					
Pattern designation:					
Observer:					
		<u> </u>	At start	At end	_
		Temp:			°C
		Rel. h:			%
		Date:			yy:mm:dd
		Time:			hh:mm:ss
Verification scale interval e:					
Resolution during test (smaller than e):					
Load: (see 6.1.6)					
Speed:	Pe	rmitted error:			
Automatic zero-setting dev	vice is:				
Non-existent	Not in operation	Out of w	orking range	In operation	on

Test	Indication	Error	Test	Indication	Error	Test	Indication	Error
1			21			41		
2			22			42		
3			23			43		
4			24			44		
5			25			45		
6			26			46		
7			27			47		
8			28			48		
9			29			49		
10			30			50		
11			31			51		
12			32			52		
13			33			53		
14			34			54		
15			35			55		
16			36			56		
17			37			57		
18			38			58		
19			39			59		
20			40			60		

7.1.3	Pre-test for	instruments	that	weigh statically	v -	Test 3	(continued)
7.1.0	I I C CCSC IOI	mou amend	unu	Weigh budden	•	I COL O	Commune	

Maximum error =

7.1.4 Pre-test for instruments that weigh statically - Test 4 (Use this test sheet for alternative speed, min. load)

Application No:					
Pattern designation:					
Observer:					
		<u> </u>	At start	At end	_
		Temp:			°C
		Rel. h:			%
		Date:			yy:mm:dd
		Time:			hh:mm:ss
Verification scale interval e:					
Resolution during test (smaller than e):					
Load: (see 6.1.6)					
Speed:	Pe	rmitted error:			
Automatic zero-setting dev	vice is:				
Non-existent	Not in operation	Out of w	orking range	In operation	on

Test	Indication	Error	Test	Indication	Error	Test	Indication	Error
1			21			41		
2			22			42		
3			23			43		
4			24			44		
5			25			45		
6			26			46		
7			27			47		
8			28			48		
9			29			49		
10			30			50		
11			31			51		
12			32			52		
13			33			53		
14			34			54		
15			35			55		
16			36			56		
17			37			57		
18			38			58		
19			39			59		
20			40			60		

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7.1.4	Pre-test for instruments that weigh statically - Test 4 (continued)
Maxim	num error =
Remar	ks:

7.2 Static temperatures (2.9.1, A.7.1)

7.2.1	Static temperature	(20 °C)					
App	lication No:						
Patte	ern designation:						
Obse	erver:						
					At start	At end	
				Temp:			°C
				Rel. h:			%
				Date:			yy:mm:dd
				Time:			hh:mm:ss
	fication le interval e:						
	olution during test ller than e):						
Auton	natic zero-setting devic	e is:					
	Non-existent	Not in op	eration	Out of wo	orking range	In operation	n
Rate	of operation (max) if a	applicable				Static loa	d

CLASS X()

This table to be used for summary of automatic mode dynamic test results

	Load L	Mean of indicated readings X	Mean error (X - L)	Standard deviation s
Close to Min				
Critical point 1				
Critical point 2				
Close to Max				

This table to be used for nonautomatic single load static test results

	Load	Indication	Error
	L	I	Е
Close to Min			
Critical point 1			
Critical point 2			
Close to Max			

7.2.1 Static temperature (20 $^{\circ}$ C) (continued)

CLASS Y()

This table to be used for summary of automatic mode dynamic or nonautomatic single load static test results

	Load L	Number of weighings	Maximum error
Close to Max			
Critical point 1			
Critical point 2			
Close to Min			

Note: For Class $Y(\cdot)$ instruments for weighing loose material the number of weighings will equal 1 and the error will be the actual error E.

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	7.2.2 Static temperatur	re (specified l	high: °C)			
Observer: At start At end Temp: Rel. h: Date: Time: Verification scale interval e: Resolution during test (smaller than e): Automatic zero-setting device is: Non-existent Not in operation Out of working range In operation Rate of operation (max) if applicable Static load CLASS X() This table to be used for summary of automatic mode dynamic test results Load Mean of indicated Mean error Standard deviation L readings X (X - L) s	Application No:					
At start At end Temp: Rel. h: Date: Time: Verification scale interval e: Resolution during test (smaller than e): Automatic zero-setting device is: Non-existent Not in operation Out of working range In operation Rate of operation (max) if applicable Static load CLASS X() This table to be used for summary of automatic mode dynamic test results Load Mean of indicated Mean error Standard deviation L readings X (X - L) s	Pattern designation:					
Temp: Rel. h: Date: Time: Verification scale interval e: Resolution during test (smaller than e): Automatic zero-setting device is: Non-existent Not in operation Out of working range In operation Rate of operation (max) if applicable CLASS X() This table to be used for summary of automatic mode dynamic test results Load Mean of indicated Mean error Standard deviation L readings X (X - L) S Close to Min	Observer:					
Rel. h: Date: Time: Werification scale interval e: Resolution during test (smaller than e): Automatic zero-setting device is: Non-existent Not in operation Out of working range In operation Rate of operation (max) if applicable Static load CLASS X() This table to be used for summary of automatic mode dynamic test results Load Mean of indicated Mean error Standard deviation L readings X (X - L) s				At start	At end	
Date: Time: wy:m hh:m Verification scale interval e:			Te	mp:		°C
Verification scale interval e: Resolution during test (smaller than e): Automatic zero-setting device is: Non-existent Not in operation Out of working range In operation Rate of operation (max) if applicable Static load CLASS X() Chis table to be used for summary of automatic mode dynamic test results Load Mean of indicated Mean error Standard deviation In readings X (X - L) S Close to Min Close to Min Standard deviation Standard Standar			Re	l. h:		%
Verification scale interval e: Resolution during test (smaller than e): Automatic zero-setting device is: Non-existent Not in operation Out of working range In operation Rate of operation (max) if applicable Static load CLASS X() This table to be used for summary of automatic mode dynamic test results Load Mean of indicated Mean error Standard deviation readings X (X - L) s Close to Min Close to Min			D	ate:		yy:mm:dd
Resolution during test (smaller than e): Automatic zero-setting device is: Non-existent Not in operation Out of working range In operation Rate of operation (max) if applicable CLASS X() This table to be used for summary of automatic mode dynamic test results Load Mean of indicated Mean error Standard deviation L readings X Close to Min Close to Min Close to Min			Ti	me:		hh:mm:ss
Automatic zero-setting device is: Non-existent Not in operation Out of working range In operation Rate of operation (max) if applicable CLASS X() This table to be used for summary of automatic mode dynamic test results Load Mean of indicated Mean error Standard deviation L readings X Close to Min Close to Min Close to Min						-
Non-existent Not in operation Out of working range In operation Rate of operation (max) if applicable Static load CLASS X() This table to be used for summary of automatic mode dynamic test results Load Mean of indicated Mean error Standard deviation Europe Standard deviation Readings X (X - L) S Close to Min Close to Min Readings X (X - L) S						
Rate of operation (max) if applicable	Automatic zero-setting dev	vice is:				
CLASS X() This table to be used for summary of automatic mode dynamic test results Load Mean of indicated Mean error Standard deviation L readings X (X - L) S Close to Min	Non-existent	Not in	operation	Out of working range	In operation	on
This table to be used for summary of automatic mode dynamic test results $ \begin{array}{c ccccccccccccccccccccccccccccccccccc$	Rate of operation (max) i	f applicable			Static load	
$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$	CLASS X()					
$\begin{array}{c ccccccccccccccccccccccccccccccccccc$	This table to be used for su	ımmary of aut	tomatic mode dynamic tes	st results		
Close to Min			Mean of indicated	Mean error	Standard deviation	7
		L	readings X	$(\overline{X} - L)$	S	
Critical point 1	Close to Min					1
	Critical point 1					1
Critical point 2						1
Close to Max						1

This table to be used for nonautomatic single load static test results

	Load	Indication	Error
	L	I	E
Close to Min			
Critical point 1			
Critical point 2			
Close to Max			

7.2.2 Static temperature (specified high: $^{\circ}$ C) (continued)

CLASS Y()

This table to be used for summary of automatic mode dynamic or nonautomatic single load static test results

	Load L	Number of weighings	Maximum error
Close to Max			
Critical point 1			
Critical point 2			
Close to Min			

Note: For Class Y() instruments for weighing loose material the number of weighings will equal 1 and the error will be the actual error E. Remarks:

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7.2.3 Static temperatur	re (specified	low: °C)					
Application No:							
Pattern designation:							
Observer:							
				At start	_	At end	1
			Temp: Rel. h:				°C %
			Date:				yy:mm:d
			Time:				hh:mm:s
Verification scale interval e:							
Resolution during test (smaller than e):							
Automatic zero-setting dev	ice is:						
Non-existent	Not in	operation	Out of w	orking range		In operation	on
Rate of operation (max) i	f applicable				Static load	1	
CLASS X()							
This table to be used for su	mmary of au	tomatic mode dynan	nic test results	S			
F	Load	Mean of indicate	ad M	ean error	Ctondo	rd deviation	1
	Load	readings X		(x - L)	Stanua	s s	
Close to Min				,			
Critical point 1							-
Critical point 2							
I -							-
Close to Max							
TI: . 11 1 16							
This table to be used for sta	atic test resul	ts					
	Load	Indication I	Error E				
	L	_	L L	II			
Close to Min	L		L	\dashv			
Close to Min Critical point 1	L	-					
I -	L						

7.2.3 Static temperature (specified low: °C) (continued)

CLASS Y()

This table to be used for summary of automatic mode dynamic or nonautomatic single load static test results

	Load L	Number of weighings	Maximum error
Close to Max			
Critical point 1			
Critical point 2			
Close to Min			

Note: For Class Y() instruments for weighing loose material the number of weighings will equal 1 and the error will be the actual error E. Remarks:

7.2.3 Static temperature (5 °C)

Application No:						
Pattern designation:						
Observer:						
			At start		At end	
		Temp:				°C
		Rel. h:				%
		Date:				yy:mm:dd
		Time:				hh:mm:ss
Verification scale interval e:						
Resolution during test (smaller than e):						
Automatic zero-setting device is	s:					
Non-existent	Not in operation	Out of w	orking range		In operation	
Rate of operation (max) if app	olicable			Static load		

CLASS X()

This table to be used for summary of automatic mode dynamic test results

	Load L	Mean of indicated readings X	Mean error $(X - L)$	Standard deviation s
Close to Min				
Critical point 1				
Critical point 2				
Close to Max				

This table to be used for nonautomatic single load static test results

	Load L	Indication I	Error E
Close to Min			
Critical point 1			
Critical point 2			
Close to Max			

7.2.3 Static temperature (5 $^{\circ}$ C) (continued)

CLASS Y()

This table to be used for summary of automatic mode dynamic or nonautomatic single load static test results

	Load L	Number of weighings	Maximum error
Close to Max			
Critical point 1			
Critical point 2			
Close to Min			

Note: For Class Y() instruments for weighing loose material the number of weighings will equal 1 and the error will be the actual error E. Remarks:

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Report	Page	 /

2.4 Static temperatu	re (20 °C)				
Application No:					
attern designation:					
Observer:					
			At start	At end	
			emp:		°C
			el. h: Date:		%
			ime:		yy:mn hh:mr
Verification scale interval e:					
Resolution during test smaller than e):					
ntomatic zero-setting dev	vice is:				
Non-existent	Not in	operation	Out of working range	In operation	n
Rate of operation (max)	if applicable			Static load	
LASS X()					
is table to be used for su	ummary of au	tomatic mode dynamic to	est results		
Γ	Load	Mean of indicated	Mean error	Standard deviation	1
	L	readings X	(X - L)	S	
Close to Min					1
Critical point 1					1
Critical point 2					┨
⊪					┨
Close to Max					
is table to be used for no	onautomatic s	ingle load static test resu	lts		
Γ	Load	Indication	Error		
	L	I	E		
Close to Min					
I -					

Critical point 2

Close to Max

7.2.4 Static temperature (20 $^{\circ}$ C) (continued)

CLASS Y()

This table to be used for summary of automatic mode dynamic or nonautomatic single load static test results

	Load L	Number of weighings	Maximum error
Close to Max			
Critical point 1			
Critical point 2			
Close to Min			

Note: For Class Y() instruments for weighing loose material the number of weighings will equal 1 and the error will be the actual error E. Remarks:

7.3 Temperat	ure effe	ct on no-l	load indi	cation (A.7.2)					
Application No:									
Pattern designation	on:								
Observer:									
Verification scale interval e:									
Resolution during (smaller than e):	g test								
Automatic zero-set		ce is:							
Report page (*)	Date	Time	Temp (°C)	Zero indication I	Add load	P	ΔΡ	ΔTem p	Zero- change per 5 °C
$\Delta P = difference of$	P for two	o consecu	tive tests	at different tem	peratures				
Δ Temp = difference	e of tem	p. for two	consecut	ive tests at diffe	erent tempera	tures			
Remarks:									

^(*) Give the report page of the relevant weighing test where weighing tests and temperature effect on no-load indication test are conducted together.

Report Page/....

7.4 Damp heat, steady state (4.1.2, A.7.3) Application No: Pattern designation: Observer: At start At end °C Temp: Rel. h: Date: yy:mm:dd Time: $hh{:}mm{:}ss$ Verification scale interval e: Resolution during test (smaller than e): Automatic zero-setting device is: Out of working range Not in operation In operation Non-existent Load L Indication Temperature Error Reference and 50 % relative humidity High and

Remarks:

85 % relative humidity

Report	Page	/	/
KCDOIL	1 ago	/	

7.5	Power voltage va	riation (2.9.2, A.7.4)				
App	olication No:					
Patt	ern designation:					
Obs	server:					
			_	At start	At end	-
			Temp:			°C
			Rel. h:			%
			Date:			yy:mm:dd
			Time:			hh:mm:ss
	ification ale interval e:					
	olution during test aller than e):					
Autor	matic zero-setting dev	ice is:				
	Non-existent	Not in operation	Out of w	orking range	In operation	on
Mai	rked nominal voltage	or voltage range:		V		
Test	t supply voltage	V	Те	st supply frequency	I	Hz
Rate	of operation (max) if	applicable				
	Sta	tic load	Sel	ected dynamic load		

CLASS X()

This table to be used for summary of automatic mode dynamic test results

Voltage	Mean of indicated readings X	Mean error (X - L)	Standard deviation s
Reference			
0.1			
- 15 %			
Reference			

Note(*)

^(*) The reference voltage shall be as defined in IEC 1000-4-11(1994) section 5.

7.5 Power voltage variation (continued)

This table to be used for nonautomatic single load static test results (when appropriate)

Voltage	Indication I	Error E
Reference		
+ 10 %		
- 15 %		
Reference		

Remarks:	
----------	--

CLASS Y()

This table to be used for summary of automatic mode dynamic test results

Voltage	Load	Number of weighings n	Maximum error
Reference			
+ 10 %			
- 15 %			
Reference			

Note: For Class Y() instruments for weighing loose material the number of weighings will equal 1 and the error will be the actual error E.

This table to be used for nonautomatic single load static test results (when appropriate)

Voltage	Indication I	Add load ΔL	Error E
Reference			
+ 10 %			
- 15 %			
Reference			

N	o	te	(;	*)

^(*) The reference voltage shall be as defined in IEC 1000-4-11(1994) section 5.

Report	Page		/
REDOIL	rage	/	

7.6 Tilti	ng (2.6.3)				
Application	No:				
Pattern desi	gnation:				
Observer:					
			At start	At end	
		Temp	:		°C
		Rel. h			%
		Date	:		yy:mm:dd
		Time	:		hh:mm:ss
Verification scale inter					
Resolution (smaller that	_				
Tiltin	ng 5 % not require	d for fixed installation			
Tiltin	ng 5 % not require	ed, can be adjusted to 1 % or less			
CLASS X()					
The followin	g two tables are to	be used for summary of automatic m	ode dynamic test result	s.	

Tilting position	Mean of indicated readings	Mean error	Standard deviation
	$\frac{\overline{x}}{x}$	(X - L)	S
Reference			
Longitudinally forward			
Longitudinally backwards			
Transversely forward			
Transversely backwards			
Reference			

Load close to Max

Tilting position	Mean of indicated readings	Mean error	Standard deviation
	X	(X - L)	8
Reference			
Longitudinally forward			
Longitudinally backwards			
Transversely forward			
Transversely backwards			
Reference			

7.6 Tilting (continued)

The following two tables are to be used for nonautomatic single load static test results.

Load close to Max

Tilting position	Indication I	Error
Reference		
Longitudinally forward		
Longitudinally backwards		
Transversely forward		
Transversely backwards		
Reference		

Load close to Min

Tilting position	Indication I	Error
Reference		
Longitudinally forward		
Longitudinally backwards		
Transversely forward		
Transversely backwards		
Reference		

7.6 Tilting (continued)

CLASS Y()

These two tables to be used for summary of automatic mode dynamic or nonautomatic single load static test results.

Tilting position	Number of weighings	Maximum error
Reference		
Longitudinally forward		
Longitudinally backwards		
Transversely forward		
Transversely backwards		
Reference		

Load close to Max

Tilting position	Number of weighings	Maximum error
Reference		
Longitudinally forward		
Longitudinally backwards		
Transversely forward		
Transversely backwards		
Reference		

Note: For Class Y() instruments for weighing loose material the number of weighings will equal 1 and the error will be the actual error E. Give (if appropriate on a separate sheet) a sketch of the load receptor showing the location of the level indicator if provided.

8 DISTURBANCES (4.1.3, A.8)

8.1	Short time	power reductions (A.8.1)

Application No:				
Pattern designation:				
Observer:				
		At start	At end	
	Temp:			°C
	Rel. h:			%
	Date:			yy:mm:dd
	Time:			hh:mm:ss
Verification scale interval e:				
Resolution during test (smaller than e):				
[V			

Load	Disturbance				Result			
	Amplitude $\%$ of U_n	Duration cycles	Number of disturbances	Repetition interval (s)	Indication I	S No	Significant fault (> e) Yes (remarks)	
	without disturbance							
	0	0.5	10					
	50	1	10					

Note(*)

^(*) The reference voltage shall be as defined in IEC 1000-4-11 (1994) section 5.

8.2 Electrical bursts (4.1.3)

8.2.1 Power supply lines				
Application No:				
Pattern designation:				
Observer:				
		At start	At end	
	Temp:			°C
	Rel. h:			%
	Date:			yy:mm:dd
	Time:			hh:mm:ss
Verification scale interval e:				
Resolution during test (smaller than e):				

Power supply lines: test voltage 1 kV, duration of the test 1 min at each polarity

Load	Connection			Polarity	Result		
	L	N	PE		Indication I	Significant fault (> e)	
	ground	ground	ground			No	Yes (remarks)
		without d	isturbance				
	x			pos			
	Α			neg			
	without disturbance						
10 e =		X		pos			
				neg			
	without disturbance						
			X	pos			
			Λ	neg			

N	ote	(*)
LΝ	OLC	. ,

L = phase, N = neutral, PE = protective earth

^(*) The reference voltage shall be as defined in IEC 1000-4-11(1994) section 5.

8.2 Electrical bursts (continued)

1 min at each polarity

8.2.2 I/O circuits and communication lines

Application No:					
Pattern designation:					
Observer:					
			At start	At end	
		Temp:			°C
		Rel. h:			%
		Date:			yy:mm:dd
		Time:			hh:mm:ss
Verification scale interval e:					_
Resolution during test (smaller than e):					
I/O signals, data and control	lines: test voltage 0.5 kV, durat	ion of the test	ī		

Cable/Interface Load Polarity Result Indication Significant fault (>e)No Yes (remarks) without disturbance pos 10 e =neg without disturbance pos 10 e = neg without disturbance pos 10 e =

Note(*)

Explain or make a sketch indicating where the clamp is located on the cable; if necessary, add additional page.

^(*) The reference voltage shall be as defined in IEC 1000-4-11 (1994) section 5.

8.3 Electrostatic discharges (4.1.3, A.8.3)

8.3.1	Direct application				
Appl	ication No:				
Patte	rn designation:				
Obse	rver:				
			At start	At end	
		Temp:			°C
		Rel. h:			%
		Date:			yy:mm:dd
		Time:			hh:mm:ss
	ication e interval e:				
	lution during test ller than e):				
	Contact discharges	Paint penetration			
	Air discharges	Polarity(*): pos	neş	7	

Load	Discharges					Result
	Test Voltage (kV)	Number of discharges 10	Repetition interval (s)	Indication I	No	Significant fault (> e) Yes (remarks,test points)
		without disturbance				
	2					
	4					
	6					
	8 (air discharges)					

^(*) IEC 801-2 specifies that the test shall be conducted with the most sensitive polarity.

Report	Page	/	/		
ICOPOIL	1 ago	/	• •	٠	•

8.3	Electrostatic	discharges	(cont.))
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8.3.2 Indirect application (contact discharges only) Application No: Pattern designation: Observer: At start At end Temp: $^{\circ}C$ Rel. h: Date: yy:mm:dd Time: hh:mm:ss Verification scale interval e: Resolution during test (smaller than e): Polarity(*): neg

Horizontal coupling plane

Load			Result			
	Test voltage	Number of	Repetition interval	Indication		Significant fault (> e)
	(kV)	discharges ≥ 10	(s)	1	No	Yes (remarks)
	without disturbance					
	2					
	4					
10 e =	6					

Vertical coupling plane

Load			Result			
	Test voltage	Number of	Repetition interval	Indication		Significant fault (> e)
	(kV)	discharges ≥ 10	(s)	1	No	Yes (remarks)
	without disturbance					
	2					
	4					
10 e =	6					

Remarks:

^(*) IEC 801-2 specifies that the test shall be conducted with the most sensitive polarity.

Report	Page	/	·
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	Report Page/
8.3	Electrostatic discharges (cont.)
Specific	cation of test points of EUT (direct application), e.g. by photos or sketches
a)	Direct application
Contac	t discharges:
Air disc	charges:
b)	Indirect application

8.4 Electromagnetic susceptibility (4.1.3, A.8.4)

Application No:				
Pattern designation:				
Observer:				
		At start	At end	_
	Temp:			°C
	Rel. h:			%
	Date:			yy:mm:dd
	Time:			hh:mm:ss
Verification scale interval e:				
Resolution during test (smaller than e):				
Rate of sweep:				
Load:	Material load:			

	Disturb	ances	Result			
Antenna	Frequency range (MHz)	Polarization	Facing EUT	Indication I	No	Significant fault Yes (remarks)
without di		sturbance				
			Front			
			Right			
		Vertical	Left			
		Vertical	Rear			
			Front			
		Horizontal	Right			
			Left			
			Rear			
			Front			
			Right			
		Vertical	Left			
		Vertical	Rear			
			Front			
			Right			
		Horizontal	Left			
		Honzontal	Rear			

Frequency range: 26 - 1000 MHz Field strength: 3 V/m

Modulation: 80 % AM, 1 kHz sine wave

8.4 Electromagnetic susceptibility (continued)

Include a description of the set-up of EUT, e.g. by photos or sketches.

Note: If EUT fails, the frequency and field strength at which this occurs must be recorded.

9 SPAN STABILITY (6.5.1	, A.	9
-------------------------	------	---

Patte Obse Veri sca Reso	crn designation: erver: fication le interval e: clution during test diller than e):							
Auton	natic zero-setting de	vice is:						
	Non-existent	Not in op	eration	Out of w	orking range			
Test lo	oad =							
Measu	rement No 1: Initia	al measurement						
					At start	A	at end	
Obse	erver:			Temp:				°C
				Rel. h:				%
Loca	ation:			Date:				yy:mm:dd
				Time:				hh:mm:ss
$\mathbf{E}_0 = \mathbf{I}_0$	$_{0} + \frac{1}{2} e - \Delta L_{0} - L_{0}$	$E_L = I_L + \frac{1}{2} e^{-\frac{1}{2}}$	- ΔL - L					
	Indication	Add. load	E_0	Indication	Add. load	E_L	$E_L - E_0$	Corrected
	of zero (I ₀)	(ΔL_0)		of load (I _L)	(\Delta L)			value (*)
1								
2								+
3								+
5								+
(*)	rage error = average $-E_0^{}_{max} - (E_L - E_0^{})_{t}$	$e(E_L - E_0)$	etions result	ing from variations	of temperature,	pressure, et	c. See remarl	KS.

 $If *(E_L - E_0)_{max} - (E_L - E_0)_{min} * \leq 0.1 \ e, the \ loading \ and \ reading \ will \ be \ sufficient \ for each \ of the \ subsequent \ measurements.$

Subsequent measurements

For each of the subsequent measurements (at least 7), indicate on the "conditions of the measurement", as appropriate, if the measurement has been performed:

- after the temperature test, the EUT having been stabilized for at least 16 h;
- after the humidity test, the EUT having been stabilized for at least 16 h;
- after the EUT has been disconnected from the mains for at least 8 h and then stabilized for at least 5 h;
- after any change in the test location;
- under any other specific condition.

Measurement No 2:

		At start	At end	
Observer:	Temp:			°C
	Rel. h:			%
Location:	Date:			yy:mm:dc
	Time:			hh:mm:ss

Conditions of the measurement:

$$E_0 = I_0 + \frac{1}{2} e - \Delta L_0 - L_0 \qquad E_L = I_L + \frac{1}{2} e - \Delta L - L$$

	Indication of zero (I_0)	Add. load (ΔL_0)	E_0	Indication of load (I _L)	Add. load (ΔL)	E_{L}	$E_L - E_0$	Corrected value (*)
1								
2								
3								
4								
5								

(*) When applic	able, necessary	corrections resu	ulting from	variations of tem	perature, pressure	e, etc. See remarks.
	, which applie	abic, necessar y	COHECTIONS ICS	aithig ii Oili	variations of tem	iperature, pressure	, etc. Dec remarks.

If five loadings and readings have been performed:

Average error = average $(E_L - E_0)$	

		At start	At end	
Observer:	Temp:			°C
	Rel. h:			%
Location:	Date:			yy:mm:dd
	Time:			hh:mm:ss

Conditions of the measurement:

$$E_0 = I_0 + {}^{1}\!\!/_{\!\!2} \, e \, - \, \Delta L_0 \, - \, L_0 \qquad E_L = I_L + {}^{1}\!\!/_{\!\!2} \, e \, - \, \Delta L \, - \, L$$

	Indication of zero (I_0)	Add. load (ΔL_0)	E_0	Indication of load (I_L)	Add. load (ΔL)	E_L	$E_L - E_0$	Corrected value (*)
1								
2								
3								
4								
5								

							~ .
*)	When applicable, necessa	ary corrections re	esulting from	variations of	temperature.	pressure, etc.	See remarks.

If five loadings and readings have been performed:

Average error = average $(E_L - E_0)$	
---------------------------------------	--

Measurement No 4:		

		At start	At end	_
Observer:	Temp:			°C
	Rel. h:			%
Location:	Date:			yy:mm:dd
	Time:			hh:mm:ss

Conditions of the measurement:

$$E_0 = I_0 + {}^{1}\!\!/_{\!\!2} \; e \; - \; \Delta L_0 \; - \; L_0 \qquad E_L = I_L + {}^{1}\!\!/_{\!\!2} \; e \; - \; \Delta L \; - \; L$$

	Indication of zero (I_0)	Add. load (ΔL_0)	E_0	Indication of load (I _L)	Add. load (ΔL)	E_L	$E_L - E_0$	Corrected value (*)
1								
2								
3								
4								
5								

1	(*)	When applicable.	necessary correc	tione regulting	r from variati	one of temperatu	ra pracciira	ata Saa ramarka
()	when additione.	necessary correc	uons resulum	2 mom variau	ons of temperatu	re, bressure.	etc. See remarks

If five loadings and readings have been performed:

Average error = average $(E_L - E_0)$	1

Measurement	No	5:	
-------------	----	----	--

		At start	At end	
Observer:	Temp:			°C
	Rel. h:			%
Location:	Date:			yy:mm:dd
	Time:			hh:mm:ss

Conditions of the measurement:

$$E_0 = I_0 + 1/2 \ e - \Delta L_0 - L_0 \qquad E_L = I_L + 1/2 \ e - \Delta L - L$$

	Indication of zero (I ₀)	Add. load (ΔL ₀)	E_0	Indication of load (IL)	Add. load (ΔL)	E_{L}	$E_L - E_0$	Corrected value (*)
1								
2								
3								
4								
5								

(*) When applicable, necessary corrections resulting from variations of temperature, pressure, etc. See remarks.

If five loadings and readings have been performed:

Average error = average $(E_1 - E_0)$	

Measurement No 6:				
		At start	At end	_
Observer:	Temp:			°C
	Rel. h:			%

Date:

Time:

yy:mm:dd

hh:mm:ss

Conditions of the measurement:

Location:

$$E_0 = I_0 + 1/2 \ e - \Delta L_0 - L_0 \qquad E_L = I_L + 1/2 \ e - \Delta L - L$$

	Indication of zero (I ₀)	Add. load (ΔL ₀)	E_0	Indication of load (IL)	Add. load (ΔL)	E_L	$E_L - E_0$	Corrected value (*)
1								
2								
3								
4								
5								

(*)	When applicable, necessary	corrections r	esulting from	variations of	temperature	pressure etc.	See remarks

If five loadings and readings have been performed:

Average error = average $(E_L - E_0)$	

9 Span stability (cont	i.)
------------------------	-----

At start At end	
Observer: Temp:	
Rel. h: %	
Location: Date: yy:m	ım:dd
Time: hh:m	ım:ss

Conditions of the measurement:

$$E_0 = I_0 + {}^{1}\!\!/_{\!\!2} \; e \; - \; \Delta L_0 \; - \; L_0 \qquad E_L = I_L + {}^{1}\!\!/_{\!\!2} \; e \; - \; \Delta L \; - \; L$$

	Indication of zero (I ₀)	Add. load (ΔL ₀)	E_0	Indication of load (IL)	Add. load (ΔL)	E_L	$E_L - E_0$	Corrected value (*)
1								
2								
3								
4								
5								

(*)	When applicable, necessary	corrections r	esulting from	variations of	temperature	pressure etc.	See remarks

If five loadings and readings have been performed:

Average error = average $(E_L - E_0)$	

0	Cnan	stability	(cont)
7	OUAII	Stability	(COIII.

Mea	C11#	on	on	ı N	~ Q	
IVIEA	SHI	ен	ιеп	ıv	() ^	

	_	At start	At end	_
Observer:	Temp:			°C
	Rel. h:			%
Location:	Date:			yy:mm:dd
	Time:			hh:mm:ss

Conditions of the measurement:

$$E_0 = I_0 + {}^{1}\!\!/_{\!\!2} \; e \; - \; \Delta L_0 \; - \; L_0 \qquad E_L = I_L + {}^{1}\!\!/_{\!\!2} \; e \; - \; \Delta L \; - \; L$$

	Indication of zero (I ₀)	Add. load (ΔL ₀)	E_0	Indication of load (IL)	Add. load (ΔL)	E_L	$E_L - E_0$	Corrected value (*)
1								
2								
3								
4								
5								

1	*)	When applicable.	necessary correct	ione reculting f	from variations o	f tamparatura	nraccura ato	Saa ramarke
()	when additioned.	necessary correct	ions resulting i	TOIII Variauons o	n temberature.	bressure, etc	. See remarks.

If five loadings and readings have been performed:

Average error = average $(E_L - E_0)$	

)	Spar	1 stability	(contin	ued)																		
	Appl	ication No	:																			
	Patte	rn designa	tion:																			
	1 4440	iii desigin																				
	Plot	on the dias	ram the	e indic	ation of ter	nperature t	est (T).	damp h	eat test (D) and	d disconne	ctions from	ı th	e mains pov	ver supply	, (P)					
e			,			1	1	Т-		,			_	F	· · · · · · · · · · · · · · · · · · ·		,	-				
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							+						ł			1						
													†			1						
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۵																1						

SAMPLE TEST REPORT FOR RECORDING INDIVIDUAL WEIGHTS WHERE APPLICABLE

TEST TYPE:					
Test section:					
Relevant section	on of Part 1:				
Relevant section	n of test procedure:				
Application N					
Pattern design	nation:				
Observer:					
			At start	At end	
		Temp:			°C
		Rel. h:			%
		Date:			yy:mm:dd
		Time:			hh:mm:ss
		—	Record only data		
Verification		•	record only data	Toto valie to test	
scale interva	l e:				
Resolution du (smaller than					
	<u>~</u>).				
Load:			Statio	cload	
Eccentricity battering (if applicable)	nd:				
Rate of operation	on:				
Automatic zero	-setting device is:				
Non-exis	Not in ope	Out of v	working range	In operation	
Test	Indication	Error	Test	Indication	Error
1			16		
2			17		
3			18		
4			19		
5			20		
6			21		
7			22		
8			23		
9			24		
10			25		
11			26		
12			27		
13			28		
14			29		
15			30		

$SAMPLE\ TEST\ REPORT\ FOR\ RECORDING\ INDIVIDUAL\ WEIGHTS\ WHERE\ APPLICABLE\ (continued)$

Test	Indication	Error	Test	Indication	Error
31			46		
32			47		
33			48		
34			49		
35			50		
36			51		
37			52		
38			53		
39			54		
40			55		
41			56		
42			57		
43			58		
44			59		
45			60		

$$mpme = \frac{\sum x}{n} = mps = \sqrt{\frac{\sum (\overline{x} - x)^2}{n - 1}} =$$

SAMPLE TEST REPORT FOR RECORDING INDIVIDUAL WEIGHTS WHERE APPLICABLE

TEST TYPE:	
Test section:	
Relevant section of Part 1:	
Relevant section of test procedure:	

The following table is to be used for Class (Y) nonautomatic single load static test results (when appropriate)

Test	Indication	Add load	Error
1			
2			
3			
4			
5			
6			
7			
8			
9			
10			
11			
12			
13			
14			
15			
16			
17			
18			
19			
20			
21			
22			
23			
24			
25			
26			
27			
28			
29			
30			